

# CS 1571 Introduction to AI

## Lecture 24

### Learning

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### Administration

- **Problem set 9:**
  - due on Thursday
- **Final exam**
  - December 10, 2003 at 10:00-11:50am
  - 25 % of the grade

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## Machine Learning

- The field of **machine learning** studies the design of computer programs (agents) capable of learning from past experience or adapting to changes in the environment
- The need for building agents capable of learning is everywhere
  - Predictions in medicine, text classification, speech recognition, image/text retrieval, commercial software
- Machine learning is not only the deduction but induction of rules from examples that facilitate prediction and decision making

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## Learning

### Learning process:

Learner (a computer program) takes data ***D*** representing past experiences and tries to either:

- to develop an appropriate response to future data, or
- describe in some meaningful way the data seen

### Example:

Learner sees a set of past patient cases (patient records) with corresponding diagnoses. It can either try:

- to predict the presence of a disease for future patients
- describe the dependencies between diseases, symptoms (e.g. builds a Bayesian network for them)

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## Types of learning

- **Supervised learning**
  - Learning mapping between inputs  $x$  and desired outputs  $y$
  - Teacher gives me  $y$ 's for the learning purposes
- **Unsupervised learning**
  - Learning relations between data components
  - No specific outputs given by a teacher
- **Reinforcement learning**
  - Learning mapping between inputs  $x$  and desired outputs  $y$
  - Critic does not give me  $y$ 's but instead a signal (reinforcement) of how good my answer was
- **Other types of learning:**
  - **Concept learning, explanation-based learning, etc.**

## Supervised learning

**Data:**  $D = \{d_1, d_2, \dots, d_n\}$  a set of  $n$  examples

$$d_i = \langle \mathbf{x}_i, y_i \rangle$$

$\mathbf{x}_i$  is input vector, and  $y$  is desired output (given by a teacher)

**Objective:** learn the mapping  $f : X \rightarrow Y$

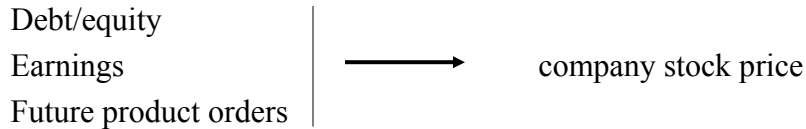
$$\text{s.t. } y_i \approx f(x_i) \quad \text{for all } i = 1, \dots, n$$

**Two types of problems:**

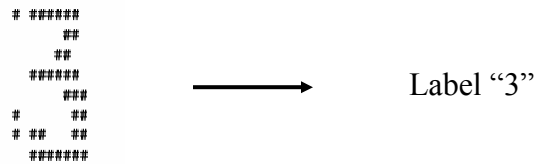
- **Regression:**  $X$  discrete or continuous  $\rightarrow$   
 $Y$  is **continuous**
- **Classification:**  $X$  discrete or continuous  $\rightarrow$   
 $Y$  is **discrete**

## Supervised learning examples

- **Regression:** Y is **continuous**



- **Classification:** Y is **discrete**



Handwritten digit (array of 0,1s)

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## Unsupervised learning

- **Data:**  $D = \{d_1, d_2, \dots, d_n\}$   
 $d_i = \mathbf{x}_i$  vector of values  
No target value (output) y
- **Objective:**
  - learn relations between samples, components of samples

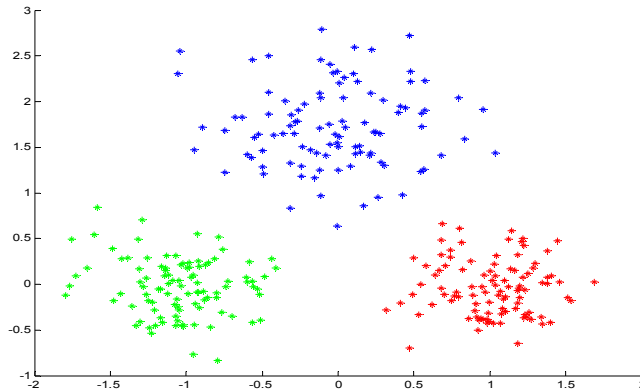
### Types of problems:

- **Clustering**  
Group together “similar” examples, e.g. patient cases
- **Density estimation**
  - Model probabilistically the population of samples, e.g. relations between the diseases, symptoms, lab tests etc.

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## Unsupervised learning example.

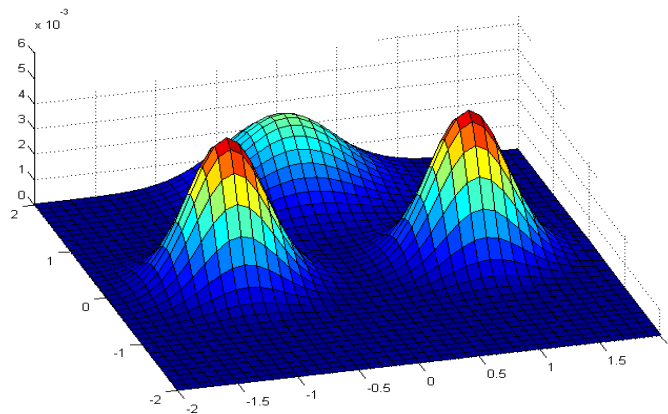
- **Density estimation.** We want to build the probability model of a population from which we draw samples  $d_i = \mathbf{x}_i$



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## Unsupervised learning. Density estimation

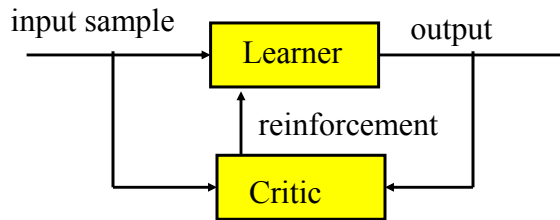
- A probability density of a point in the two dimensional space
  - Model used here: Mixture of Gaussians



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## Reinforcement learning

- We want to learn:  $f : X \rightarrow Y$
- We see samples of  $\mathbf{x}$  but not  $y$
- Instead of  $y$  we get a feedback (reinforcement) from a **critic** about how good our output was

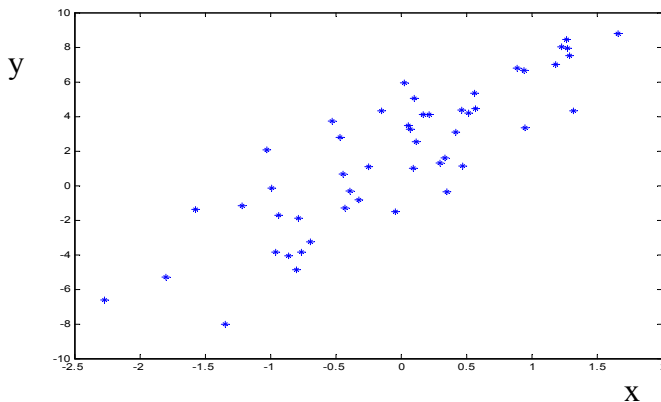


- The goal is to select output that leads to the best reinforcement

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## Learning

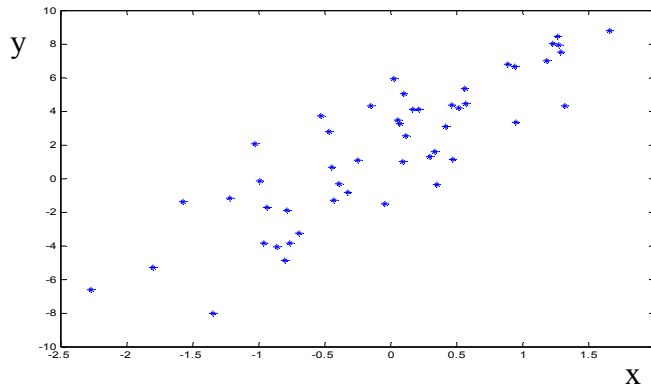
- Assume we see examples of pairs  $(\mathbf{x}, y)$  and we want to learn the mapping  $f : X \rightarrow Y$  to predict future  $y$ s for values of  $\mathbf{x}$
- We get the data what should we do?



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## Learning bias

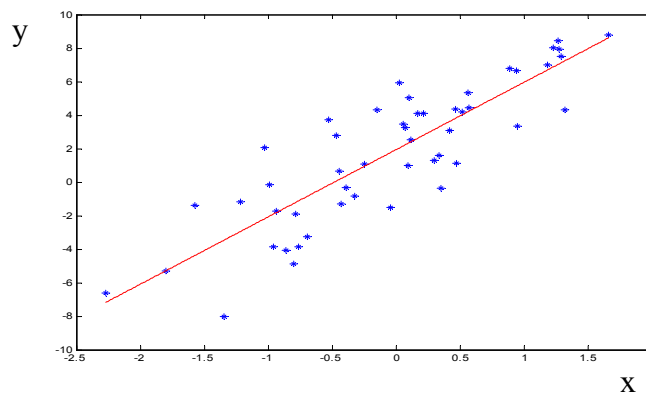
- **Problem:** many possible functions  $f: X \rightarrow Y$  exists for representing the mapping between  $x$  and  $y$
- Which one to choose? Many examples still unseen!



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## Learning bias

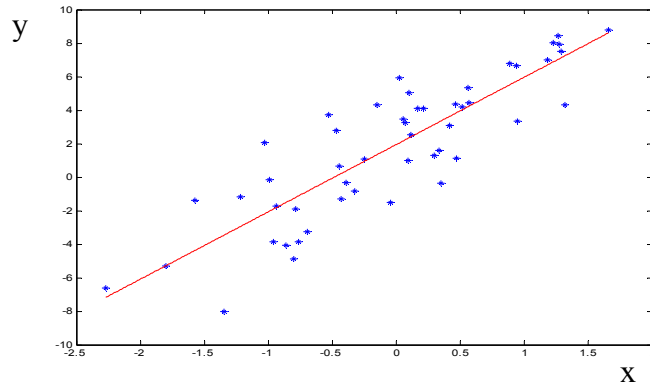
- Problem is easier when we make an assumption about the model, say,  $f(x) = ax + b + \varepsilon$   
 $\varepsilon = N(0, \sigma)$  - random (normally distributed) noise
- Restriction to a linear model is an example of the learning bias



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## Learning bias

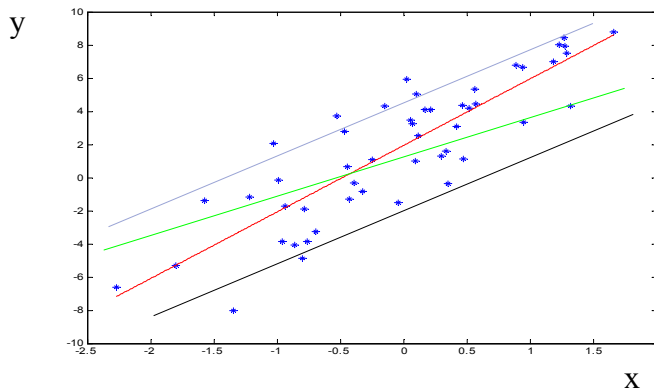
- **Bias** provides the learner with some basis for choosing among possible representations of the function.
- **Forms of bias:** constraints, restrictions, model preferences
- **Important:** There is no learning without a bias!



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## Learning bias

- Choosing a parametric model or a set of models is not enough  
Still too many functions  $f(x) = ax + b + \varepsilon$   $\varepsilon = N(0, \sigma)$ 
  - One for every pair of parameters  $a, b$



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## Fitting the data to the model

We are interested in finding the **best set** of model parameters

**How is the best set defined?**

Our goal is to have the parameters that:

- reduce the misfit between the model and data
- Or, (in other words) that explain the data the best

**Error function:**

**Gives a measure of misfit between the data and the model**

- Examples of error functions:

- Mean square error

$$\frac{1}{n} \sum_{i=1}^n (y_i - f(x_i))^2$$

- Misclassification error

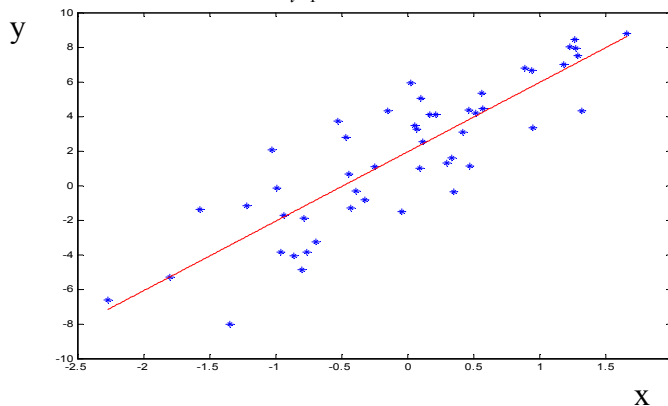
Average # of misclassified cases  $y_i \neq f(x_i)$

## Fitting the data to the model

- **Linear regression**

- Least squares fit with the linear model

- minimizes 
$$\frac{1}{n} \sum_{i=1}^n (y_i - f(x_i))^2$$



## Typical learning

### Three basic steps:

- **Select a model** or a set of models (with parameters)  
E.g.  $y = ax + b + \varepsilon$     $\varepsilon = N(0, \sigma)$
- **Select the error function** to be optimized  
E.g.  $\frac{1}{n} \sum_{i=1}^n (y_i - f(x_i))^2$
- **Find the set of parameters optimizing the error function**
  - The model and parameters with the smallest error represent the best fit of the model to the data

But there are problems one must be careful about ...

## Learning

### Problem

- We fit the model based on past experience (past examples seen)
- But ultimately we are interested in learning the mapping that performs well on the whole population of examples

**Training data:** Data used to fit the parameters of the model

**Training error:**  $\frac{1}{n} \sum_{i=1}^n (y_i - f(x_i))^2$

**True (generalization) error** (over the whole unknown population):

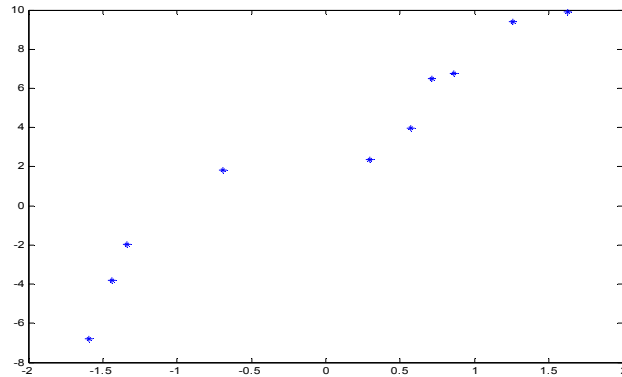
$$E_{(x,y)}(y - f(x))^2 \quad \text{Expected squared error}$$

**Training error tries to approximate the true error !!!!**

**Does a good training error imply a good generalization error?**

## Overfitting

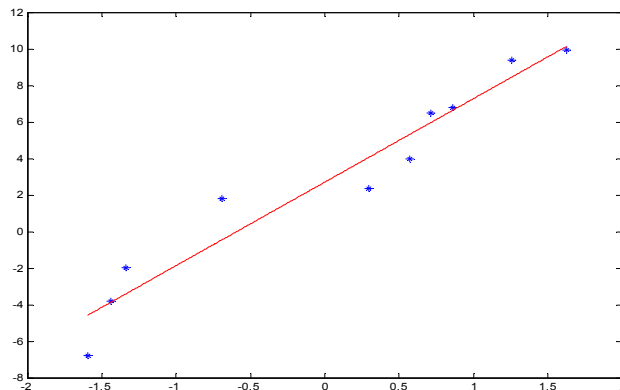
- Assume we have a set of 10 points and we consider polynomial functions as our possible models



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## Overfitting

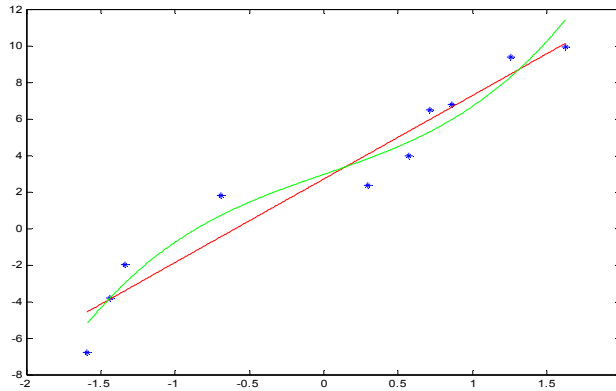
- Fitting a linear function with mean-squares error
- Error is nonzero



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## Overfitting

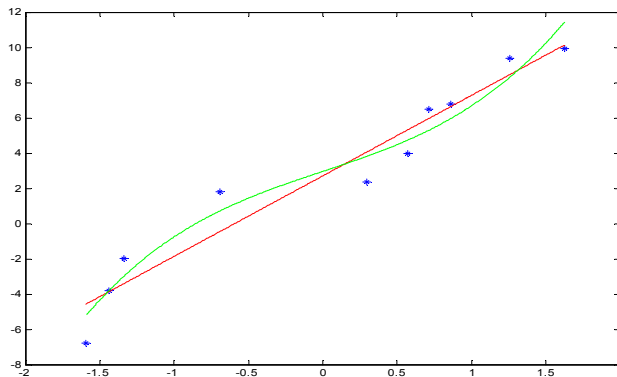
- Linear vs. cubic polynomial
- Higher order polynomial leads to a better fit, smaller error



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## Overfitting

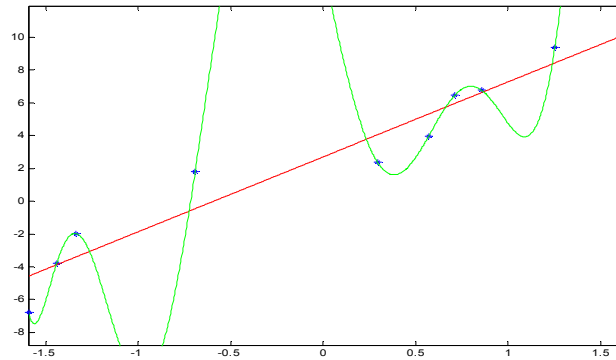
- Is it always good to minimize the error of the observed data?



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## Overfitting

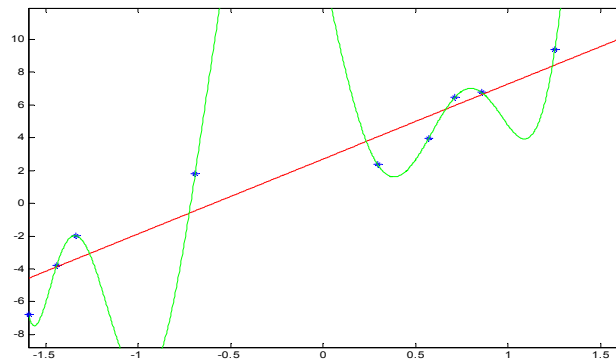
- For 10 data points, degree 9 polynomial gives a perfect fit (Lagrange interpolation). Error is zero.
- Is it always good to minimize the training error?



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## Overfitting

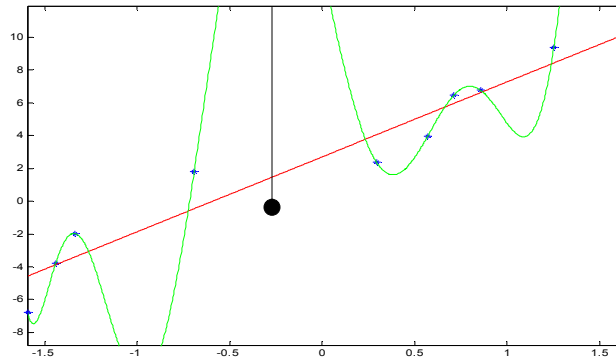
- For 10 data points, degree 9 polynomial gives a perfect fit (Lagrange interpolation). Error is zero.
- Is it always good to minimize the training error? **NO !!**
- More important: How do we perform on the unseen data?



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## Overfitting

- The situation when the training error is low and the generalization error is high. Causes of the phenomenon:
  - Model with more degrees of freedom (more parameters)
  - Small data size (as compared to the complexity of model)



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## How to evaluate the learner's performance?

- **Generalization error** is the true error for the population of examples we would like to optimize
$$E_{(x,y)}(y - f(x))^2$$
  - **But it cannot be computed exactly**
- **Optimizing (mean) training error** can lead to overfit, i.e. training error may not reflect properly the generalization error

$$\frac{1}{n} \sum_{i=1, \dots, n} (y_i - f(x_i))^2$$

- **So how to test the generalization error?**

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## How to evaluate the learner's performance?

- **Generalization error** is the true error for the population of examples we would like to optimize

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$$\frac{1}{n} \sum_{i=1,..,n} (y_i - f(x_i))^2$$

- **How to test the generalization error?**

**Answer:** Use a separate data set with  $m$  data samples to test it

- **(Mean) test error**  $\frac{1}{m} \sum_{j=1,..,m} (y_j - f(x_j))^2$

## Basic experimental setup to test the learner's performance

### 1. Take a dataset $D$ and divide it into:

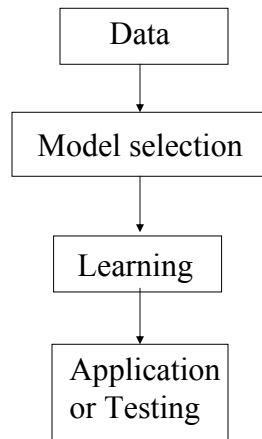
- Training data set
- Testing data set

### 2. Use the training set and your favorite ML algorithm to train the learner

### 3. Test (evaluate) the learner on the testing data set

- The results on the testing set can be used to compare different learners powered with different models and learning algorithms

## Design of a learning system



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## Design of a learning system.

**1. Data:**  $D = \{d_1, d_2, \dots, d_n\}$

**2. Model selection:**

- **Select a model** or a set of models (with parameters)

E.g.  $y = ax + b + \varepsilon$        $\varepsilon = N(0, \sigma)$

- **Select the error function** to be optimized

E.g.  $\frac{1}{n} \sum_{i=1}^n (y_i - f(x_i))^2$

**3. Learning:**

- **Find the set of parameters optimizing the error function**
  - The model and parameters with the smallest error

**4. Application:**

- **Apply the learned model**
  - E.g. predict  $y$ s for new inputs  $\mathbf{x}$  using learned  $f(\mathbf{x})$

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