

CS 2750 Machine Learning Lecture 7

- Classification learning:**
- **Logistic regression**
 - **Generative classification model**

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Classification

- **Data:** $D = \{d_1, d_2, \dots, d_n\}$
 $d_i = \langle \mathbf{x}_i, y_i \rangle$
 - y_i represents a discrete class value
- **Goal: learn** $f : X \rightarrow Y$
- **Binary classification**
 - A special case when $Y \in \{0,1\}$
- **First step:**
 - we need to devise a model of the function f

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Discriminant functions

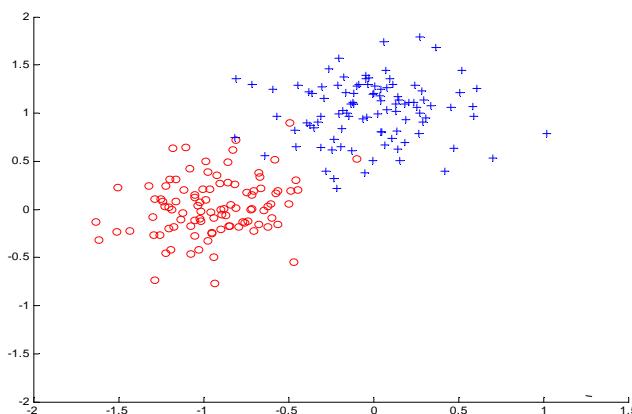
- A common way to represent a **classifier** is by using
 - **Discriminant functions**
- **Works for both the binary and multi-way classification**
- **Idea:**
 - For every class $i = 0, 1, \dots, k$ define a function $g_i(\mathbf{x})$ mapping $X \rightarrow \mathbb{R}$
 - When the decision on input \mathbf{x} should be made choose the class with the highest value of $g_i(\mathbf{x})$

$$y^* = \arg \max_i g_i(\mathbf{x})$$

- So what happens with the input space? Assume a binary case.

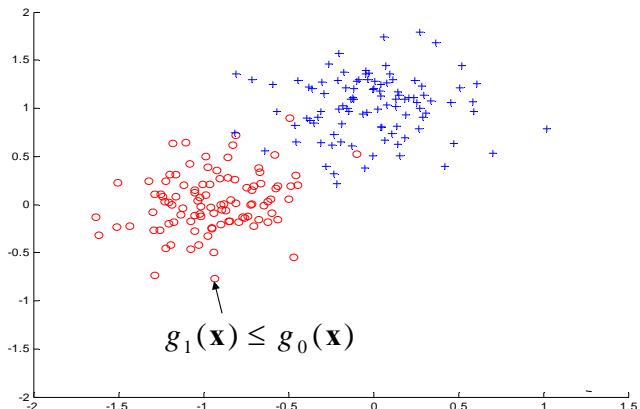
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Discriminant functions



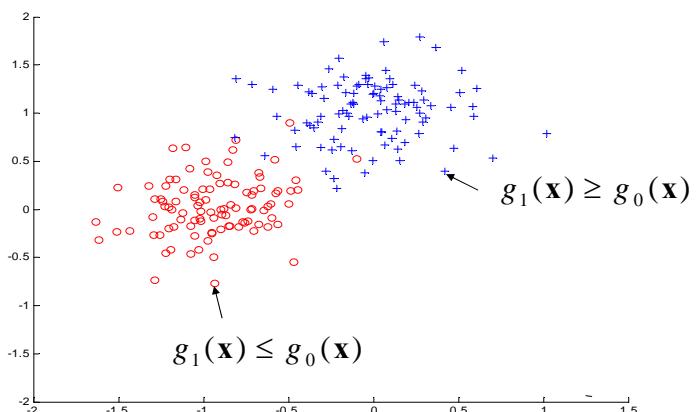
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Discriminant functions



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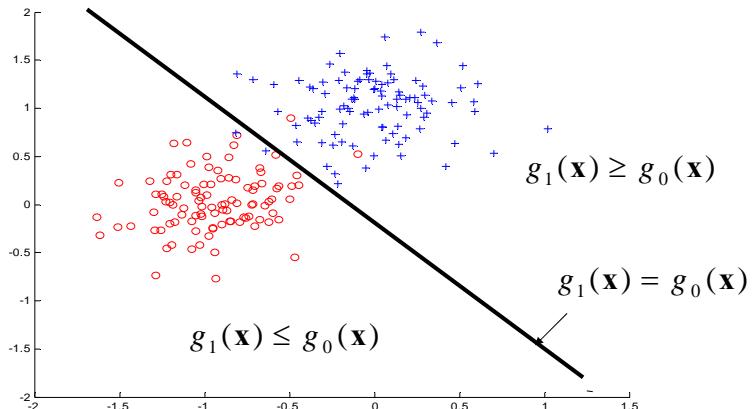
Discriminant functions



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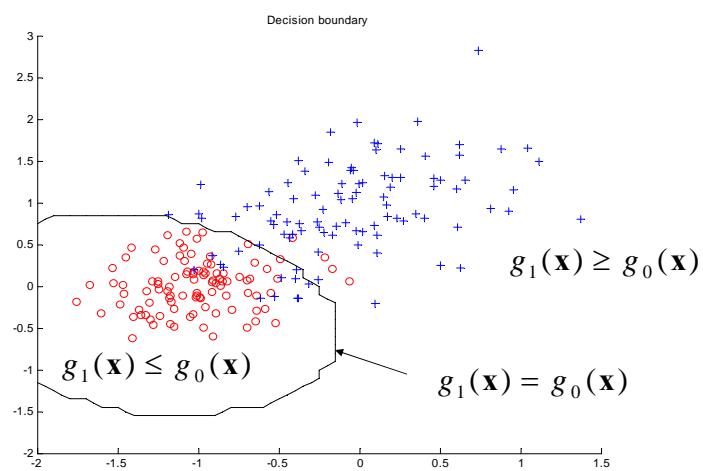
Discriminant functions

- **Decision boundary:** discriminant functions are equal



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Quadratic decision boundary



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Logistic regression model

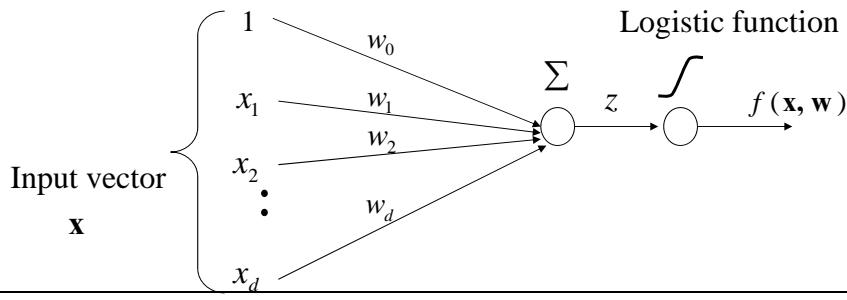
- Defines a linear decision boundary

- Discriminant functions:

$$g_1(\mathbf{x}) = g(\mathbf{w}^T \mathbf{x}) \quad g_0(\mathbf{x}) = 1 - g(\mathbf{w}^T \mathbf{x})$$

- where $g(z) = 1/(1 + e^{-z})$ - is a logistic function

$$f(\mathbf{x}, \mathbf{w}) = g_1(\mathbf{w}^T \mathbf{x}) = g(\mathbf{w}^T \mathbf{x})$$

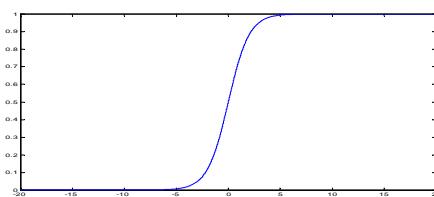


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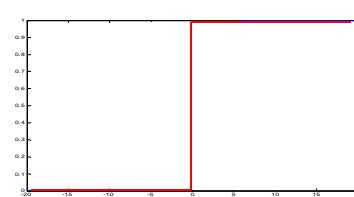
Logistic function

Function:
$$g(z) = \frac{1}{(1 + e^{-z})}$$

- Is also referred to as a **sigmoid function**
- takes a real number and outputs the number in the interval [0,1]
- Models a smooth switching function; replaces hard threshold function



Logistic (smooth) switching



Threshold (hard) switching

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Logistic regression model

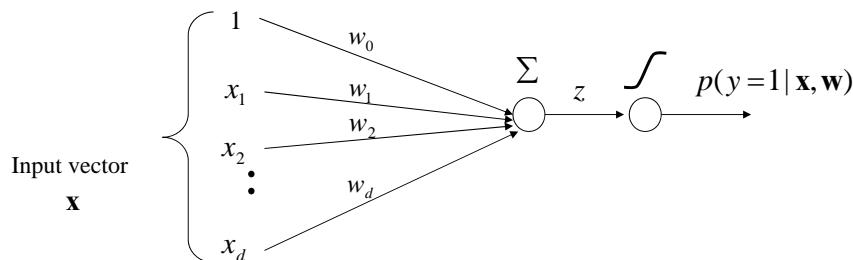
- **Discriminant functions:**

$$g_1(\mathbf{x}) = g(\mathbf{w}^T \mathbf{x}) \quad g_0(\mathbf{x}) = 1 - g(\mathbf{w}^T \mathbf{x})$$

- **Values of discriminant functions vary in interval [0,1]**

- **Probabilistic interpretation**

$$f(\mathbf{x}, \mathbf{w}) = p(y=1 | \mathbf{w}, \mathbf{x}) = g_1(\mathbf{x}) = g(\mathbf{w}^T \mathbf{x})$$



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Logistic regression

- We learn **a probabilistic function**

$$f : X \rightarrow [0,1]$$

- where f describes the probability of class 1 given \mathbf{x}

$$f(\mathbf{x}, \mathbf{w}) = g_1(\mathbf{w}^T \mathbf{x}) = p(y=1 | \mathbf{x}, \mathbf{w})$$

Note that:

$$p(y=0 | \mathbf{x}, \mathbf{w}) = 1 - p(y=1 | \mathbf{x}, \mathbf{w})$$

- Making decisions with the logistic regression model:

?

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Logistic regression

- We learn **a probabilistic function**

$$f : X \rightarrow [0,1]$$

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$$f(\mathbf{x}, \mathbf{w}) = g_1(\mathbf{w}^T \mathbf{x}) = p(y = 1 | \mathbf{x}, \mathbf{w})$$

Note that:

$$p(y = 0 | \mathbf{x}, \mathbf{w}) = 1 - p(y = 1 | \mathbf{x}, \mathbf{w})$$

- Making decisions with the logistic regression model:

If $p(y = 1 | \mathbf{x}) \geq 1/2$ then choose **1**
Else choose **0**

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Linear decision boundary

- Logistic regression model defines a **linear decision boundary**
- **Why?**
- **Answer:** Compare two **discriminant functions**.
- **Decision boundary:** $g_1(\mathbf{x}) = g_0(\mathbf{x})$
- For the boundary it must hold:

$$\log \frac{g_o(\mathbf{x})}{g_1(\mathbf{x})} = \log \frac{1 - g(\mathbf{w}^T \mathbf{x})}{g(\mathbf{w}^T \mathbf{x})} = 0$$

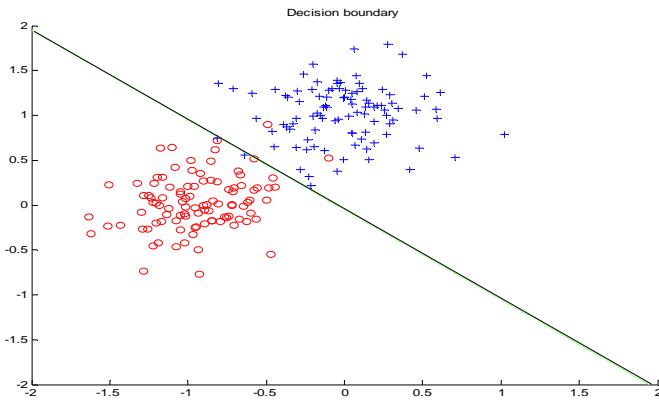
$$\log \frac{g_o(\mathbf{x})}{g_1(\mathbf{x})} = \log \frac{\frac{\exp - (\mathbf{w}^T \mathbf{x})}{1 + \exp - (\mathbf{w}^T \mathbf{x})}}{\frac{1}{1 + \exp - (\mathbf{w}^T \mathbf{x})}} = \log \frac{\exp - (\mathbf{w}^T \mathbf{x})}{1 + \exp - (\mathbf{w}^T \mathbf{x})} = \mathbf{w}^T \mathbf{x} = 0$$

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Logistic regression model. Decision boundary

- LR defines a linear decision boundary

Example: 2 classes (blue and red points)



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Logistic regression: parameter learning

Likelihood of outputs

- Let

$$D_i = \langle \mathbf{x}_i, y_i \rangle \quad \mu_i = p(y_i = 1 | \mathbf{x}_i, \mathbf{w}) = g(z_i) = g(\mathbf{w}^T \mathbf{x})$$

- Then

$$L(D, \mathbf{w}) = \prod_{i=1}^n P(y = y_i | \mathbf{x}_i, \mathbf{w}) = \prod_{i=1}^n \mu_i^{y_i} (1 - \mu_i)^{1-y_i}$$

- Find weights \mathbf{w} that maximize the likelihood of outputs

– Apply the log-likelihood trick. The optimal weights are the same for both the likelihood and the log-likelihood

$$\begin{aligned} l(D, \mathbf{w}) &= \log \prod_{i=1}^n \mu_i^{y_i} (1 - \mu_i)^{1-y_i} = \sum_{i=1}^n \log \mu_i^{y_i} (1 - \mu_i)^{1-y_i} = \\ &= \sum_{i=1}^n y_i \log \mu_i + (1 - y_i) \log(1 - \mu_i) \end{aligned}$$

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Logistic regression: parameter learning

- **Notation:** $\mu_i = p(y_i = 1 | \mathbf{x}_i, \mathbf{w}) = g(z_i) = g(\mathbf{w}^T \mathbf{x})$
- **Log likelihood**

$$l(D, \mathbf{w}) = \sum_{i=1}^n y_i \log \mu_i + (1 - y_i) \log(1 - \mu_i)$$

- **Derivatives of the loglikelihood**

$$\begin{aligned} -\frac{\partial}{\partial w_j} l(D, \mathbf{w}) &= \sum_{i=1}^n -x_{i,j} (y_i - g(z_i)) \\ \nabla_{\mathbf{w}} l(D, \mathbf{w}) &= \sum_{i=1}^n -\mathbf{x}_i (y_i - g(\mathbf{w}^T \mathbf{x}_i)) = \sum_{i=1}^n -\mathbf{x}_i (y_i - f(\mathbf{w}, \mathbf{x}_i)) \end{aligned}$$

Nonlinear in weights !!

- **Gradient descent:**

$$\begin{aligned} \mathbf{w}^{(k)} &\leftarrow \mathbf{w}^{(k-1)} - \alpha(k) \nabla_{\mathbf{w}} [-l(D, \mathbf{w})] \Big|_{\mathbf{w}^{(k-1)}} \\ \mathbf{w}^{(k)} &\leftarrow \mathbf{w}^{(k-1)} + \alpha(k) \sum_{i=1}^n [y_i - f(\mathbf{w}^{(k-1)}, \mathbf{x}_i)] \mathbf{x}_i \end{aligned}$$

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Derivation of the gradient

- **Log likelihood** $l(D, \mathbf{w}) = \sum_{i=1}^n y_i \log \mu_i + (1 - y_i) \log(1 - \mu_i)$

- **Derivatives of the loglikelihood**

$$\frac{\partial}{\partial w_j} l(D, \mathbf{w}) = \sum_{i=1}^n \frac{\partial}{\partial z_i} [y_i \log \mu_i + (1 - y_i) \log(1 - \mu_i)] \frac{\partial z_i}{\partial w_j}$$

Derivative of a logistic function

$$\frac{\partial z_i}{\partial w_j} = x_{i,j} \quad \frac{\partial g(z_i)}{\partial z_i} = g(z_i)(1 - g(z_i))$$

$$\begin{aligned} \frac{\partial}{\partial z_i} [y_i \log \mu_i + (1 - y_i) \log(1 - \mu_i)] &= y_i \frac{1}{g(z_i)} \frac{\partial g(z_i)}{\partial z_i} + (1 - y_i) \frac{-1}{1 - g(z_i)} \frac{\partial g(z_i)}{\partial z_i} \\ &= y_i(1 - g(z_i)) + (1 - y_i)(-g(z_i)) = y_i - g(z_i) \end{aligned}$$

$$\nabla_{\mathbf{w}} l(D, \mathbf{w}) = \sum_{i=1}^n \mathbf{x}_i (y_i - g(\mathbf{w}^T \mathbf{x}_i)) = \sum_{i=1}^n \mathbf{x}_i (y_i - f(\mathbf{w}, \mathbf{x}_i))$$

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Logistic regression. Online gradient descent

- **On-line component of the loglikelihood**

$$- J_{\text{online}}(D_i, \mathbf{w}) = y_i \log \mu_i + (1 - y_i) \log(1 - \mu_i)$$

- **On-line learning update for weight \mathbf{w}** $J_{\text{online}}(D_k, \mathbf{w})$

$$\mathbf{w}^{(k)} \leftarrow \mathbf{w}^{(k-1)} - \alpha(k) \nabla_{\mathbf{w}} [J_{\text{online}}(D_k, \mathbf{w})] |_{\mathbf{w}^{(k-1)}}$$

- **ith update for the logistic regression** and $D_k = \langle \mathbf{x}_k, y_k \rangle$

$$\mathbf{w}^{(i)} \leftarrow \mathbf{w}^{(k-1)} + \alpha(k)[y_i - f(\mathbf{w}^{(k-1)}, \mathbf{x}_k)]\mathbf{x}_k$$

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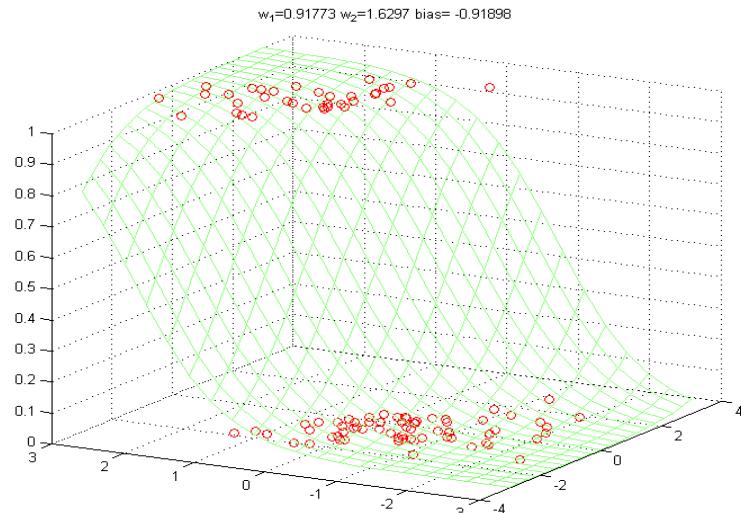
Online logistic regression algorithm

Online-logistic-regression (D , number of iterations)

```
initialize weights  $\mathbf{w} = (w_0, w_1, w_2 \dots w_d)$ 
for  $i=1:1:$  number of iterations
    do      select a data point  $D_i = \langle \mathbf{x}_i, y_i \rangle$  from  $D$ 
            set  $\alpha = 1/i$ 
            update weights (in parallel)
             $\mathbf{w} \leftarrow \mathbf{w} + \alpha(i)[y_i - f(\mathbf{w}, \mathbf{x}_i)]\mathbf{x}_i$ 
    end for
return weights  $\mathbf{w}$ 
```

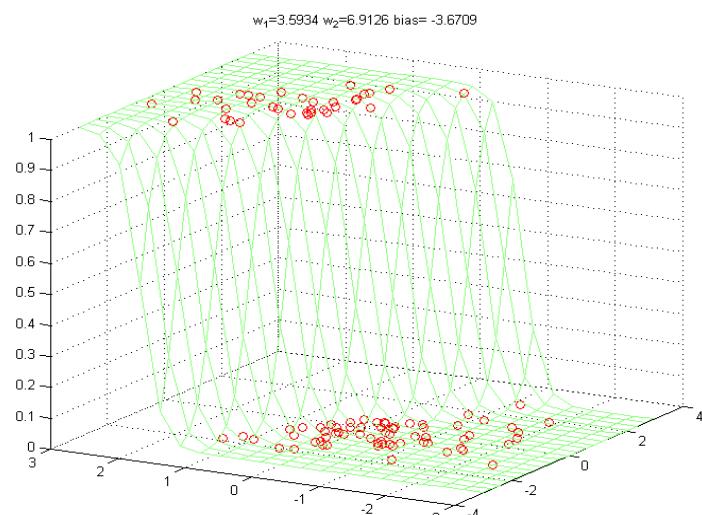
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Online algorithm. Example.



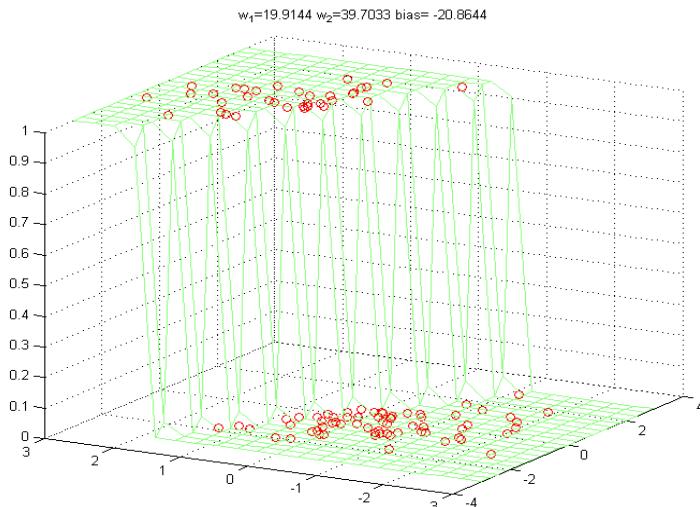
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Online algorithm. Example.



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Online algorithm. Example.



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Generative approach to classification

Logistic regression: model $p(y | \mathbf{x})$

Generative approach:

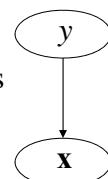
1. Represent and learn the distribution $p(\mathbf{x}, y)$
2. Use it to define probabilistic discriminant functions

E.g. $g_0(\mathbf{x}) = p(y = 0 | \mathbf{x})$ $g_1(\mathbf{x}) = p(y = 1 | \mathbf{x})$

Typical model $p(\mathbf{x}, y) = p(\mathbf{x} | y)p(y)$

- $p(\mathbf{x} | y)$ = **Class-conditional distributions (densities)**
binary classification: two class-conditional distributions
 $p(\mathbf{x} | y = 0)$ $p(\mathbf{x} | y = 1)$
- $p(y)$ = **Priors on classes** - probability of class y
binary classification: Bernoulli distribution

$$p(y = 0) + p(y = 1) = 1$$



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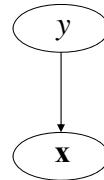
Quadratic discriminant analysis (QDA)

Model:

- **Class-conditional distributions**
 - **multivariate normal distributions**

$$\mathbf{x} \sim N(\boldsymbol{\mu}_0, \Sigma_0) \quad \text{for } y = 0$$

$$\mathbf{x} \sim N(\boldsymbol{\mu}_1, \Sigma_1) \quad \text{for } y = 1$$



Multivariate normal $\mathbf{x} \sim N(\boldsymbol{\mu}, \Sigma)$

$$p(\mathbf{x} | \boldsymbol{\mu}, \Sigma) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp \left[-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right]$$

- **Priors on classes (class 0,1)** $y \sim \text{Bernoulli}$
 - **Bernoulli distribution**

$$p(y, \theta) = \theta^y (1 - \theta)^{1-y} \quad y \in \{0,1\}$$

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Learning of parameters of the QDA model

Density estimation in statistics

- We see examples – we do not know the parameters of Gaussians (class-conditional densities)

$$p(\mathbf{x} | \boldsymbol{\mu}, \Sigma) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp \left[-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right]$$

- **ML estimate of parameters** of a multivariate normal $N(\boldsymbol{\mu}, \Sigma)$ for a set of n examples of \mathbf{x}

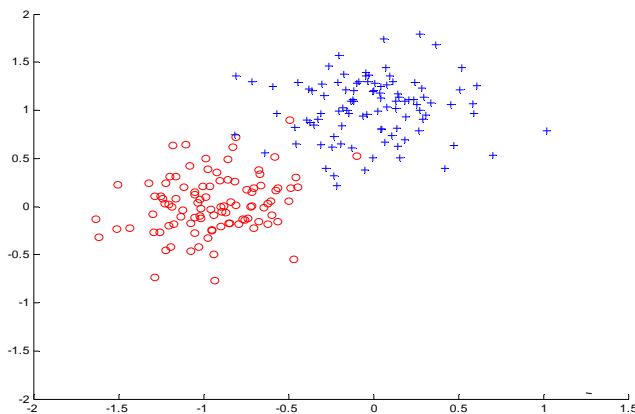
Optimize log-likelihood: $l(D, \boldsymbol{\mu}, \Sigma) = \log \prod_{i=1}^n p(\mathbf{x}_i | \boldsymbol{\mu}, \Sigma)$

$$\hat{\boldsymbol{\mu}} = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i \quad \hat{\Sigma} = \frac{1}{n} \sum_{i=1}^n (\mathbf{x}_i - \hat{\boldsymbol{\mu}})(\mathbf{x}_i - \hat{\boldsymbol{\mu}})^T$$

- How about **class priors**?

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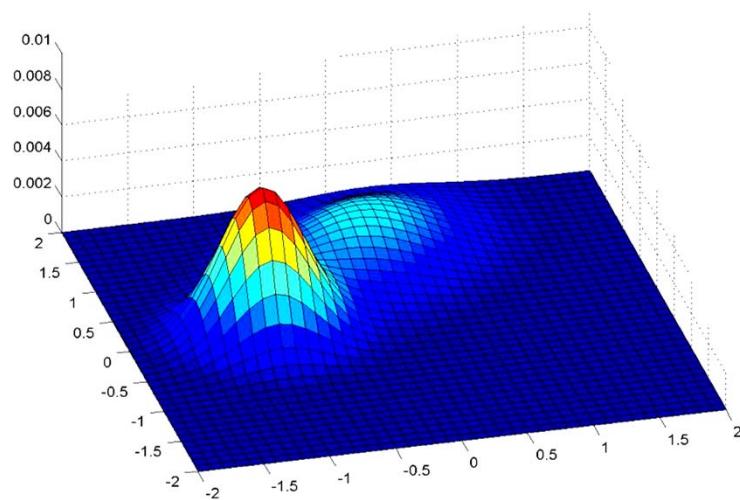
QDA



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2 Gaussian class-conditional densities

Class conditional densities



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QDA: Making class decision

Basically we need to design discriminant functions

Two possible choices:

- **Likelihood of data** – choose the class (Gaussian) that explains the input data (\mathbf{x}) better (likelihood of the data)

$$\underbrace{p(\mathbf{x} | \mu_1, \Sigma_1)}_{g_1(\mathbf{x})} > \underbrace{p(\mathbf{x} | \mu_0, \Sigma_0)}_{g_0(\mathbf{x})} \rightarrow \begin{array}{ll} \text{then } y=1 \\ \text{else } y=0 \end{array}$$

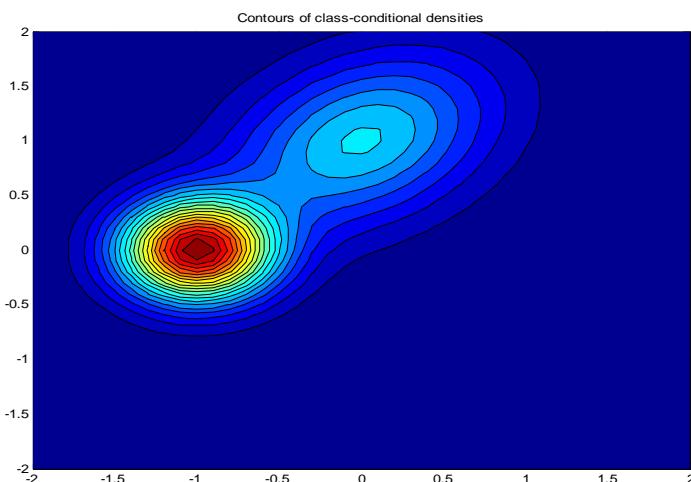
- **Posterior of a class** – choose the class with better posterior probability

$$p(y = 1 | \mathbf{x}) > p(y = 0 | \mathbf{x}) \quad \begin{array}{ll} \text{then } y=1 \\ \text{else } y=0 \end{array}$$

$$p(y = 1 | \mathbf{x}) = \frac{p(\mathbf{x} | \mu_1, \Sigma_1) p(y = 1)}{p(\mathbf{x} | \mu_0, \Sigma_0) p(y = 0) + p(\mathbf{x} | \mu_1, \Sigma_1) p(y = 1)}$$

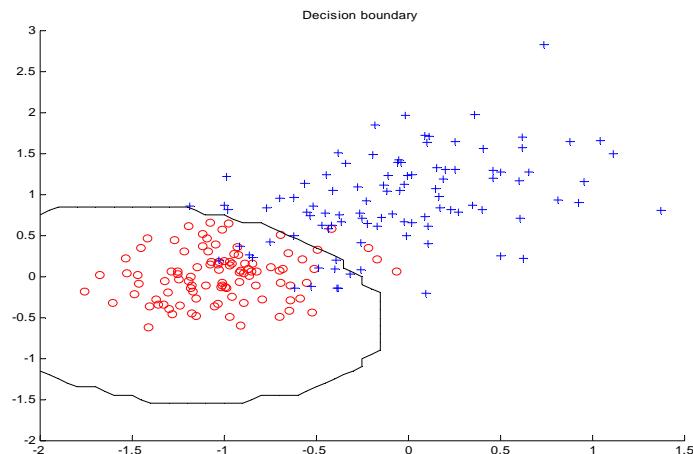
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QDA: Quadratic decision boundary



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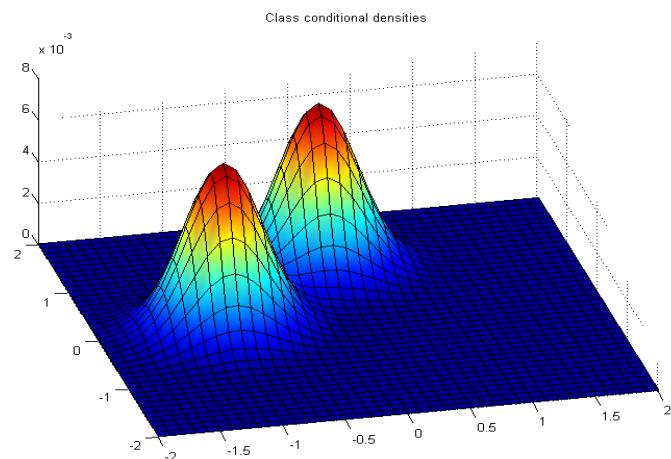
QDA: Quadratic decision boundary



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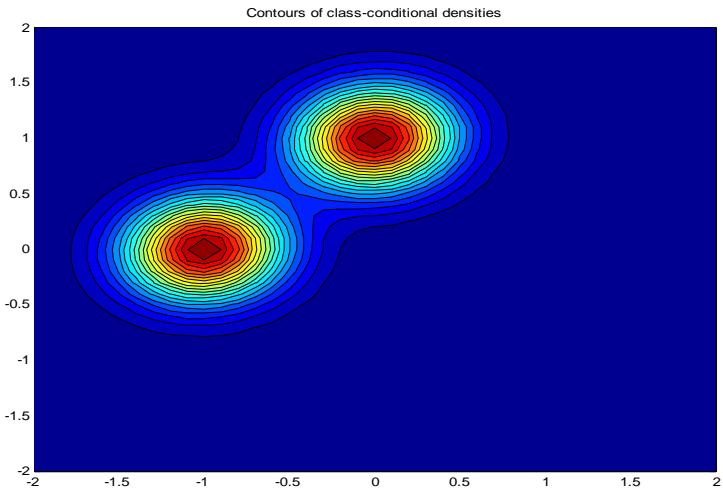
Linear discriminant analysis (LDA)

- When covariances are the same $\mathbf{x} \sim N(\boldsymbol{\mu}_0, \Sigma), y = 0$
 $\mathbf{x} \sim N(\boldsymbol{\mu}_1, \Sigma), y = 1$



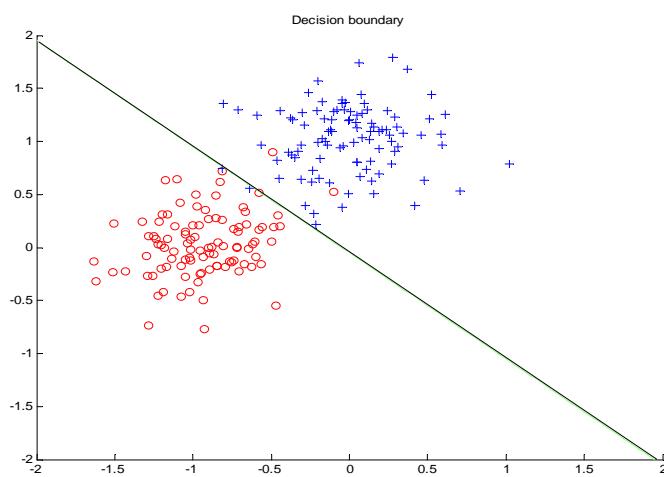
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LDA: Linear decision boundary



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LDA: linear decision boundary



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