CS 1550 Introduction to Operating Systems

# RECITATION – WEEK 4

**PRANUT JAIN** 

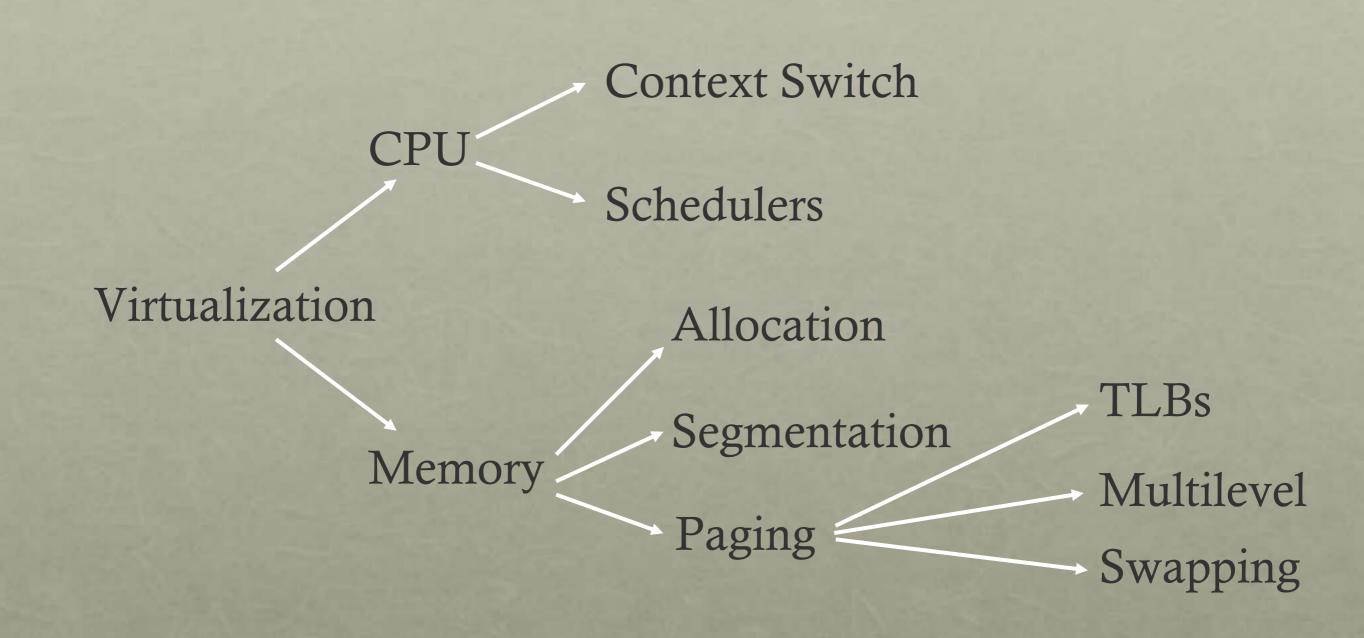
# PLAN FOR TODAY

- Threads discussion
- Scheduling introduction

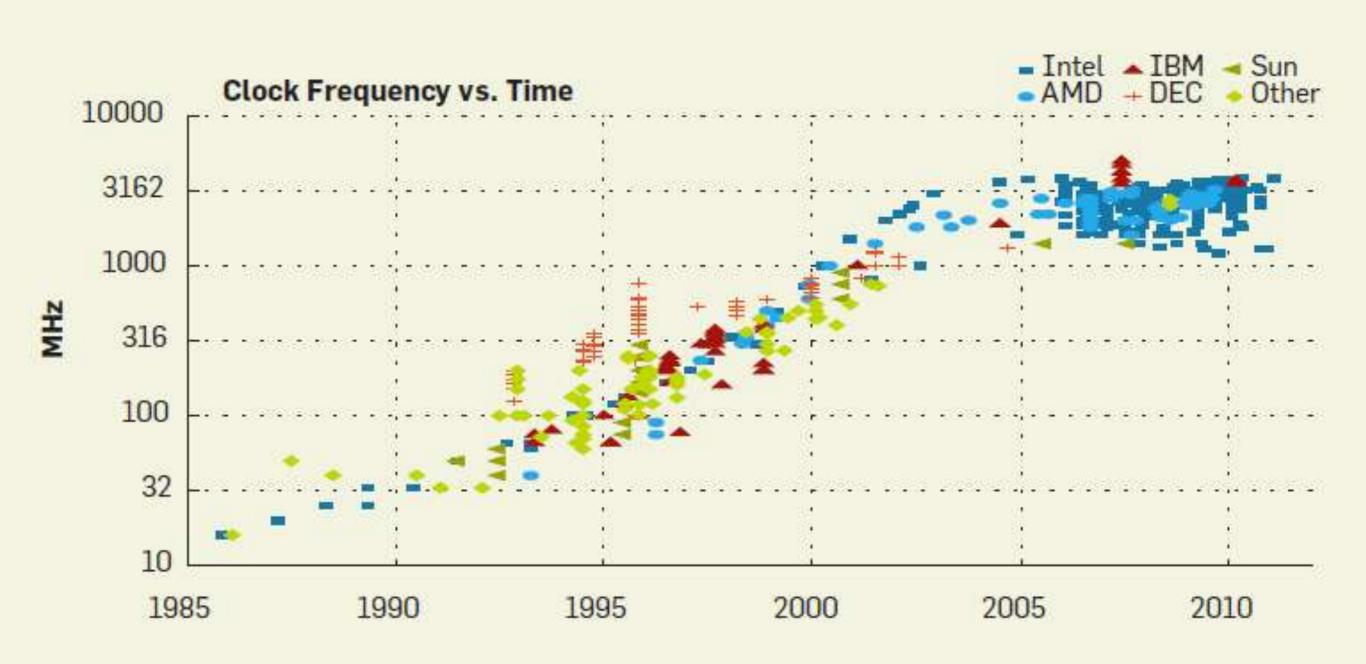
## DISCLAIMER

 Slides originally by Andrea for Professor Remzi H. Arpaci-Dusseau, UNIVERSITY of WISCONSIN-MADISON

### REVIEW: EASY PIECE 1



# MOTIVATION FOR CONCURRENCY



### MOTIVATION

CPU Trend: Same speed, but multiple cores

Goal: Write applications that fully utilize many cores

Option 1: Build apps from many communicating processes

- Example: Chrome (process per tab)
- Communicate via pipe() or similar

#### Pros?

Don't need new abstractions; good for security

### Cons?

- Cumbersome programming
- High communication overheads
- Expensive context switching (why expensive?)

# CONCURRENCY: OPTION 2

New abstraction: thread

Threads are like processes, except: multiple threads of same process share an address space

Divide large task across several cooperative threads

Communicate through shared address space

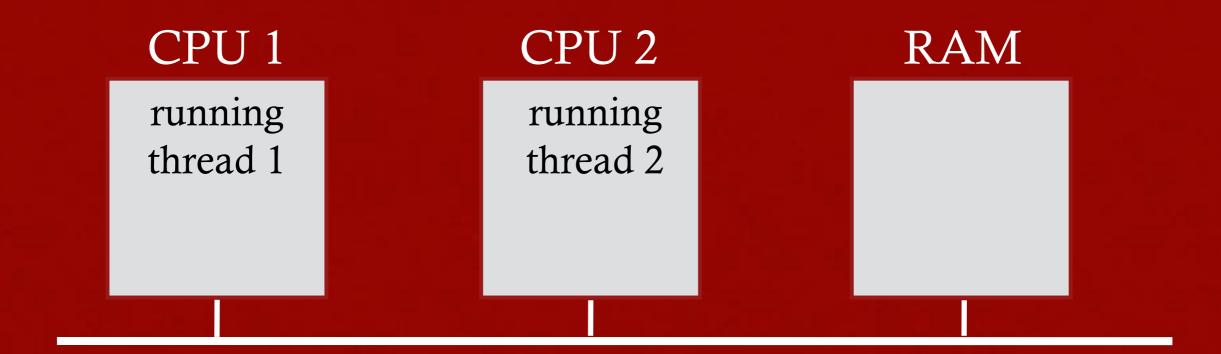
# COMMON PROGRAMMING MODELS

Multi-threaded programs tend to be structured as:

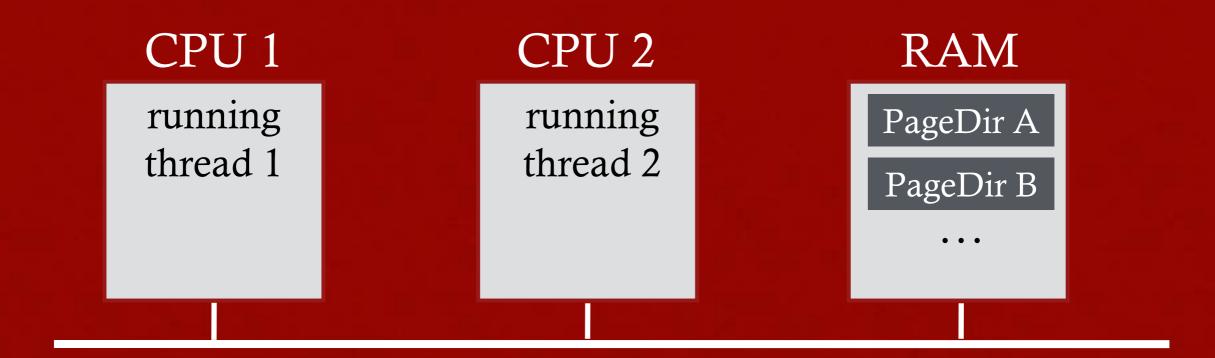
- Producer/consumer

  Multiple producer threads create data (or work) that is handled by one of the multiple consumer threads
- Pipeline

  Task is divided into series of subtasks, each of which is handled in series by a different thread
- Defer work with background thread
  One thread performs non-critical work in the background (when CPU idle)



What state do threads share?



What threads share page directories?

CPU 1

running
thread 1

PTBR

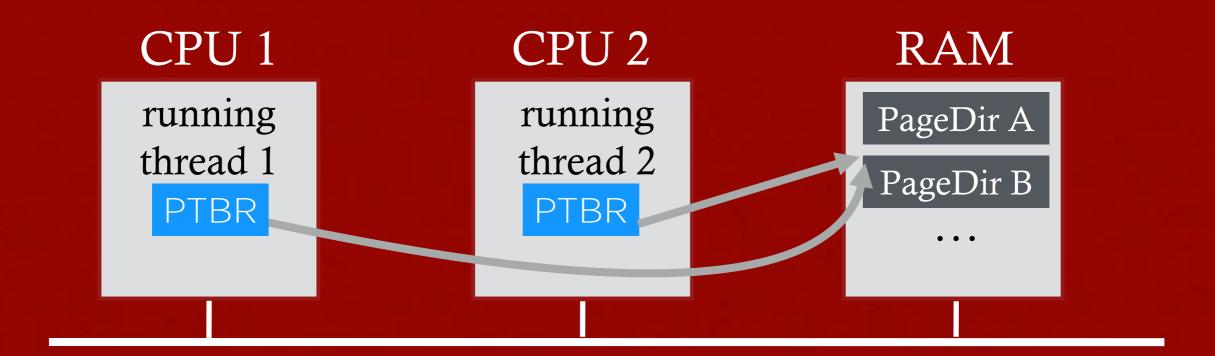
CPU 2

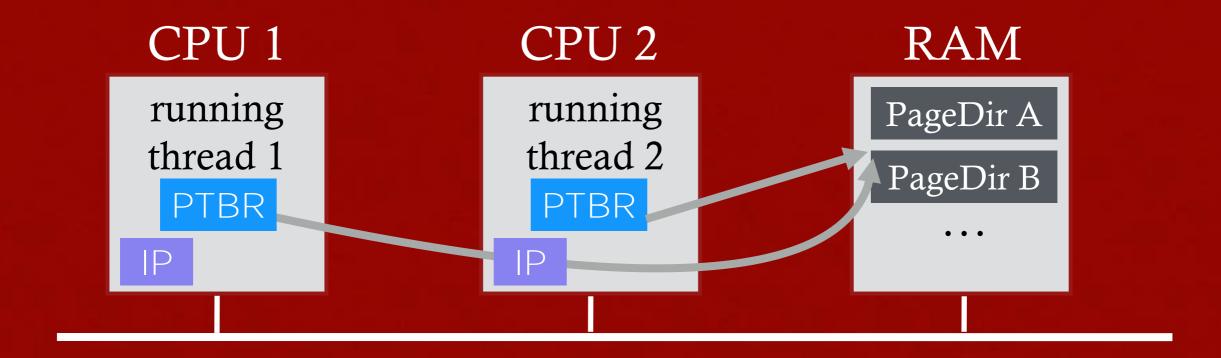
RAM

PageDir A

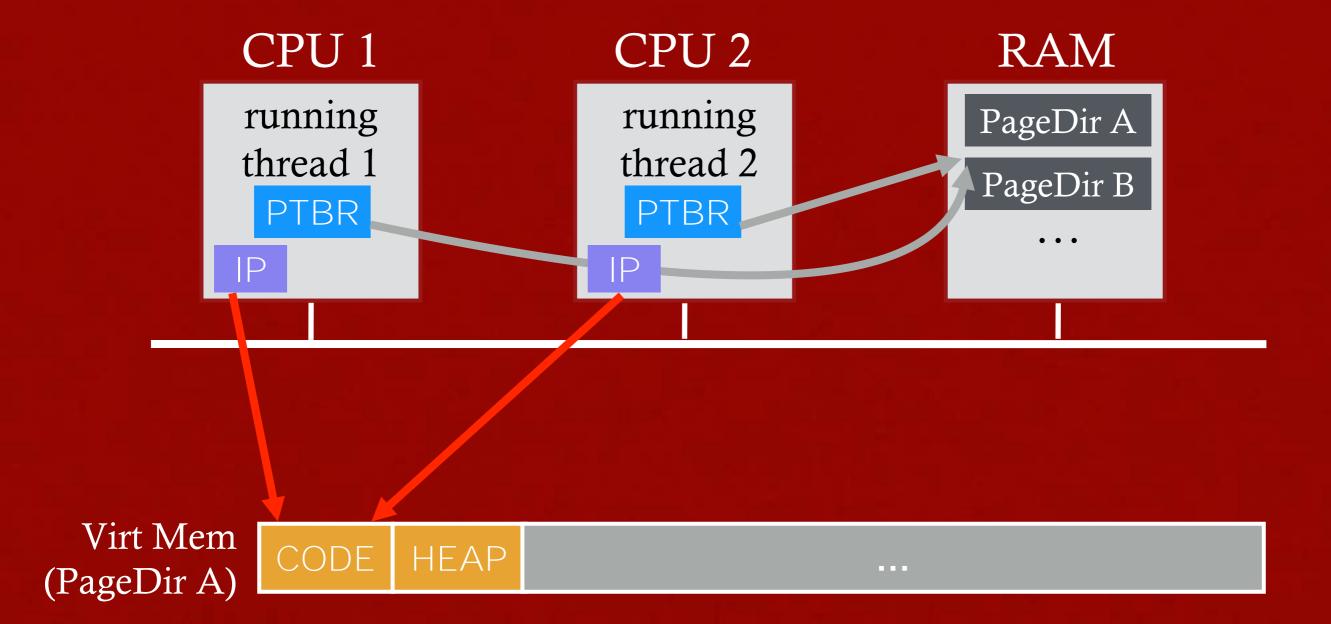
PageDir B

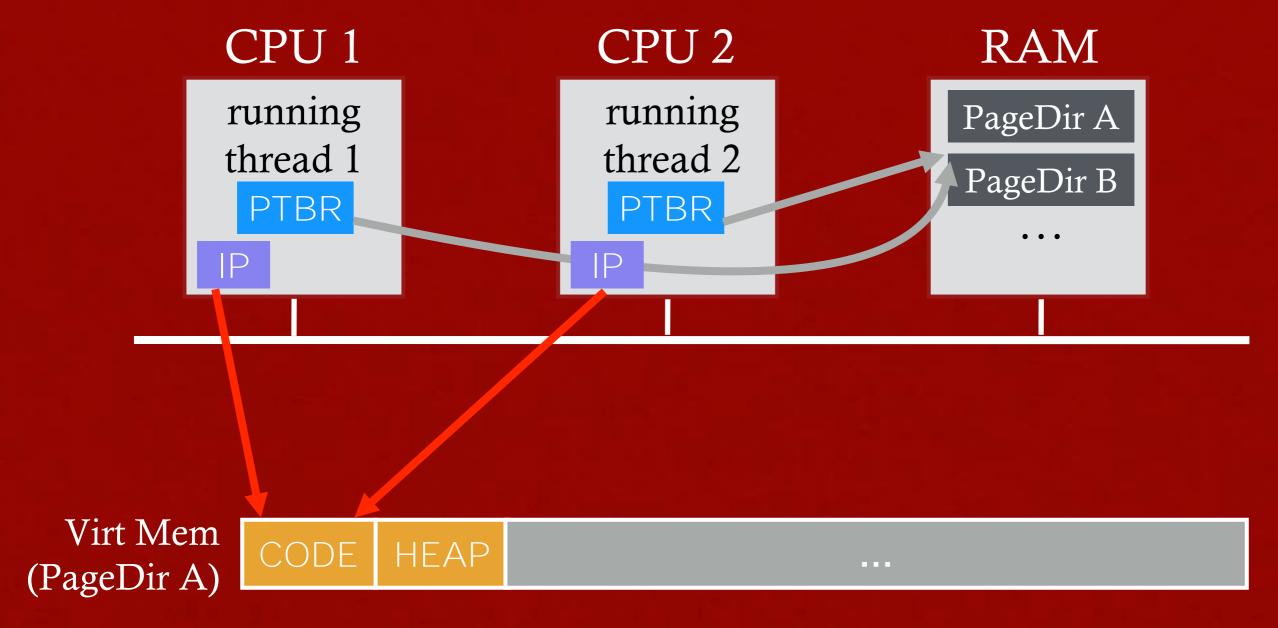
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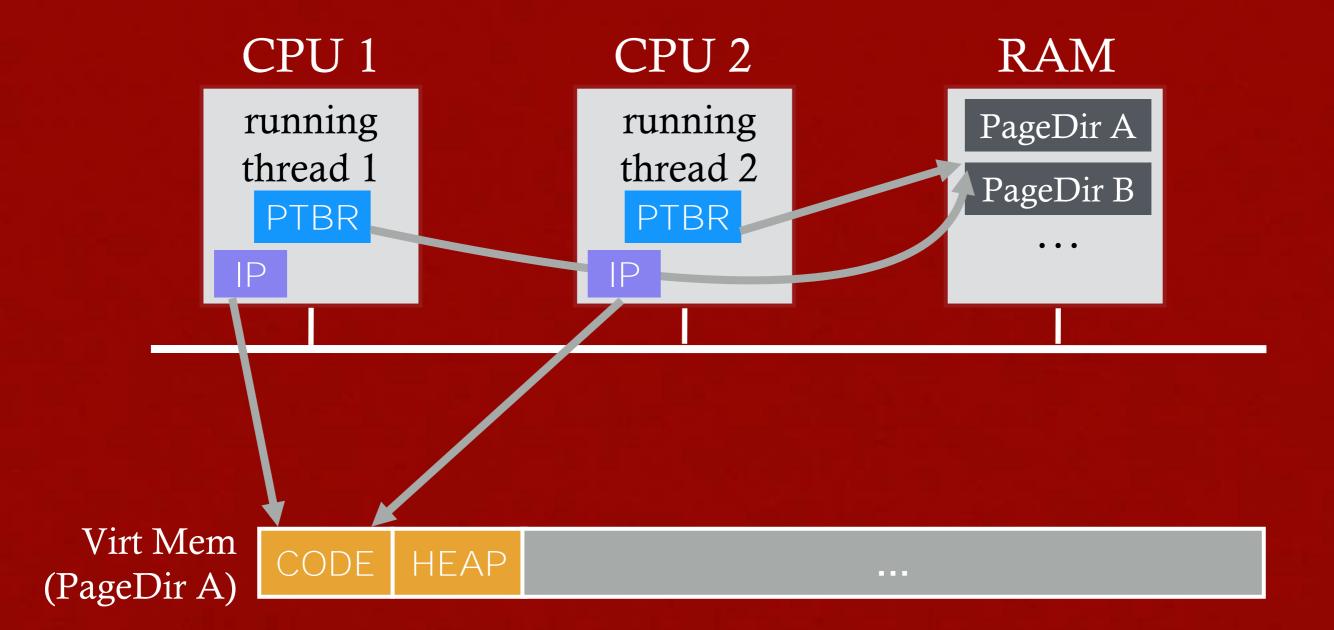
Do threads share Instruction Pointer?

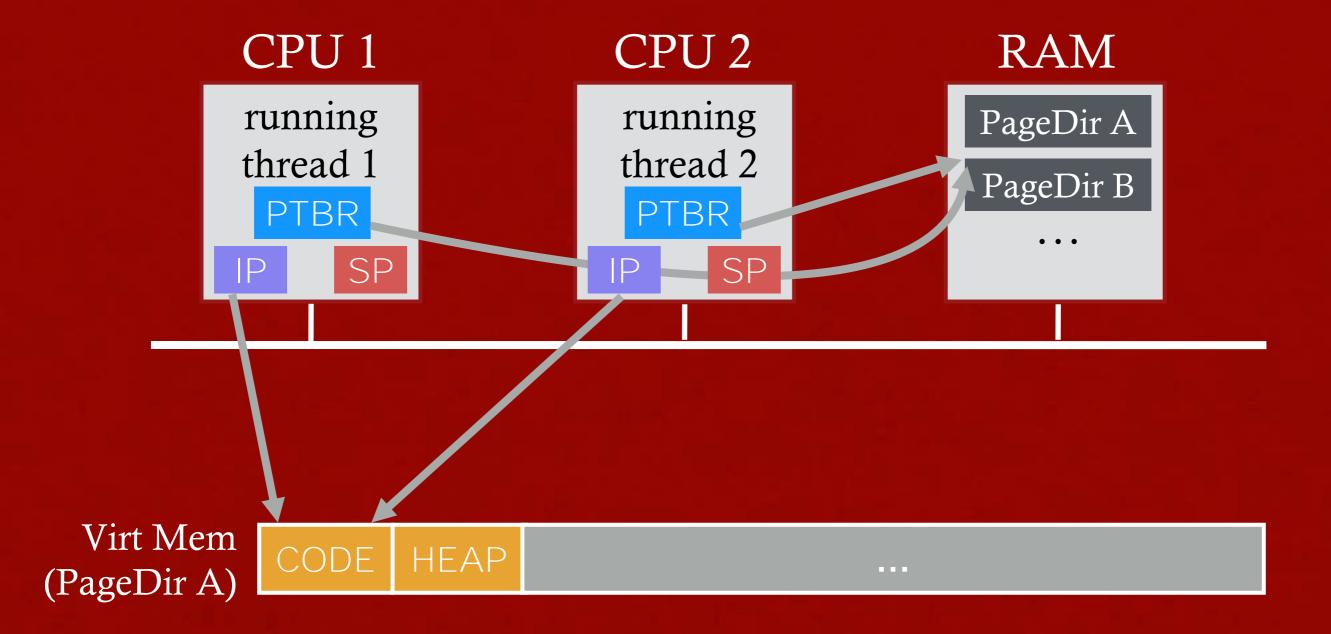




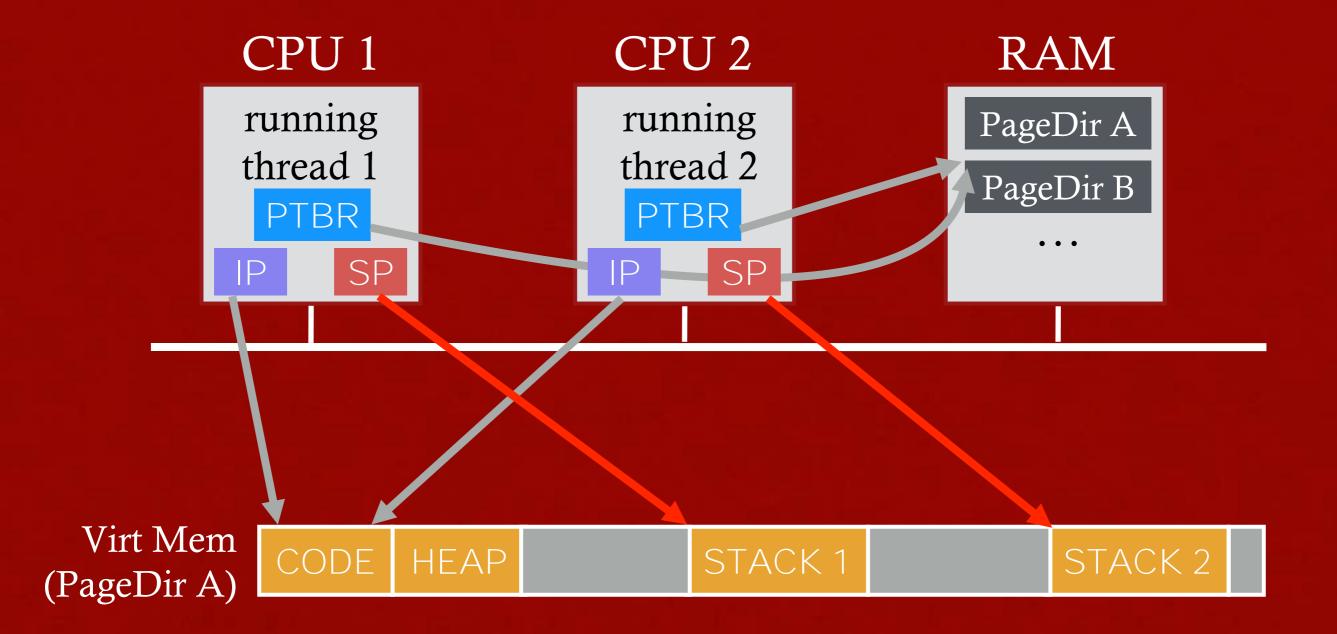
Share code, but each thread may be executing different code at the same time

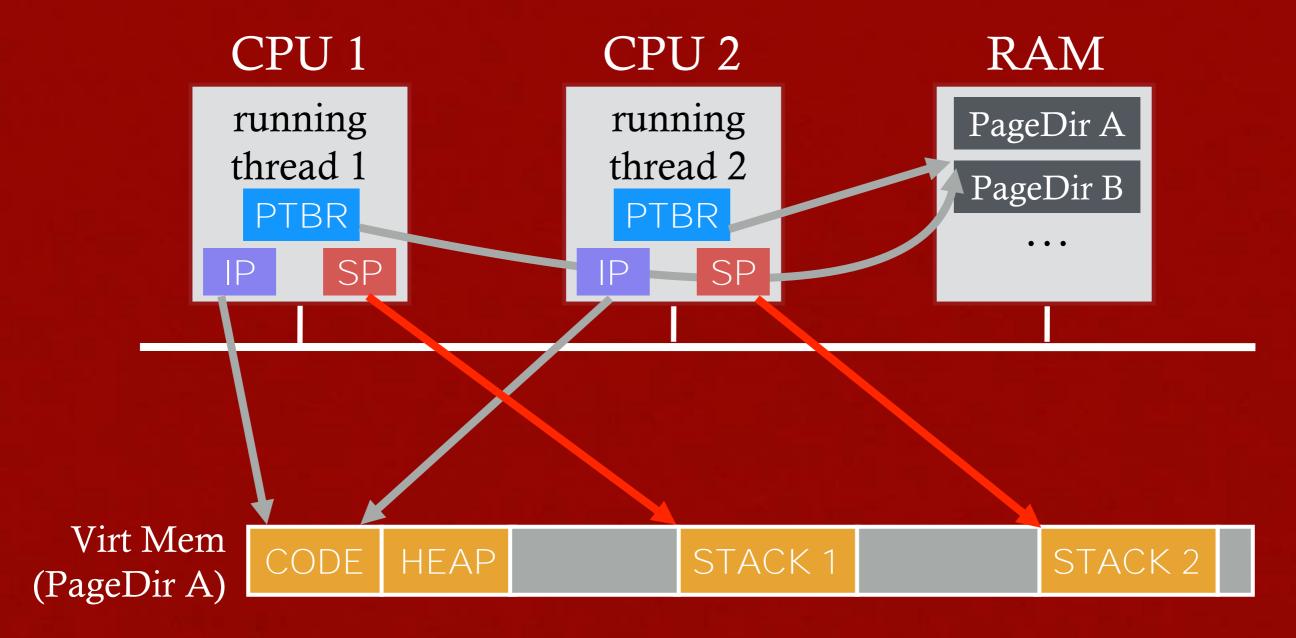
→ Different Instruction Pointers





Do threads share stack pointer?





threads executing different functions need different stacks

# THREAD VS. PROCESS

### Multiple threads within a single process share:

- Process ID (PID)
- Address space
  - Code (instructions)
  - Most data (heap)
- Open file descriptors
- Current working directory
- User and group id

### Each thread has its own

- Thread ID (TID)
- Set of registers, including Program counter and Stack pointer
- Stack for local variables and return addresses (in same address space)

## THREAD API

### Variety of thread systems exist

POSIX Pthreads

### Common thread operations

- Create
- Exit
- Join (instead of wait() for processes)

# OS SUPPORT: APPROACH 1

### User-level threads: Many-to-one thread mapping

- Implemented by user-level runtime libraries
  - Create, schedule, synchronize threads at user-level
- OS is not aware of user-level threads
  - OS thinks each process contains only a single thread of control

### Advantages

- Does not require OS support; Portable
- Can tune scheduling policy to meet application demands
- Lower overhead thread operations since no system call

### Disadvantages?

- Cannot leverage multiprocessors
- Entire process blocks when one thread blocks

# OS SUPPORT: APPROACH 2

### Kernel-level threads: One-to-one thread mapping

- OS provides each user-level thread with a kernel thread
- Each kernel thread scheduled independently
- Thread operations (creation, scheduling, synchronization) performed by OS

### Advantages

- Each kernel-level thread can run in parallel on a multiprocessor
- When one thread blocks, other threads from process can be scheduled

### Disadvantages

- Higher overhead for thread operations
- OS must scale well with increasing number of threads

# DEMO: BASIC THREADS

### balance = balance + 1; balance at 0x9cd4

#### State:

0x9cd4: 100

%eax: ?

%rip = 0x195

### process

control

blocks:

### Thread 1

%eax: ?

%rip: 0x195

#### Thread 2

%eax: ?

%rip: 0x195



- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4A

process

control

blocks:

#### State:

0x9cd4: 100

%eax: 100

%rip = 0x19a

#### Thread 1

%eax: ?

%rip: 0x195

#### Thread 2

%eax: ?

%rip: 0x195

• 0x195 mov 0x9cd4, %eax

T1

- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4

#### State:

T1

0x9cd4: 100

%eax: 101

%rip = 0x19d

Thread 1

process %eax:?

blocks: %rip: 0x195

Thread 2

%eax: ?

%rip: 0x195

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax

• 0x19d mov %eax, 0x9cd4

process

control

blocks:

#### State:

0x9cd4: 101

%eax: 101

%rip = 0x1a2

#### Thread 1

%eax: ?

%rip: 0x195

#### Thread 2

%eax: ?

%rip: 0x195

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4



process

control

blocks:

#### State:

0x9cd4: 101

%eax: 101

%rip = 0x1a2

#### Thread 1

%eax: ?

%rip: 0x195

#### Thread 2

%eax: ?

%rip: 0x195

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4



# Thread Context Switch

process

control

blocks:

State:

0x9cd4: 101

%eax: ?

%rip = 0x195

Thread 1

%eax: 101

%rip: 0x1a2

Thread 2

%eax: ?

%rip: 0x195

T2

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4

process

control

blocks:

#### State:

0x9cd4: 101

%eax: 101

%rip = 0x19a

#### Thread 1

%eax: 101

%rip: 0x1a2

### Thread 2

%eax: ?

%rip: 0x195

0x195 mov 0x9cd4, %eax

T2

- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4

#### State:

0x9cd4: 101

%eax: 102

%rip = 0x19d

process

control

blocks:

### Thread 1

%eax: 101

%rip: 0x1a2

### Thread 2

%eax: ?

%rip: 0x195

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax

0x19d mov %eax, 0x9cd4



#### State:

0x9cd4: 102

%eax: 102

%rip = 0x1a2

### 1111

process control

blocks:

#### Thread 1

%eax: 101

%rip: 0x1a2

#### Thread 2

%eax: ?

%rip: 0x195

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4



#### State:

0x9cd4: 102

%eax: 102

%rip = 0x1a2

process

control

blocks:

#### Thread 1

%eax: 101

%rip: 0x1a2

#### Thread 2

%eax: ?

%rip: 0x195

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4

T2

Desired Result!

# ANOTHER SCHEDULE

process

control

blocks:

#### State:

0x9cd4: 100

%eax: ?

%rip = 0x195

### Thread 1

%eax: ?

%rip: 0x195

### Thread 2

%eax: ?

%rip: 0x195



- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4

process

control

blocks:

### State:

0x9cd4: 100

%eax: 100

%rip = 0x19a

### Thread 1

%eax: ?

%rip: 0x195

### Thread 2

%eax: ?

%rip: 0x195

- 0x195 mov 0x9cd4, %eax
- T1
- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4

process

control

blocks:

#### State:

0x9cd4: 100

%eax: 101

%rip = 0x19d

Thread 1

%eax: ?

%rip: 0x195

Thread 2

%eax: ?

%rip: 0x195

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax

T1

0x19d mov %eax, 0x9cd4

Thread Context Switch

process

control

blocks:

### State:

0x9cd4: 100

%eax: ?

%rip = 0x195

### Thread 1

%eax: 101

%rip: 0x19d

### Thread 2

%eax: ?

%rip: 0x195

# T2

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4

### State:

0x9cd4: 100

%eax: 100

%rip = 0x19a

process

control

blocks:

### Thread 1

%eax: 101

%rip: 0x19d

### Thread 2

%eax: ?

%rip: 0x195

T2

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4

process

control

blocks:

### State:

0x9cd4: 100

%eax: 101

%rip = 0x19d

### Thread 1

%eax: 101

%rip: 0x19d

### Thread 2

%eax: ?

%rip: 0x195

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax

• 0x19d mov %eax, 0x9cd4



process

control

blocks:

### State:

0x9cd4: 101

%eax: 101

%rip = 0x1a2

Thread 1

%eax: 101

%rip: 0x19d

Thread 2

%eax: ?

%rip: 0x195

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4A



process

control

blocks:

#### State:

0x9cd4: 101

%eax: 101

%rip = 0x1a2

### Thread 1

%eax: 101

%rip: 0x19d

### Thread 2

%eax: ?

%rip: 0x195

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax

0x19d mov %eax, 0x9cd4



Thread Context Switch

process

control

blocks:

#### State:

0x9cd4: 101

%eax: 101

%rip = 0x19d

### Thread 1

%eax: 101

%rip: 0x19d

### Thread 2

%eax: 101

%rip: 0x1a2

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax

T1

0x19d mov %eax, 0x9cd4

# Thread Context Switch

### State:

0x9cd4: 101

%eax: 101

%rip = 0x19d

11110

control %

blocks:

process

Thread 1

%eax: 101

%rip: 0x19d

Thread 2

%eax: 101

%rip: 0x1a2

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, **%eax**

T1

0x19d mov %eax, 0x9cd4

### State:

0x9cd4: 101

%eax: 101

%rip = 0x1a2

process control

blocks:

### Thread 1

%eax: 101

%rip: 0x1a2

### Thread 2

%eax: 101

%rip: 0x1a2

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4



### State:

0x9cd4: 101

%eax: 101

%rip = 0x1a2

### 1 nreac

process control

blocks:

### Thread 1

%eax: 101

%rip: 0x1a2

### Thread 2

%eax: 101

%rip: 0x1a2

- 0x195 mov 0x9cd4, %eax
- 0x19a add \$0x1, %eax
- 0x19d mov %eax, 0x9cd4



WRONG Result! Final value of balance is 101

Thread 1

Thread 2

mov 0x123, %eax

add %0x1, %eax

mov %eax, 0x123

mov 0x123, %eax

add %0x2, %eax

mov %eax, 0x123

How much is added to shared variable?

3: correct!

Thread 1

mov 0x123, %eax

add %0x1, %eax

mov %eax, 0x123

Thread 2

mov 0x123, %eax

add %0x2, %eax

mov %eax, 0x123

How much is added?

2: incorrect!

Thread 1

Thread 2

mov 0x123, %eax

mov 0x123, %eax

add %0x2, %eax

add %0x1, %eax

mov %eax, 0x123

mov %eax, 0x123

How much is added?

1: incorrect!

Thread 1

Thread 2

mov 0x123, %eax

add %0x2, %eax

mov %eax, 0x123

mov 0x123, %eax

add %0x1, %eax

mov %eax, 0x123

How much is added?

3: correct!

Thread 1

Thread 2

mov 0x123, %eax

add %0x2, %eax

mov 0x123, %eax

add %0x1, %eax

mov %eax, 0x123

mov %eax, 0x123

How much is added? 2: incorrect!

### NON-DETERMINISM

Concurrency leads to non-deterministic results

- Not deterministic result: different results even with same inputs
- race conditions

Whether bug manifests depends on CPU schedule!

Passing tests means little

How to program: imagine scheduler is malicious

Assume scheduler will pick bad ordering at some point...

### WHAT DO WE WANT?

Want 3 instructions to execute as an uninterruptable group

That is, we want them to be atomic

mov 0x123, %eax add %0x1, %eax mov %eax, 0x123

critical section

### More general:

Need mutual exclusion for critical sections

• if process A is in critical section C, process B can't (okay if other processes do unrelated work)

# SYNCHRONIZATION

Build higher-level synchronization primitives in OS

• Operations that ensure correct ordering of instructions across threads

Motivation: Build them once and get them right

Monitors Locks Semaphores Condition Variables

Loads Stores Test&Set Disable Interrupts

# LOCKS

Goal: Provide mutual exclusion (mutex)

Three common operations:

- Allocate and Initialize
  - Pthread mutex t mylock = PTHREAD MUTEX INITIALIZER;
- Acquire
  - Acquire exclusion access to lock;
  - Wait if lock is not available (some other process in critical section)
  - Spin or block (relinquish CPU) while waiting
  - Pthread\_mutex\_lock(&mylock);
- Release
  - Release exclusive access to lock; let another process enter critical section
  - Pthread\_mutex\_unlock(&mylock);

# CONCLUSIONS

Concurrency is needed to obtain high performance by utilizing multiple cores

Threads are multiple execution streams within a single process or address space (share PID and address space, own registers and stack)

Context switches within a critical section can lead to nondeterministic bugs (race conditions)

Use locks to provide mutual exclusion