

CS 1571 Introduction to AI

Lecture 17

Bayesian belief networks

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Uncertainty

- Is an essential feature of many real-world problems
- Relations between components, states of the world are often uncertain

Examples:

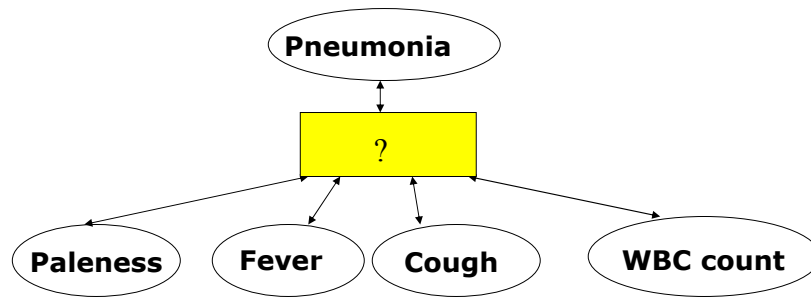
- Medical diagnosis
 - A patient suffering from pneumonia may not have fever all the times, may or may not have a cough, white blood cell test can be in a normal range.
 - High fever is typical for many diseases (e.g. bacterial diseases) and does not point specifically to pneumonia
- Therapy planning
 - A response of a patient to a therapy is not deterministic, the patient's state can improve, stay the same, or worsen

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Modeling the uncertainty.

Key issues:

- How to describe, represent the relations in the presence of uncertainty?
- How to manipulate such knowledge to make inferences?
 - **Humans can reason with uncertainty.**



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Probability theory

a well-defined coherent theory for representing uncertainty and for reasoning with it

Representation:

Propositional statements – assignment of values to random variables

Pneumonia = True WBCcount = high

Probabilities over statements model the degree of belief in these statements

$P(\text{Pneumonia} = \text{True}) = 0.001$

$P(\text{WBCcount} = \text{high}) = 0.005$

$P(\text{Pneumonia} \neq \text{True}, \text{Fever} = \text{True}) = 0.0009$

$P(\text{Pneumonia} = \text{False}, \text{WBCcount} = \text{normal}, \text{Cough} = \text{False}) = 0.97$

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Joint probability distribution

Joint probability distribution (for a set variables)

- Defines probabilities for all possible assignments of values to variables in the set

$P(\text{pneumonia}, \text{WBCcount})$ 2×3 table

		WBCcount			
		high	normal	low	$P(\text{Pneumonia})$
Pneumonia	True	0.0008	0.0001	0.0001	0.001
	False	0.0042	0.9929	0.0019	0.999
		0.005	0.993	0.002	

$P(\text{WBCcount})$

Marginalization - summing out variables

Variable independence

- The joint distribution over a subset of variables can be always computed from the joint distribution through marginalization
- Not the other way around !!!
 - Only exception:** when variables are independent

$$P(A, B) = P(A)P(B)$$

$P(\text{pneumonia}, \text{WBCcount})$		WBCcount			$P(\text{Pneumonia})$
		high	normal	low	
Pneumonia	True	0.0008	0.0001	0.0001	0.001
	False	0.0042	0.9929	0.0019	0.999
		0.005	0.993	0.002	

$P(\text{WBCcount})$

Conditional probability

Conditional probability :

- Probability of A given B

$$P(A | B) = \frac{P(A, B)}{P(B)}$$

- Conditional probability is defined in terms of joint probabilities
- Joint probabilities can be expressed in terms of conditional probabilities

$$P(A, B) = P(A | B)P(B) \quad \text{(product rule)}$$

$$P(X_1, X_2, \dots, X_n) = \prod_{i=1}^n P(X_i | X_1, \dots, X_{i-1}) \quad \text{(chain rule)}$$

- Conditional probability – is useful for **various probabilistic inferences**

$$P(\text{Pneumonia} = \text{True} | \text{Fever} = \text{True}, \text{WBCcount} = \text{high}, \text{Cough} = \text{True})$$

Bayes rule

Conditional probability.

$$P(A | B) = \frac{P(A, B)}{P(B)} \quad \text{---} \quad P(A, B) = P(B | A)P(A)$$

Bayes rule:

$$P(A | B) = \frac{P(B | A)P(A)}{P(B)}$$

When is it useful?

- When we are interested in computing the diagnostic probability, from the causal probability

$$P(\text{cause} | \text{effect}) = \frac{P(\text{effect} | \text{cause})P(\text{cause})}{P(\text{effect})}$$

- **Reason:** It is often easier to assess causal probability
 - E.g. Probability of pneumonia causing fever
vs. probability of pneumonia given fever

Probabilistic inference

Various inference tasks:

- **Diagnostic task. (from effect to cause)**

$$P(Pneumonia \mid Fever = T)$$

- **Prediction task. (from cause to effect)**

$$P(Fever \mid Pneumonia = T)$$

- **Other probabilistic queries** (queries on joint distributions).

$$P(Fever)$$

$$P(Fever, ChestPain)$$

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Inference

Any query can be computed from the full joint distribution !!!

- **Joint over a subset of variables** is obtained through marginalization

$$P(A = a, C = c) = \sum_i \sum_j P(A = a, B = b_i, C = c, D = d_j)$$

- **Conditional probability over set of variables**, given other variables' values is obtained through marginalization and definition of conditionals

$$\begin{aligned} P(D = d \mid A = a, C = c) &= \frac{P(A = a, C = c, D = d)}{P(A = a, C = c)} \\ &= \frac{\sum_i P(A = a, B = b_i, C = c, D = d)}{\sum_i \sum_j P(A = a, B = b_i, C = c, D = d_j)} \end{aligned}$$

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Inference.

Any query can be computed from the full joint distribution !!!

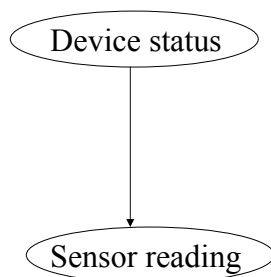
- Any joint probability can be expressed as a product of conditionals via the **chain rule**.

$$\begin{aligned}P(X_1, X_2, \dots, X_n) &= P(X_n | X_1, \dots, X_{n-1})P(X_1, \dots, X_{n-1}) \\&= P(X_n | X_1, \dots, X_{n-1})P(X_{n-1} | X_1, \dots, X_{n-2})P(X_1, \dots, X_{n-2}) \\&= \prod_{i=1}^n P(X_i | X_1, \dots, X_{i-1})\end{aligned}$$

- It is often easier to define the distribution in terms of conditional probabilities:
 - E.g. $\mathbf{P}(\text{Fever} | \text{Pneumonia} = T)$
 $\mathbf{P}(\text{Fever} | \text{Pneumonia} = F)$

Simple diagnostic inference. Example.

- Device** (equipment) operating *normally* or *malfunctioning*.
 - Operation of the device sensed indirectly via a sensor
- Sensor reading** is either *high* or *low*



P(Device status)

normal	malfunctioning
0.9	0.1

P(Sensor reading | Device status)

Device\Sensor	high	low
normal	0.1	0.9
malfunctioning	0.6	0.4

Diagnostic inference. Example.

- **Diagnostic inference:** compute the probability of device operating normally or malfunctioning given a sensor reading

$$P(\text{Device status} \mid \text{Sensor reading} = \textit{high}) = ?$$

$$= \begin{pmatrix} P(\text{Device status} = \textit{normal} \mid \text{Sensor reading} = \textit{high}) \\ P(\text{Device status} = \textit{malfunctioning} \mid \text{Sensor reading} = \textit{high}) \end{pmatrix}$$

- Note that the opposite conditional probabilities are available
- **Solution:** apply **Bayes rule** to reverse the conditioning variables

Modeling uncertainty with probabilities

- Defining the full joint distribution makes it possible to represent and reason with uncertainty in a uniform way
- We are able to handle an arbitrary inference problem

Problems:

- **Space complexity.** To store a full joint distribution we need to remember $O(d^n)$ numbers.
 n – number of random variables, d – number of values
- **Inference (time) complexity.** To compute some queries requires $O(d^n)$ steps.
- **Acquisition problem.** Who is going to define all of the probability entries?

Medical diagnosis example.

- **Space complexity.**

- Pneumonia (2 values: T,F), Fever (2: T,F), Cough (2: T,F), WBCcount (3: high, normal, low), paleness (2: T,F)
- Number of assignments: $2*2*2*3*2=48$
- We need to define at least 47 probabilities.

- **Time complexity.**

- Assume we need to compute the marginal of $P(\text{Pneumonia}=T)$ from the full joint distribution

$$\begin{aligned} P(\text{Pneumonia}=T) &= \\ &= \sum_{i \in T, F} \sum_{j \in T, F} \sum_{k=h,n,l} \sum_{u \in T, F} P(\text{Pneumonia}=T, \text{Fever}=i, \text{Cough}=j, \text{WBCcount}=k, \text{Pale}=u) \end{aligned}$$

- Sum over: $2*2*3*2=24$ combinations

Modeling uncertainty with probabilities

- **Knowledge based system era (70s – early 80's)**

- **Extensional non-probabilistic models**
- Solve the space, time and acquisition bottlenecks in probability-based models
- froze the development and advancement of KB systems and contributed to the slow-down of AI in 80s in general

- Breakthrough (late 80s, beginning of 90s)

- **Bayesian belief networks**

- Give solutions to the space, acquisition bottlenecks
- Partial solutions for time complexities
- Bayesian belief network

Bayesian belief networks (BBNs)

Bayesian belief networks.

- Represent the full joint distribution over the variables more compactly with a **smaller number of parameters**.
- Take advantage of **conditional and marginal independences** among random variables

- **A and B are independent**

$$P(A, B) = P(A)P(B)$$

- **A and B are conditionally independent given C**

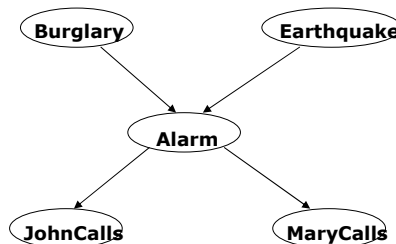
$$P(A, B | C) = P(A | C)P(B | C)$$

$$P(A | C, B) = P(A | C)$$

Alarm system example.

- Assume your house has an **alarm system** against **burglary**. You live in the seismically active area and the alarm system can get occasionally set off by an **earthquake**. You have two neighbors, **Mary** and **John**, who do not know each other. If they hear the alarm they call you, but this is not guaranteed.
- We want to represent the probability distribution of events:
 - Burglary, Earthquake, Alarm, Mary calls and John calls

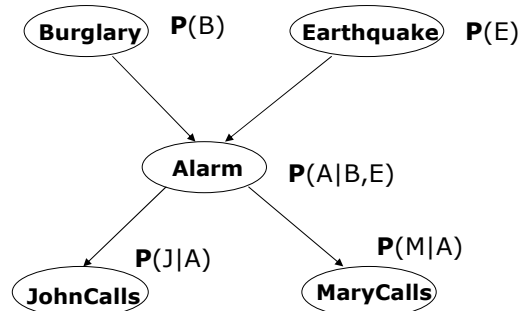
Causal relations



Bayesian belief network.

1. Directed acyclic graph

- **Nodes** = random variables
Burglary, Earthquake, Alarm, Mary calls and John calls
- **Links** = direct (causal) dependencies between variables.
The chance of Alarm being is influenced by Earthquake,
The chance of John calling is affected by the Alarm

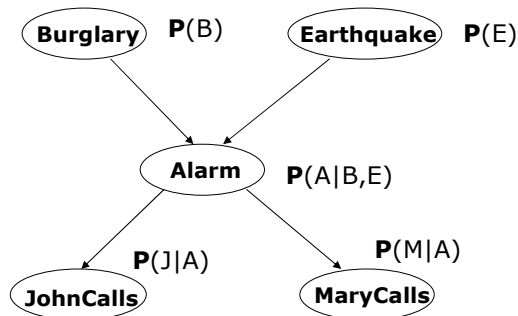


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Bayesian belief network.

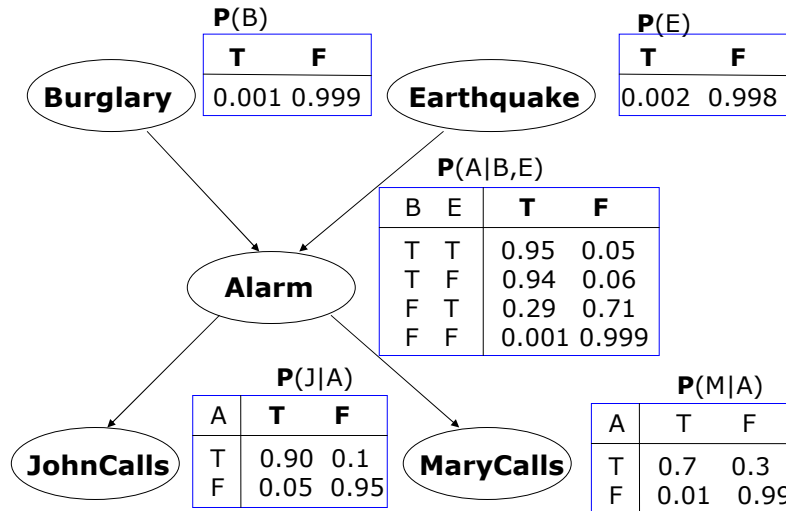
2. Local conditional distributions

- relate variables and their parents



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Bayesian belief network.



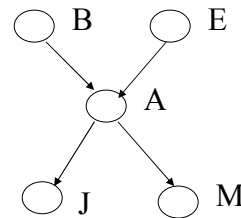
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Bayesian belief networks (general)

Two components: $B = (S, \Theta_S)$

- **Directed acyclic graph**

- Nodes correspond to random variables
- (Missing) links encode independences



- **Parameters**

- Local conditional probability distributions for every variable-parent configuration

$$P(X_i | pa(X_i))$$

Where:

$pa(X_i)$ - stand for parents of X_i

P(A|B,E)

B	E	T	F
T	T	0.95	0.05
T	F	0.94	0.06
F	T	0.29	0.71
F	F	0.001	0.999

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Full joint distribution in BBNs

Full joint distribution is defined in terms of local conditional distributions (obtained via the chain rule):

$$\mathbf{P}(X_1, X_2, \dots, X_n) = \prod_{i=1, \dots, n} \mathbf{P}(X_i \mid pa(X_i))$$

Example:

Assume the following assignment of values to random variables

$$B=T, E=T, A=T, J=T, M=F$$

Then its probability is:

$$P(B=T, E=T, A=T, J=T, M=F) =$$

$$P(B=T)P(E=T)P(A=T \mid B=T, E=T)P(J=T \mid A=T)P(M=F \mid A=T)$$

