

CS 1675 Introduction to Machine Learning
Lecture 12

Multilayer neural networks

Milos Hauskrecht
milos@cs.pitt.edu
5329 Sennott Square

CS 2750 Machine Learning

Midterm exam

Midterm Thursday, March 2, 2017

- in-class (75 minutes)
- closed book

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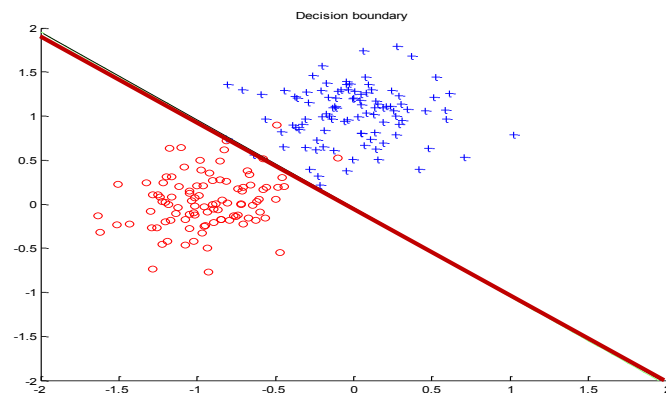
Multilayer neural networks

Or another way of modeling nonlinearities
for regression and classification problems

Classification with the linear model.

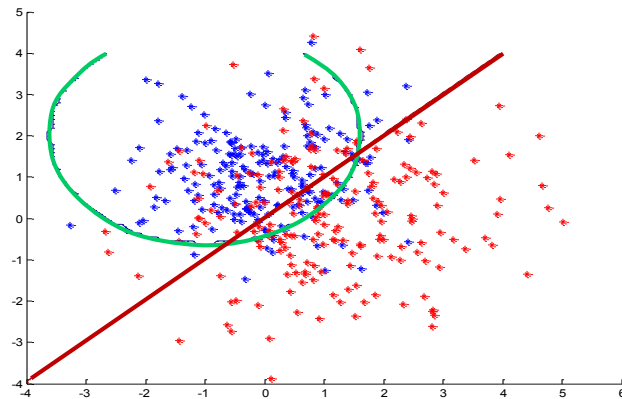
Logistic regression model defines a linear decision boundary

- Example: 2 classes (blue and red points)



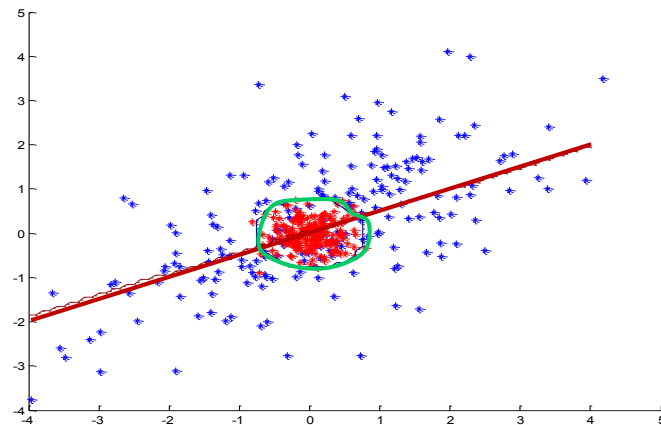
Linear decision boundary

- logistic regression model is not optimal, but not that bad



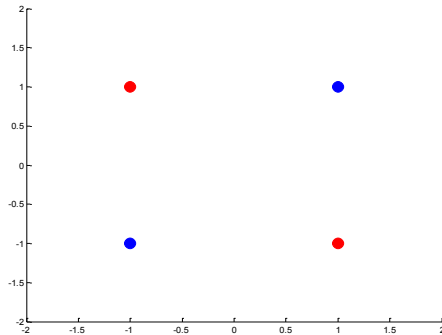
When logistic regression fails?

- Example in which the logistic regression model fails



Limitations of linear units

- Logistic regression does not work for **parity functions**
 - no linear decision boundary exists



Solution: a model of a non-linear decision boundary

Extensions of simple linear units

- Feature (basis) functions to model **nonlinearities**

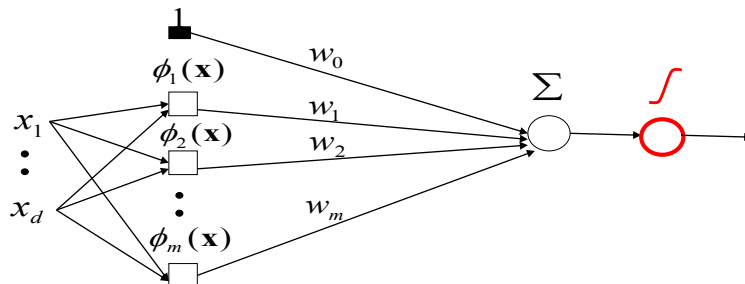
Linear regression

$$f(\mathbf{x}) = w_0 + \sum_{j=1}^m w_j \phi_j(\mathbf{x})$$

Logistic regression

$$f(\mathbf{x}) = g(w_0 + \sum_{j=1}^m w_j \phi_j(\mathbf{x}))$$

$\phi_j(\mathbf{x})$ - an arbitrary function of $\mathbf{x}$



Learning with extended linear units

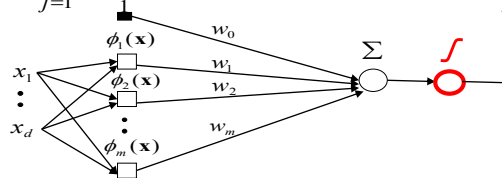
Feature (basis) functions model **nonlinearities**

Linear regression

$$f(\mathbf{x}) = w_0 + \sum_{j=1}^m w_j \phi_j(\mathbf{x})$$

Logistic regression

$$f(\mathbf{x}) = g(w_0 + \sum_{j=1}^m w_j \phi_j(\mathbf{x}))$$



Good property:

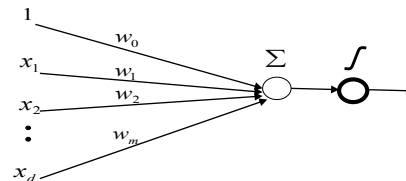
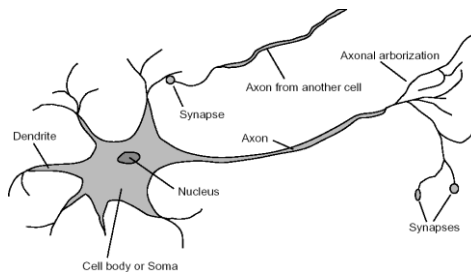
- The same problem as learning of the weights for linear units

Problems:

- define the right set of basis functions
- Many basis functions $\rightarrow$ many weights to learn

Multi-layered neural networks

- An alternative way to introduce **nonlinearities to regression/classification models**
- **Key idea: Cascade several simple nonlinear switching models (e.g. logistic units) to model nonlinearities.** Much like neuron connections.

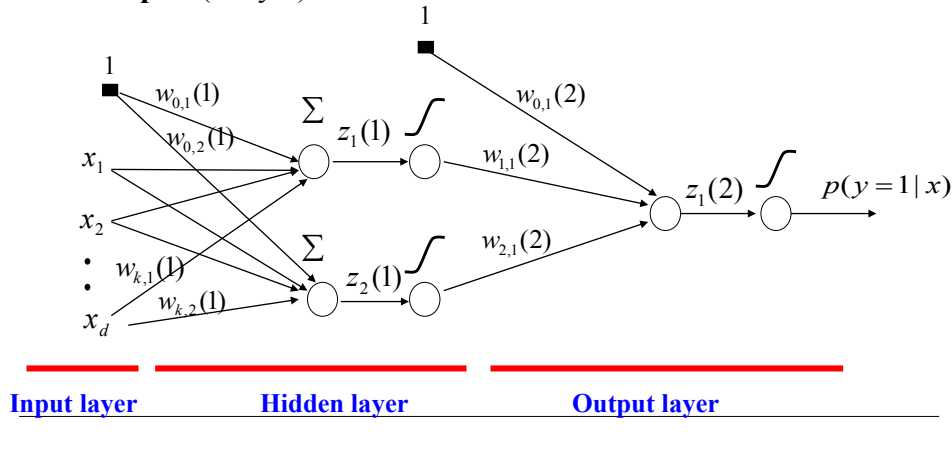


Multilayer neural network

Also called a **multilayer perceptron (MLP)**

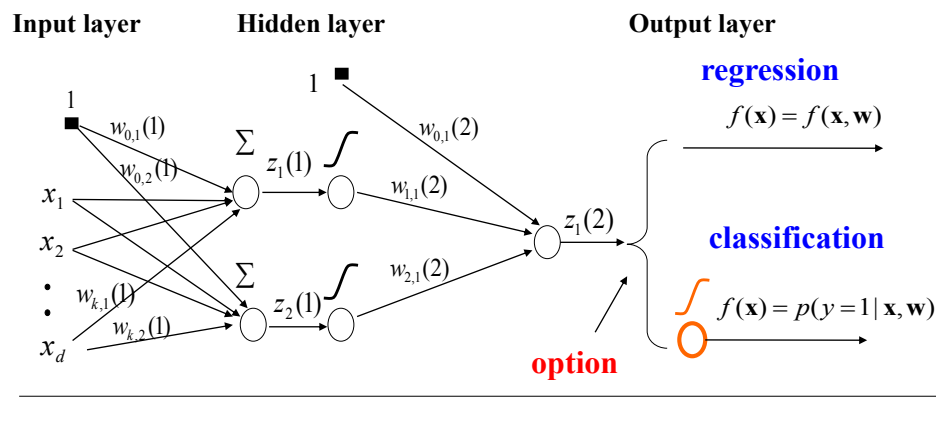
Cascades multiple **logistic regression** units

Example: (2 layer) classifier with non-linear decision boundaries



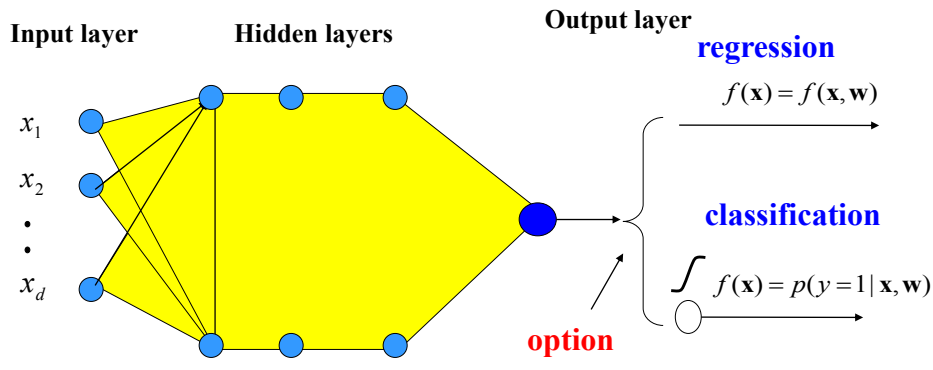
Multilayer neural network

- Models **non-linearity through nonlinear switching units**
- Can be applied to both **regression and binary classification problems**



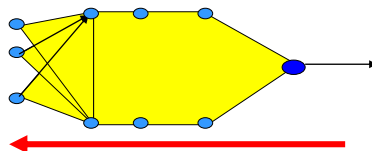
Multilayer neural network

- Non-linearities are modeled using multiple hidden nonlinear units (organized in layers)
- The output layer determines whether it is a **regression** or a **binary classification problem**



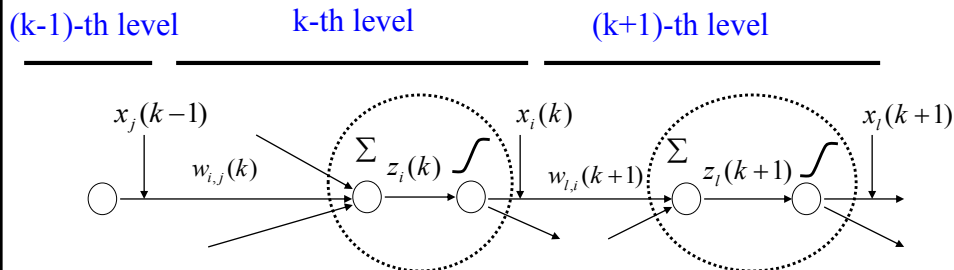
Learning with MLP

- How to learn the parameters of the neural network?
 - **Gradient descent algorithm**
 - Weight updates based on the error: $J(D, \mathbf{w})$
- $$\mathbf{w} \leftarrow \mathbf{w} - \alpha \nabla_{\mathbf{w}} J(D, \mathbf{w})$$
- We need to **compute gradients for weights in all units**
 - **Can be computed in one backward sweep through the net !!!**



- The process is called **back-propagation**

Backpropagation



$x_i(k)$ - output of the unit i on level k

$z_i(k)$ - input to the sigmoid function on level k

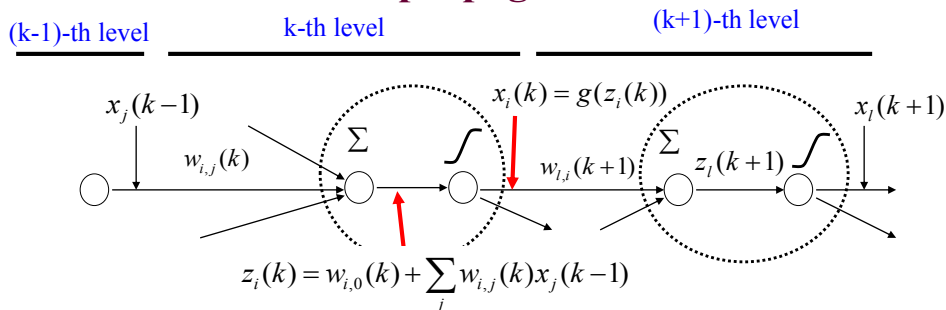
$w_{i,j}(k)$ - weight between units j and i on levels $(k-1)$ and k

$$z_i(k) = w_{i,0}(k) + \sum_j w_{i,j}(k)x_j(k-1)$$

$$x_i(k) = g(z_i(k))$$

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Backpropagation



- **Error function:** $J(D, \mathbf{w})$ (online) error where D is a data point

– **Regression**

$$J(D, \mathbf{w}) = (y_u - f(\mathbf{x}_u))^2$$

– **Classification**

$$J(D, \mathbf{w}) = -\log p(y_u | \mathbf{x}_u)$$

- **Gradient descent:** $w_{i,j}(k) \leftarrow w_{i,j}(k) - \alpha \frac{\partial}{\partial w_{i,j}(k)} J(D, \mathbf{w})$

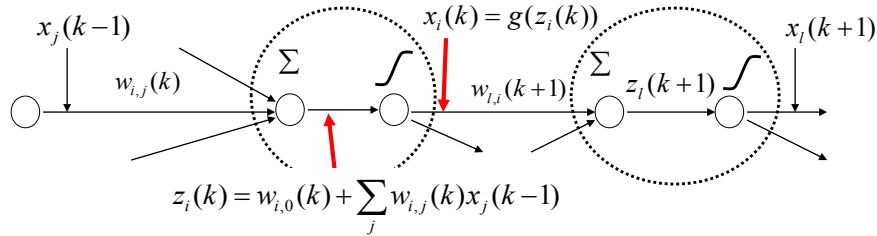
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Backpropagation

(k-1)-th level

k-th level

(k+1)-th level



- Gradient descent:** $w_{i,j}(k) \leftarrow w_{i,j}(k) - \alpha \frac{\partial}{\partial w_{i,j}(k)} J(D, \mathbf{w})$

$$\frac{\partial}{\partial w_{i,j}(k)} J(D, \mathbf{w}) = \frac{\partial J(D, \mathbf{w})}{\partial z_i(k)} \frac{\partial z_i(k)}{\partial w_{i,j}(k)} = \delta_i(k) x_j(k-1)$$

$$\delta_i(k) = \frac{\partial}{\partial z_i(k)} J(D, \mathbf{w}) \quad x_j(k-1)$$

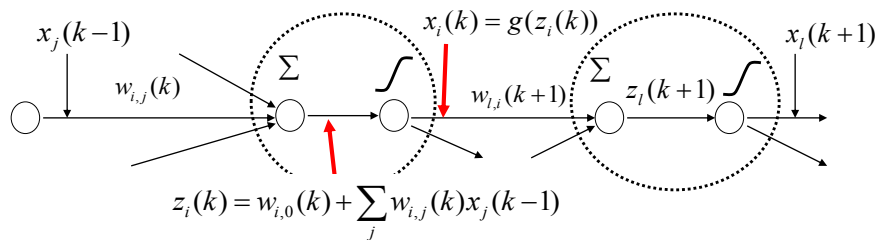
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Backpropagation

(k-1)-th level

k-th level

(k+1)-th level



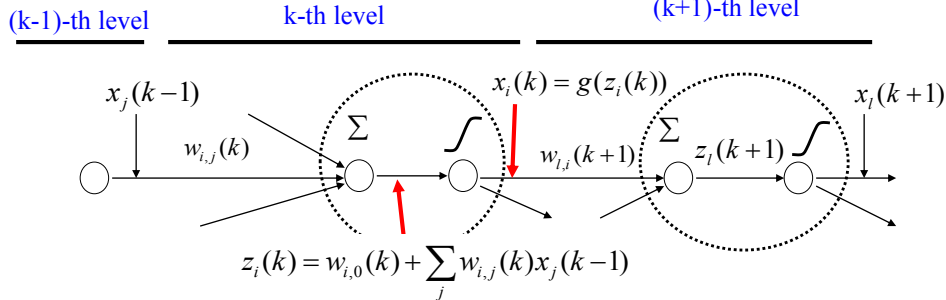
- Derivation:**

$$\delta_i(k) = \frac{\partial}{\partial z_i(k)} J(D, \mathbf{w}) = \frac{\partial}{\partial x_i(k)} J(D, \mathbf{w}) * \frac{\partial x_i(k)}{\partial z_i(k)}$$

$$\frac{\partial}{\partial x_i(k)} J(D, \mathbf{w}) = \sum_l \underbrace{\frac{\partial}{\partial z_l(k+1)} J(D, \mathbf{w})}_{\delta_l(k+1)} * \underbrace{\frac{\partial z_l(k+1)}{\partial x_i(k+1)}}_{w_{l,i}(k+1)} \quad \frac{\partial x_i(k)}{\partial z_i(k)} = x_i(k)(1 - x_i(k))$$

$$\delta_i(k) = \left[\sum_l \delta_l(k+1) w_{l,i}(k+1) \right] x_i(k)(1 - x_i(k))$$

Backpropagation



- Gradient:**

$$w_{i,j}(k) \leftarrow w_{i,j}(k) - \alpha [\delta_i(k)x_j(k-1)]$$

$$\delta_i(k) = \left[\sum_l \delta_l(k+1)w_{l,i}(k+1) \right] x_i(k)(1-x_i(k))$$

- Last unit** (is the same as for the regular linear units),

E.g. for regression:

$$\delta_i(K) = -(y_u - f(\mathbf{x}_u, \mathbf{w}))$$

Backpropagation

Update weight $w_{i,j}(k)$ using data D $D = \{<\mathbf{x}, y>\}$

$$w_{i,j}(k) \leftarrow w_{i,j}(k) - \alpha \frac{\partial}{\partial w_{i,j}(k)} J(D, \mathbf{w})$$

Let $\delta_i(k) = \frac{\partial}{\partial z_i(k)} J(D, \mathbf{w})$

Then: $\frac{\partial}{\partial w_{i,j}(k)} J(D, \mathbf{w}) = \frac{\partial J(D, \mathbf{w})}{\partial z_i(k)} \frac{\partial z_i(k)}{\partial w_{i,j}(k)} = \delta_i(k)x_j(k-1)$

S.t. $\delta_i(k)$ is computed from $x_i(k)$ and the next layer $\delta_i(k+1)$

$$\delta_i(k) = \left[\sum_l \delta_l(k+1)w_{l,i}(k+1) \right] x_i(k)(1-x_i(k))$$

Last unit (is the same as for the regular linear units):

$$\delta_i(K) = -(y_u - f(\mathbf{x}_u, \mathbf{w}))$$

It is the same for the classification with the log-likelihood measure of fit and linear regression with least-squares error!!!

Learning with MLP

- **Online gradient descent algorithm**

- Weight update:

$$w_{i,j}(k) \leftarrow w_{i,j}(k) - \alpha \frac{\partial}{\partial w_{i,j}(k)} J_{\text{online}}(D_u, \mathbf{w})$$

$$\frac{\partial}{\partial w_{i,j}(k)} J_{\text{online}}(D_u, \mathbf{w}) = \frac{\partial J_{\text{online}}(D_u, \mathbf{w})}{\partial z_i(k)} \frac{\partial z_i(k)}{\partial w_{i,j}(k)} = \delta_i(k) x_j(k-1)$$

$$w_{i,j}(k) \leftarrow w_{i,j}(k) - \alpha \delta_i(k) x_j(k-1)$$

$x_j(k-1)$ - j-th output of the (k-1) layer

$\delta_i(k)$ - derivative computed via backpropagation

α - a learning rate

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Online gradient descent algorithm for MLP

Online-gradient-descent (D , number of iterations)

Initialize all weights $w_{i,j}(k)$

for $i=1:1$: number of iterations

do **select** a data point $D_u = \langle \mathbf{x}, y \rangle$ from D

set learning rate α

compute outputs $x_j(k)$ for each unit

compute derivatives $\delta_i(k)$ via **backpropagation**

update all weights (in parallel)

$$w_{i,j}(k) \leftarrow w_{i,j}(k) - \alpha \delta_i(k) x_j(k-1)$$

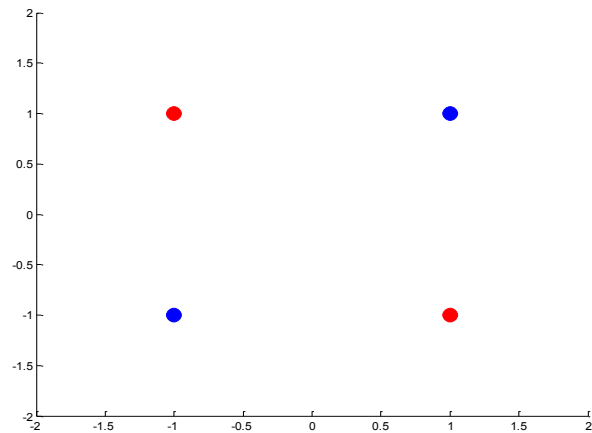
end for

return weights $\mathbf{w}$

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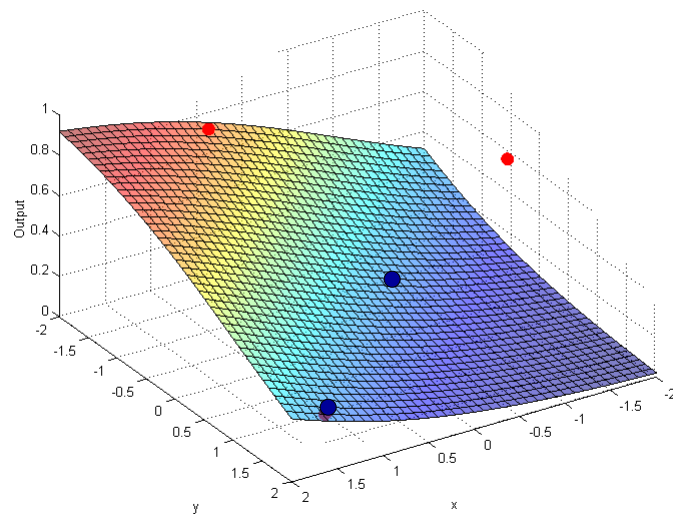
Xor Example.

- linear decision boundary does not exist



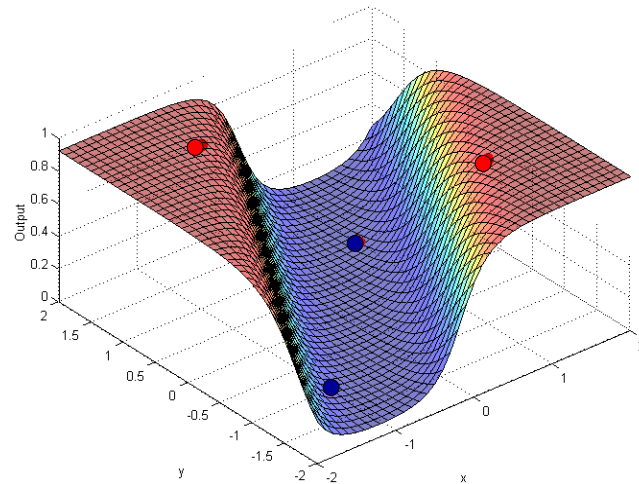
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Xor example. Linear unit



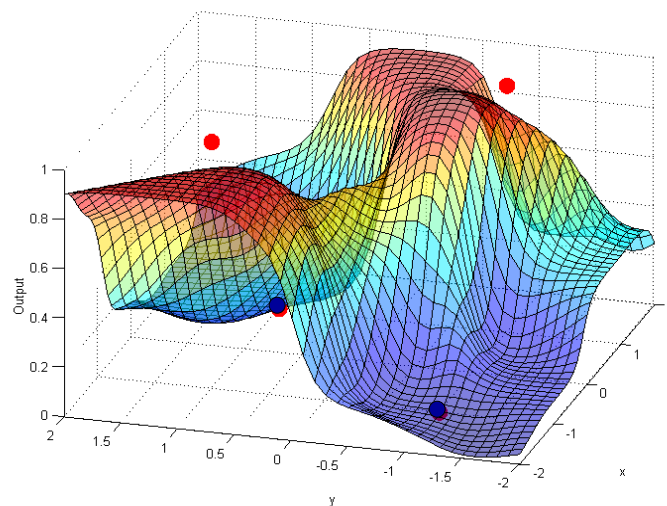
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Xor example.
Neural network with 2 hidden units



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Xor example.
Neural network with 10 hidden units



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MLP in practice

- **Optical character recognition** – digits 20x20
 - Automatic sorting of mails
 - 5 layer network with multiple output functions

