

CS 1571 Introduction to AI

Lecture 23

Decision making in the presence of uncertainty

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Administration

- **Final exam**
 - **Monday, December 08, 2003 at 10:00-11:50am**
- **Problem set 9 is out:**
 - **Due on Thursday, November 20, 2003**

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Topics

- **Review of the decision tree model and its properties**
- **Modeling of exploratory action**
- **Utility theory**

Decision-making in the presence of uncertainty

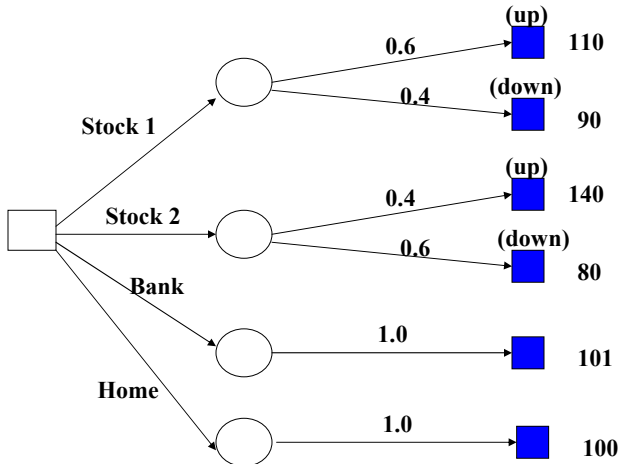
- Many real-world problems require **to choose future actions in the presence of uncertainty**
- **Examples:** patient management, investments

Main issues:

- **How to model the decision process in the computer ?**
- **How to make decisions about actions in the presence of uncertainty?**

Decision tree representation of the problem

Investing \$100 for 6 months



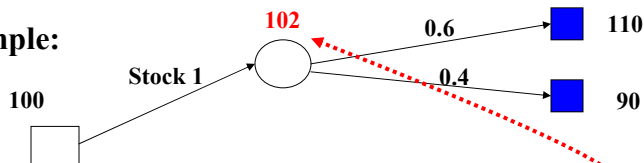
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Expected value

- Let X be a random variable representing the monetary outcome with a discrete set of values Ω_X .
- Expected value** of X is:

$$E(X) = \sum_{x \in \Omega_X} xP(X = x)$$

- Expected value** summarizes all stochastic outcomes into a single quantity
- Example:**



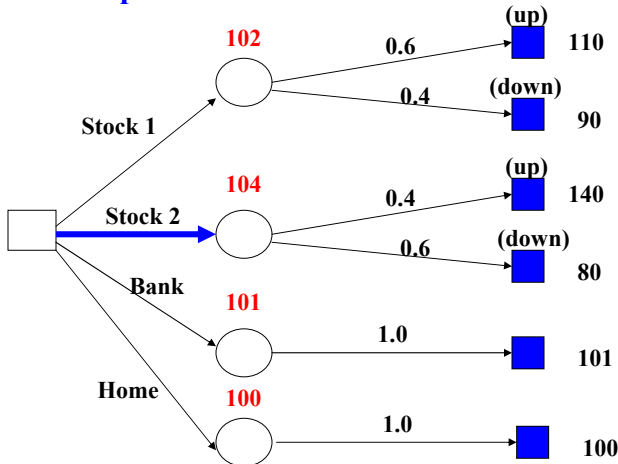
Expected value for the outcome of the Stock 1 option is:

$$0.6 \times 110 + 0.4 \times 90 = 66 + 36 = 102$$

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Selection based on expected values

The optimal action is the option that maximizes the expected outcome:



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Sequential (multi-stage) problems

The decision tree can be build to capture multi-stage decision problems:

1. Choose an action
2. Observe the stochastic outcome
3. And repeat step 1

How to make decisions for multi-step problems?

- Start from the leaves of the decision tree (outcome nodes)
- Compute expectations at chance nodes
- Maximize at the decision nodes

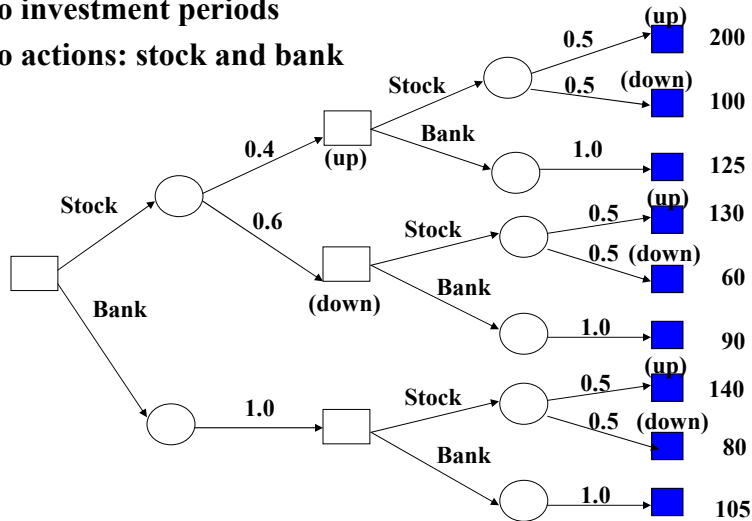
Algorithm is sometimes called **expectimax**

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Multi-stage decision problem

Assume:

- Two investment periods
- Two actions: stock and bank



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Properties of the decision tree model

• Probabilities:

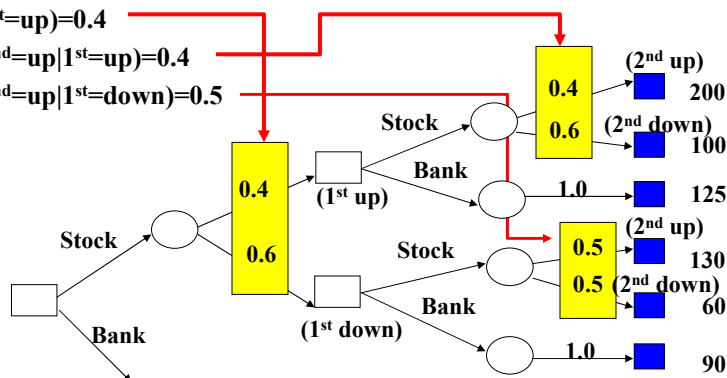
- Later outcomes can be conditioned on the earlier stochastic outcomes and actions

Example: stock movement probabilities. Assume:

$$P(1^{\text{st}}=\text{up})=0.4$$

$$P(2^{\text{nd}}=\text{up}|1^{\text{st}}=\text{up})=0.4$$

$$P(2^{\text{nd}}=\text{up}|1^{\text{st}}=\text{down})=0.5$$



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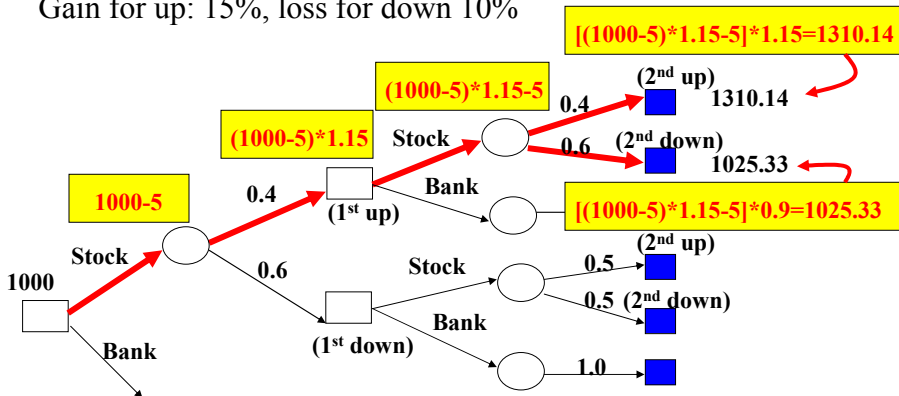
Properties of the decision tree model

- Outcome values at leaf nodes (e.g. monetary values)
 - Rewards and costs for the path trajectory

Example: stock fees and gains. **Assume:**

Fee per period: \$5 paid at the beginning

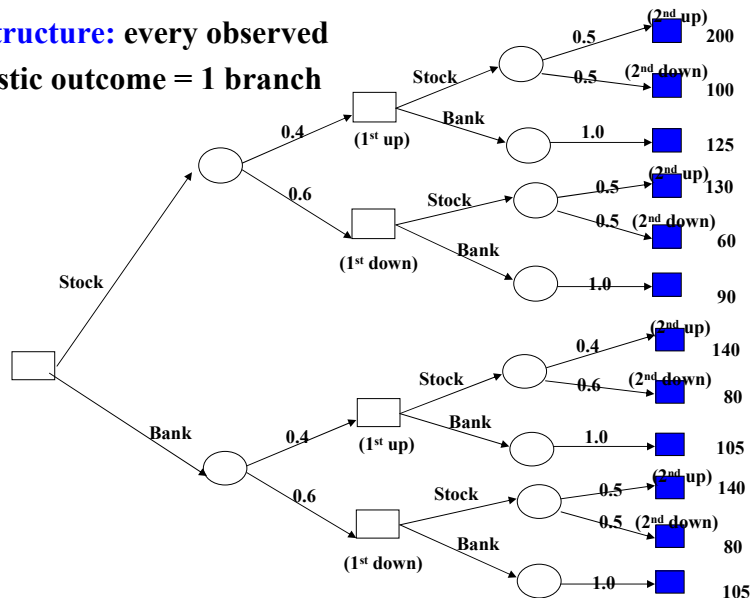
Gain for up: 15%, loss for down 10%



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Constructing the decision tree

Tree Structure: every observed stochastic outcome = 1 branch



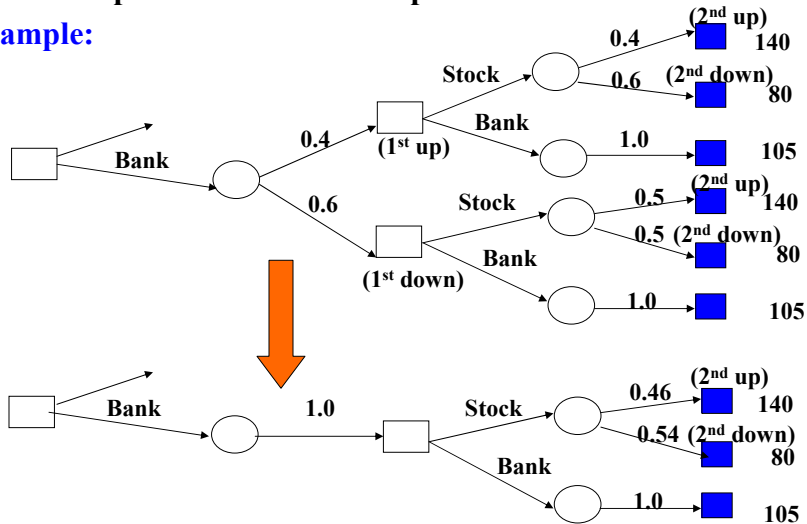
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Constructing the decision tree

- Structure

- Collapse of branches often possible

Example:

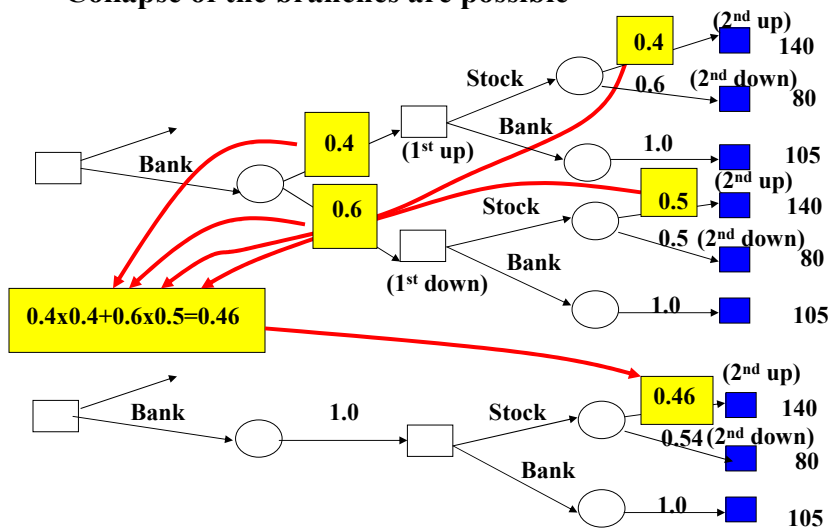


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Constructing the decision tree

- Structure

- Collapse of the branches are possible



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Information-gathering actions

- **Some actions and their outcomes irreversibly change the world**
- **Information-gathering (exploratory) actions:**
 - **make an inquiry about the world**
 - **Key benefit:** reduction in the uncertainty
- **Example: medicine**
 - Assume a patient is admitted to the hospital with some set of initial complaints
 - We are uncertain about the underlying problem and consider a surgery, or a medication to treat them
 - But there are often lab tests or observations that can help us to determine more closely the disease the patient suffers from
 - **Goal of lab tests:** Reduce the uncertainty of outcomes of treatments so that better treatment option can be chosen

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Decision-making with exploratory actions

In decision trees:

- **Exploratory actions can be represented and reasoned about the same way as other actions.**

How do we capture the effect of exploratory actions in the decision tree model?

- Information obtained through exploratory actions may affect the probabilities of later outcomes
 - Recall that the probabilities on later outcomes can be conditioned on past observed outcomes and past actions
 - Sequence of past actions and outcomes is “remembered” within the decision tree branch

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Oil wildcatter problem.

An oil wildcatter has to make a decision of whether to drill or not to drill on a specific site

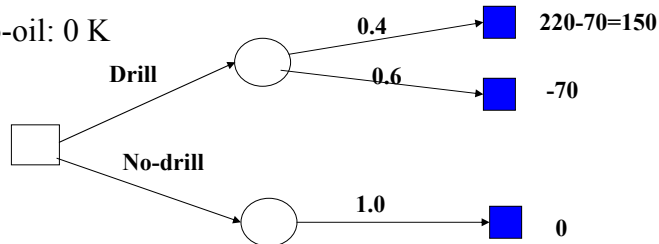
- **Chance of hitting an oil deposit:**

- Oil: 40% $P(Oil = T) = 0.4$
- No-oil: 60% $P(Oil = F) = 0.6$

- **Cost of drilling: 70K**

- **Payoffs:**

- Oil: 220K
- No-oil: 0 K



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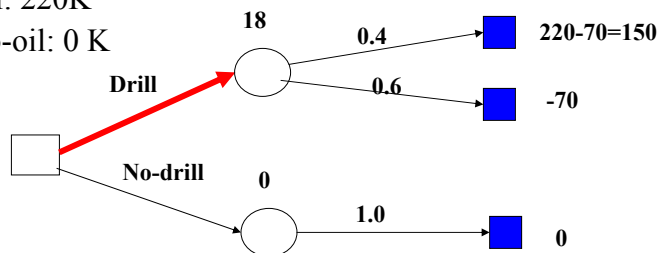
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Oil wildcatter problem

- Assume that in addition to the drill/no-drill choices we have an option to run the **seismic resonance test**
- Seismic resonance test results:**
 - Closed pattern** (more likely when the hole holds the oil)
 - Diffuse pattern** (more likely when empty)

$P(\text{Oil} \mid \text{Seismic resonance test})$

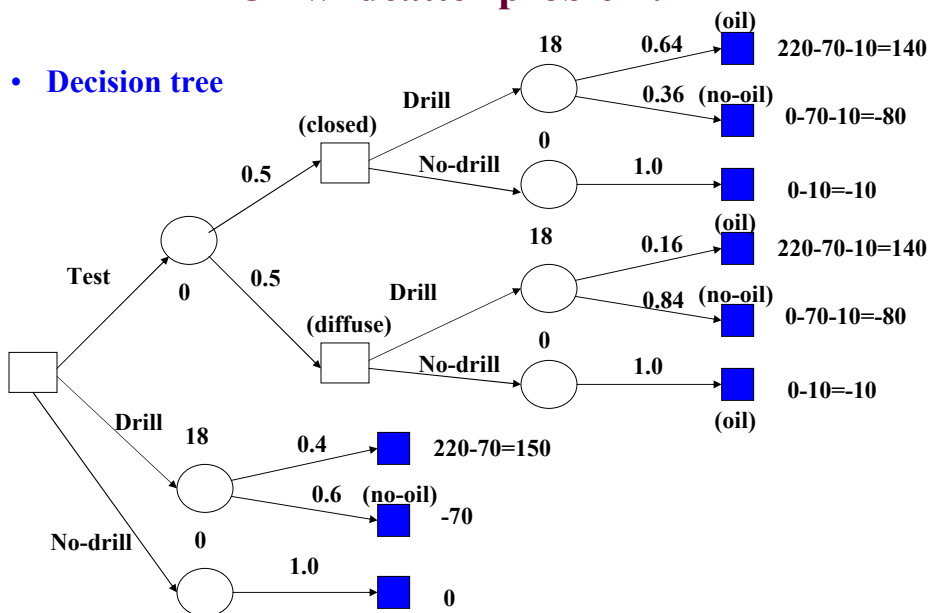
Seismic resonance test pattern

| Oil | <i>Seismic resonance test pattern</i> | |
|--------------|---------------------------------------|----------------|
| | <i>closed</i> | <i>diffuse</i> |
| <i>True</i> | 0.8 | 0.2 |
| <i>False</i> | 0.3 | 0.7 |

- Test cost:** 10K

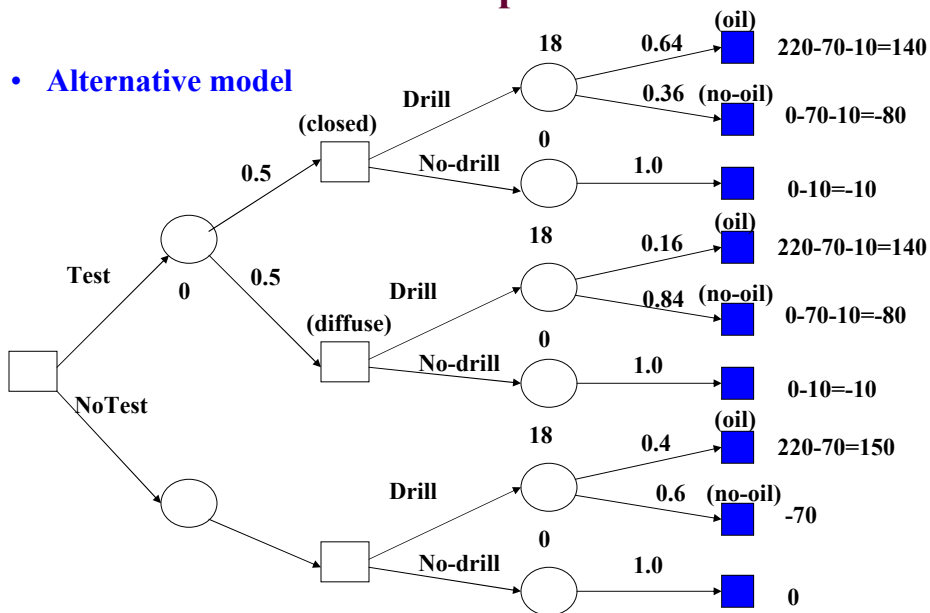
Oil wildcatter problem.

- Decision tree**



Oil wildcatter problem.

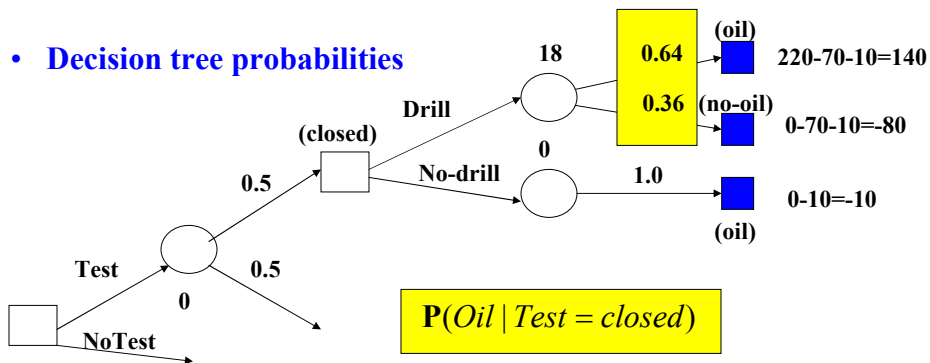
- Alternative model



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Oil wildcatter problem.

- Decision tree probabilities



$$P(Oil = T | Test = closed) = \frac{P(Test = closed | Oil = T)P(Oil = T)}{P(Test = closed)}$$

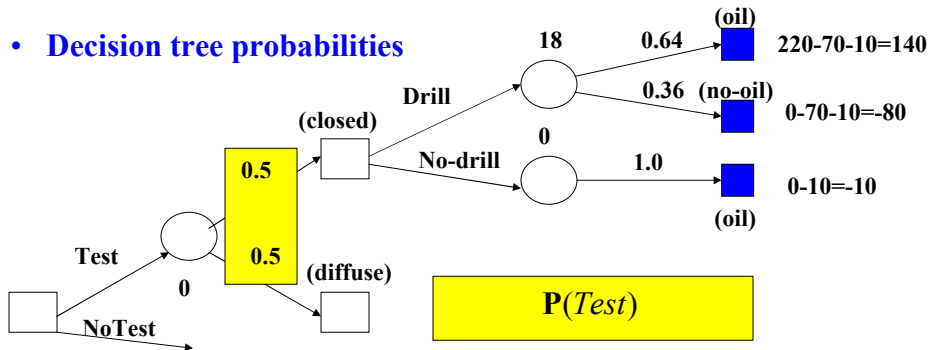
$$P(Oil = F | Test = closed) = \frac{P(Test = closed | Oil = F)P(Oil = F)}{P(T = closed)}$$

$$P(Test = closed) = P(Test = closed | Oil = F)P(Oil = F) + P(Test = closed | Oil = T)P(Oil = T)$$

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Oil wildcatter problem.

- Decision tree probabilities

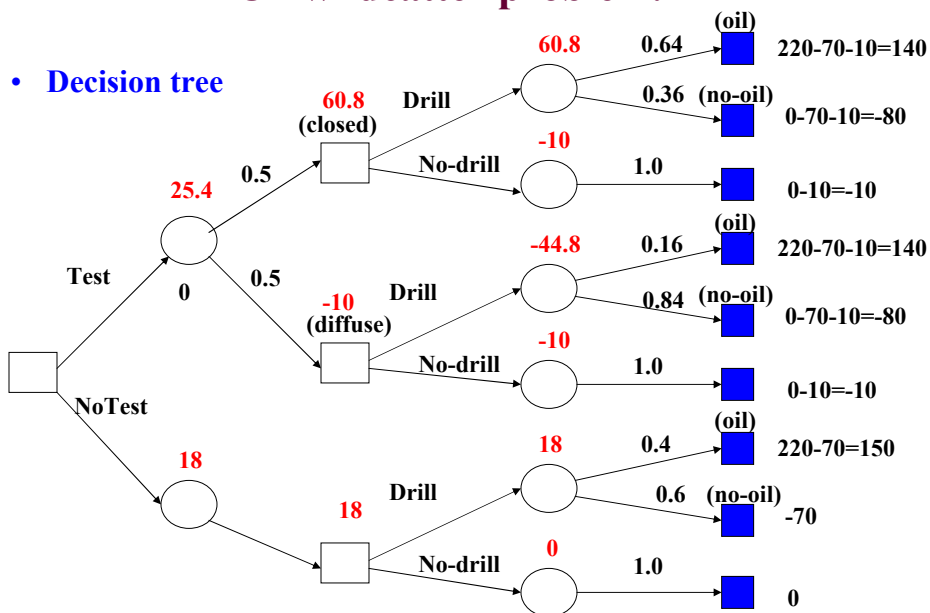


$$P(\text{Test} = \text{closed}) = P(\text{Test} = \text{closed} \mid \text{Oil} = F)P(\text{Oil} = F) + P(\text{Test} = \text{closed} \mid \text{Oil} = T)P(\text{Oil} = T)$$

$$P(\text{Test} = \text{diff}) = P(\text{Test} = \text{diff} \mid \text{Oil} = F)P(\text{Oil} = F) + P(\text{Test} = \text{diff} \mid \text{Oil} = T)P(\text{Oil} = T)$$

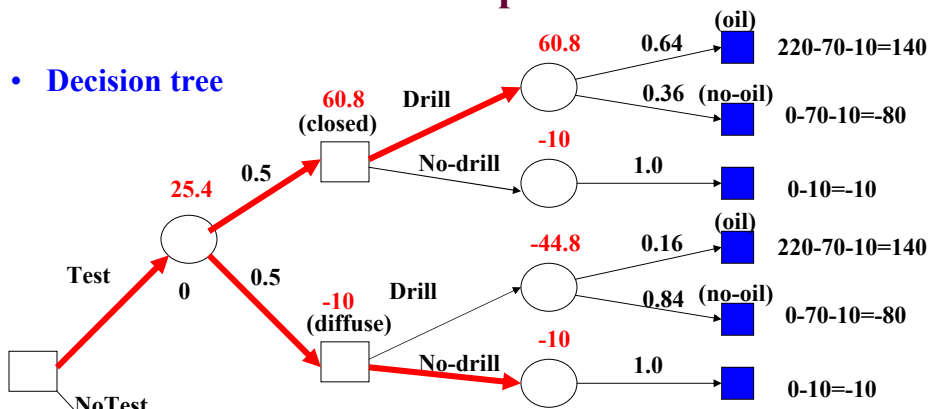
Oil wildcatter problem.

- Decision tree



Oil wildcatter problem.

- Decision tree



The presence of the test and its result affected our decision:

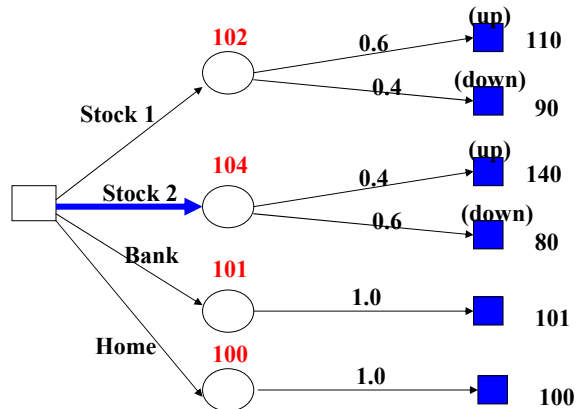
if test=closed then drill
if test=diffuse then do not drill

Value of information

- When the test makes sense?
 - Only when its result makes the decision maker to change his mind, that is he decides not to drill.
- Value of information:
 - Measure of the goodness of the information from the test
 - Difference between the expected value with and without the test information
- Oil wildcatter example:
 - Expected value without the test = 18
 - Expected value with the test = 25.4
 - Value of information for the seismic test = 7.4

Selection based on expected values

- **Until now:** The optimal action choice was the option that maximized the expected monetary value.
- **But is the expected monetary value always the quantity we want to optimize?**



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Selection based on expected values

- **Is the expected monetary value always the quantity we want to optimize?**
- **Answer:** Yes, but only if we are risk-neutral.
- But what if **we do not like the risk (we are risk-averse)?**
- In that case we may want to get the premium for undertaking the risk (of losing the money)
- **Example:**
 - we may prefer to get \$101 for sure against \$102 in expectation but with the risk of losing the money
- **Problem:** How to model decisions and account for the risk?
- **Solution:** use **utility function, and utility theory**

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Utility function

- **Utility function (denoted U)**
 - Quantifies how we “value” outcomes, i.e., it reflects our preferences
 - Can be also applied to “value” outcomes other than money and gains (e.g. utility of a patient being healthy, or ill)
- **Decision making:**
 - uses expected utilities (denoted EU)

$$EU(X) = \sum_{x \in \Omega_X} P(X = x)U(X = x)$$

$U(X = x)$ the utility of outcome x

Important !!!

- Under some conditions on preferences **we can always design the utility function that fits our preferences**

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Utility theory

- Defines axioms on preferences that involve uncertainty and ways to manipulate them.
- Uncertainty is modeled through **lotteries**
 - **Lottery:**
$$[p : A; (1 - p) : C]$$
 - Outcome A with probability p
 - Outcome C with probability (1-p)
- The following six constraints are known as the axioms of utility theory. The axioms are the most obvious semantic constraints on preferences with lotteries.
- **Notation:**
 - \succ - preferable
 - \sim - indifferent (equally preferable)

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Axioms of the utility theory

- **Orderability:** Given any two states, the a rational agent prefers one of them, else the two as equally preferable.

$$(A \succ B) \vee (B \succ A) \vee (A \sim B)$$
- **Transitivity:** Given any three states, if an agent prefers A to B and prefers B to C , agent must prefer A to C .

$$(A \succ B) \wedge (B \succ C) \Rightarrow (A \succ C)$$
- **Continuity:** If some state B is between A and C in preference, then there is a p for which the rational agent will be indifferent between state B and the lottery in which A comes with probability p , C with probability $(1-p)$.

$$(A \succ B \succ C) \Rightarrow \exists p [p : A; (1 - p) : C] \sim B$$

Axioms of the utility theory

- **Substitutability:** If an agent is indifferent between two lotteries, A and B , then there is a more complex lottery in which A can be substituted with B .

$$(A \sim B) \Rightarrow [p : A; (1 - p) : C] \sim [p : B; (1 - p) : C]$$
- **Monotonicity:** If an agent prefers A to B , then the agent must prefer the lottery in which A occurs with a higher probability

$$(A \succ B) \Rightarrow (p > q \Leftrightarrow [p : A; (1 - p) : B] \succ [q : A; (1 - q) : B])$$
- **Decomposability:** Compound lotteries can be reduced to simpler lotteries using the laws of probability.

$$[p : A; (1 - p) : [q : B; (1 - q) : C]] \Rightarrow [p : A; (1 - p)q : B; (1 - p)(1 - q) : C]$$

Utility theory

If the agent obeys the axioms of the utility theory, then

1. there exists a real valued function U such that:

$$U(A) > U(B) \Leftrightarrow A \succ B$$

$$U(A) = U(B) \Leftrightarrow A \sim B$$

2. The utility of the lottery is the expected utility, that is the sum of utilities of outcomes weighted by their probability

$$U[p : A; (1 - p) : B] = pU(A) + (1 - p)U(B)$$

3. Rational agent makes the decisions in the presence of uncertainty by maximizing its expected utility

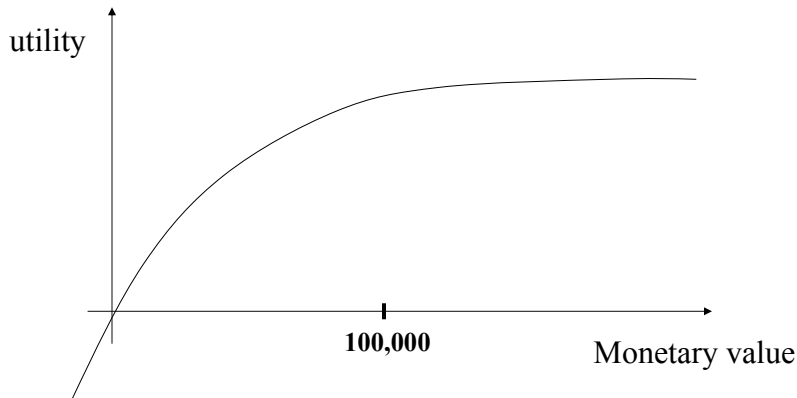
Utility functions

We can design a utility function that fits our preferences if they satisfy the axioms of utility theory.

- **But how to design the utility function for monetary values so that they incorporate the risk?**
- **What is the relations between utility function and monetary values?**
- Assume we loose or gain \$1000.
 - Typically this difference is more significant for lower values (around \$100 -1000) than for higher values (~ \$1,000,000)
- What is the relation between utilities and monetary value for a typical person?

Utility functions

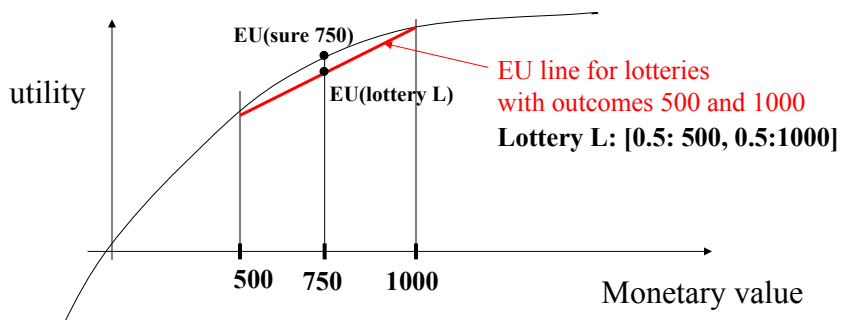
- What is the relation between utilities and monetary value for a typical person?
- Concave function that flattens at higher monetary values



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Utility functions

- Risk aversion comes from the shape of the concave function



Assume a lottery L [0.5: 500, 0.5:1000]

- Expected value of the lottery = 750
- Expected utility of the lottery $EU(\text{lottery L}) < EU(\text{sure 750})$
- Risk averse – a bonus is required for undertaking the risk

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