### CS 1675 Introduction to Machine Learning Lecture 22

# **Dimensionality reduction II**

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## **Dimensionality reduction**

Problem: Is there a lower dimensional representation of the data that captures well its characteristics?

- Assume:
  - We have data  $D = \{\mathbf{x_1, x_2,..., x_N}\}$  such that  $\mathbf{x}_i = (x_i^1, x_i^2, ..., x_i^d)$
  - Assume the dimension d of the data point x is very large
- · Our goal:
- find a lower dimensional representation d' of the data
  - where every  $\mathbf{x}_i$  is replaced with a new  $\mathbf{x}_i$ '
- Why we want to do this?
  - Many methods of analysis are sensitive to the dimensionality d

## Task-specific feature selection

#### **Assume:** Classification problem:

 $-\mathbf{x}$  - input vector,  $\mathbf{y}$  - output

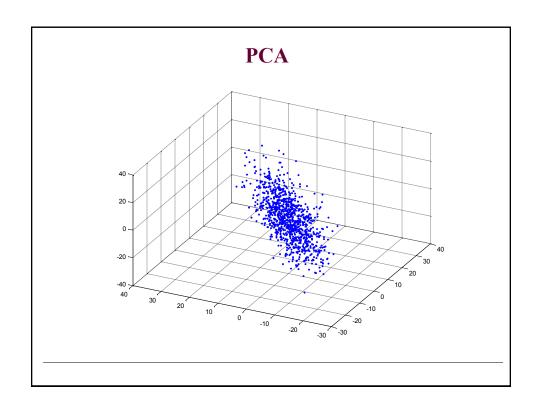
**Objective:** Find a subset of inputs/features that gives/preserves most of the data prediction capabilities

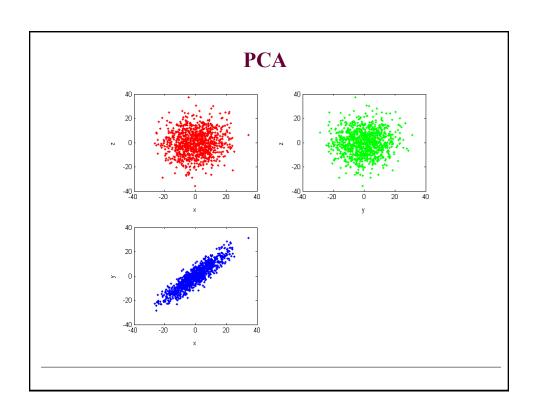
#### **Selection approaches:**

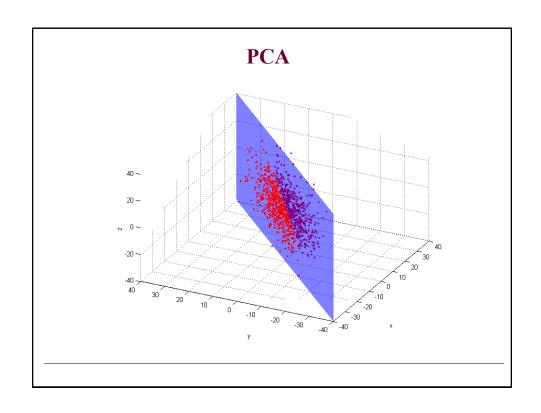
- Filtering approaches
  - Filter out features with small predictive potential
  - Done before classification; typically uses univariate analysis
- Wrapper approaches
  - Select features that directly optimize the accuracy of the multivariate classifier
- Embedded methods
  - Feature selection and learning closely tied in the method
  - Regularization methods, decision tree methods

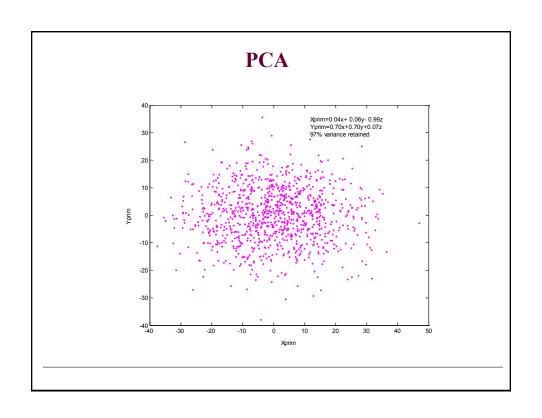
## Principal component analysis (PCA)

- Unsupervised dimensionality reduction method
- **Objective:** We want to replace a high dimensional input with a small set of features (obtained by combining inputs)
  - Different from the feature subset selection !!!
- PCA:
  - A linear transformation of d dimensional input x to M dimensional feature vector z such that M < d under which the retained variance is maximal.
  - Equivalently it is the linear projection for which the sum of squares reconstruction cost is minimized.









## Principal component analysis (PCA)

- PCA:
  - linear transformation of a d dimensional input  $\mathbf{x}$  to  $\mathbf{M}$  dimensional vector  $\mathbf{z}$  such that M < d under which the retained variance is maximal.
  - Task independent
- Fact:
  - A vector  $\mathbf{x}$  can be represented using a set of orthonormal vectors  $\mathbf{u}$   $\mathbf{x} = \sum_{i=1}^{d} z_i \mathbf{u}_i$
  - Leads to transformation of coordinates (from x to z using u's)

$$z_i = \mathbf{u}_i^T \mathbf{x}$$

### **PCA**

• Idea: replace d coordinates with M of  $z_i$  coordinates to represent x. We want to find the subset M of basis vectors.

$$\widetilde{\mathbf{x}} = \sum_{i=1}^{M} z_i \mathbf{u}_i + \sum_{i=M+1}^{d} b_i \mathbf{u}_i$$

 $b_i$  - constant and fixed

- How to choose the best set of basis vectors?
  - We want the subset that gives the best approximation of data x in the dataset on average (we use least squares fit)

Error for data entry  $\mathbf{x}^n$   $\mathbf{x}^n - \widetilde{\mathbf{x}}^n = \sum_{i=M+1}^d (z_i^n - b_i) \mathbf{u}_i$ Reconstruction error

 $E_{M} = \frac{1}{2} \sum_{n=1}^{N} \|\mathbf{x}^{n} - \widetilde{\mathbf{x}}^{n}\| = \frac{1}{2} \sum_{n=1}^{N} \sum_{i=M+1}^{d} (z_{i}^{n} - b_{i})^{2}$ 

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### **PCA**

• **Differentiate the error function** with regard to all  $b_i$  and set equal to 0 we get:

$$b_i = \frac{1}{N} \sum_{n=1}^{N} z_i^n = \mathbf{u}_i^T \overline{\mathbf{x}} \qquad \overline{\mathbf{x}} = \frac{1}{N} \sum_{n=1}^{N} \mathbf{x}^n$$

• Then we can rewrite:

$$E_{M} = \frac{1}{2} \sum_{i=M+1}^{d} \mathbf{u}_{i}^{T} \mathbf{\Sigma} \mathbf{u}_{i} \qquad \mathbf{\Sigma} = \sum_{n=1}^{N} (\mathbf{x}^{n} - \overline{\mathbf{x}}) (\mathbf{x}^{n} - \overline{\mathbf{x}})^{T}$$

• The error function is optimized when basis vectors satisfy:

$$\mathbf{\Sigma}\mathbf{u}_{i} = \lambda_{i}\mathbf{u}_{i} \qquad \qquad E_{M} = \frac{1}{2}\sum_{i=M+1}^{d}\lambda_{i}$$

# **Eigenvectors**

If A is a square matrix, a non-zero vector v is an eigenvector of
A if there is a scalar λ (eigenvalue) such that

$$Av = \lambda v$$

- Example:  $\begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 3 \\ 2 \end{pmatrix} = \begin{pmatrix} 12 \\ 8 \end{pmatrix} = 4 \begin{pmatrix} 3 \\ 2 \end{pmatrix}$
- If we think of the squared matrix as a transformation matrix, then multiply it with the eigenvector do not change its direction.

### **PCA**

• The error function

$$E_{M} = \frac{1}{2} \sum_{i=M+1}^{d} \mathbf{u}_{i}^{T} \mathbf{\Sigma} \mathbf{u}_{i} \qquad \mathbf{\Sigma} = \sum_{n=1}^{N} (\mathbf{x}^{n} - \overline{\mathbf{x}}) (\mathbf{x}^{n} - \overline{\mathbf{x}})^{T}$$

• is optimized when basis vectors satisfy:

$$\mathbf{\Sigma}\mathbf{u}_{i} = \lambda_{i}\mathbf{u}_{i} \qquad \qquad E_{M} = \frac{1}{2}\sum_{i=M+1}^{d}\lambda_{i}$$

- Eigenvectors:  $\mathbf{u}_i$  are called **principal components**
- Solution: Select the best *M* basis vectors: that is, basis vectors with the largest eigenvalues
- Or equivalently discard basis vectors with *d-M* smallest eigenvalues

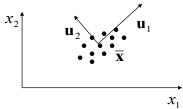
# **PCA** algorithm

PCA steps: transform an  $N \times d$  matrix X into an  $N \times m$  matrix Y:

- Centralize the data (subtract the mean).
- Calculate the  $d \times d$  covariance matrix:  $C = \frac{1}{N-1}X^TX$
- $C_{i,j} = \frac{1}{N-1} \sum_{q=1}^{N} X_{q,i} X_{q,j}$ 
  - o  $C_{i,i}$  (diagonal) is the variance of variable i.
  - o  $C_{i,j}$  (off-diagonal) is the covariance between variables i and j.
- Calculate the eigenvectors of the covariance matrix (orthonormal).
- Select *m* eigenvectors that correspond to the largest *m* eigenvalues to be the new basis.

### **PCA**

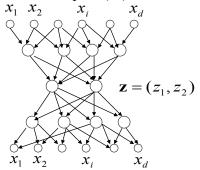
 Once eigenvectors u<sub>i</sub> with largest eigenvalues are identified, they are used to transform the original d-dimensional data to M dimensions



- To find the "true" dimensionality of the data d' we can just look at eigenvalues that contribute the most (small eigenvalues are disregarded)
- **Problem:** PCA is a linear method. The "true" dimensionality can be overestimated. There can be non-linear correlations.
- Modifications for nonlinearities: kernel PCA

# Dimensionality reduction with neural nets

- PCA is limited to linear dimensionality reduction
- To do non-linear reductions we can use neural nets
- Auto-associative (or auto-encoder) network: a neural network with the same inputs and outputs (x)



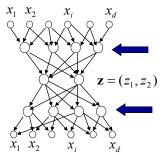
The middle layer corresponds to the reduced dimensions

## **Dimensionality reduction with neural nets**

• Error criterion:

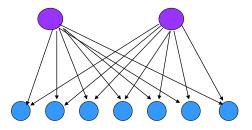
$$E = \frac{1}{2} \sum_{n=1}^{N} \sum_{i=1}^{d} (y_i(x^n) - x^n)^2$$

- Error measure tries to recover the original data through limited number of dimensions in the middle layer
- Non-linearities modeled through intermediate layers between the middle layer and input/output
- If no intermediate layers are used the model replicates PCA optimization through learning



## Latent variable models

Latent variables (s): Dimensionality k



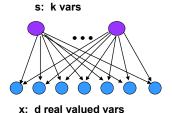
Observed variables x: real valued vars Dimensionality d

## **Examples**

#### **Model:**

$$x = \mathbf{W}\mathbf{s}$$

$$\mathbf{W} = \begin{pmatrix} w_{11} & w_{12} & \dots & w_{1k} \\ w_{21} & & & & \\ & & \dots & & \\ w_{d1} & \dots & \dots & w_{dk} \end{pmatrix}$$



### **Factor analysis:**

- **Decomposes** signal into multiple Gaussian sources **Cooperative vector quantizer:**
- **Decomposes** signal into binary sources

## **Multidimensional scaling**

- Find a lower dimensional space projection such that the distances among data points are preserved
- Used in visualization d-diminensional data transformed to 3D or 2D
- Dissimilarities before projection  $\delta_{i,j} = ||x_i x_j||$
- Objective: Optimize points and their coordinates by fitting the dissimilarities afterwards

$$\min_{\{x_1, x_2, \dots x_n\}} \sum_{i < j} (||x_i' - x_j'|| - \delta_{ij})^2$$

CS 2750 Machine Learning