CS 2770: Computer Vision Vision, Language, Reasoning

Prof. Adriana Kovashka University of Pittsburgh March 31, 2020

Plan for this lecture

- Learning the relation between images and text
 - Recurrent neural networks
 - Applications: Captioning
 - Transformers
- Visual question answering
 - Graph convolutional networks
 - Incorporating knowledge and reasoning

Motivation: Descriptive Text for Images



"It was an arresting face, pointed of chin, square of jaw. Her eyes were pale green without a touch of hazel, starred with bristly black lashes and slightly tilted at the ends. Above them, her thick black brows slanted upward, cutting a startling oblique line in her magnoliawhite skin–that skin so prized by Southern women and so carefully guarded with bonnets, veils and mittens against hot Georgia suns"

Scarlett O'Hara described in Gone with the Wind

Some pre-RNN good results



This is a picture of one sky, one road and one sheep. The gray sky is over the gray road. The gray sheep is by the gray road.



This is a picture of two dogs. The first dog is near the second furry dog.



Here we see one road, one sky and one bicycle. The road is near the blue sky, and near the colorful bicycle. The colorful bicycle is within the blue sky.

Some pre-RNN bad results

Missed detections:



Here we see one potted plant.

False detections:



There are one road and one cat. The furry road is in the furry cat.



This is a picture of one dog.



This is a picture of one tree, one road and one person. The rusty tree is under the red road. The colorful person is near the rusty tree, and under the red road.

Incorrect attributes:



This is a photograph of two sheeps and one grass. The first black sheep is by the green grass, and by the second black sheep. The second black sheep is by the green grass.



This is a photograph of two horses and one grass. The first feathered horse is within the green grass, and by the second feathered horse. The second feathered horse is within the green grass.

Results with Recurrent Neural Networks



"man in black shirt is playing guitar."



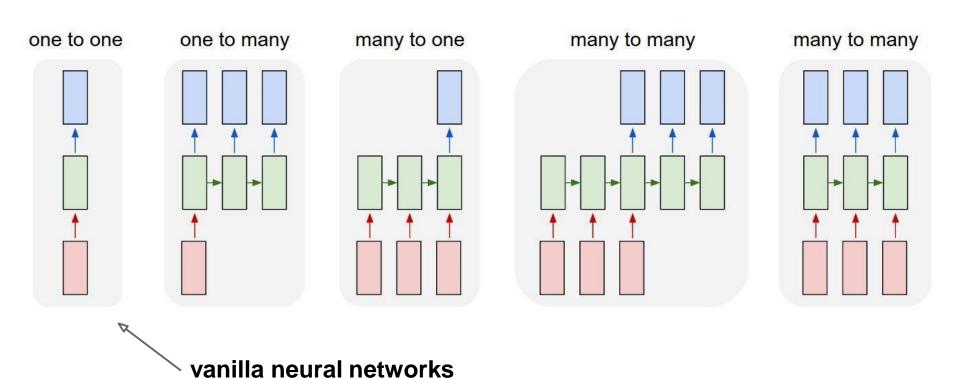
"construction worker in orange safety vest is working on road."

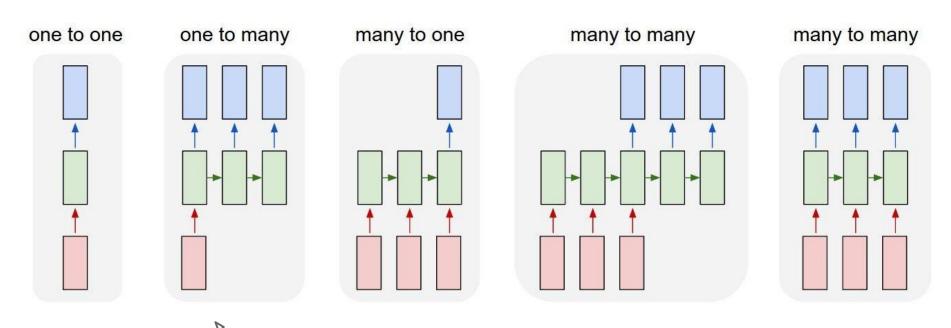


"two young girls are playing with lego toy."



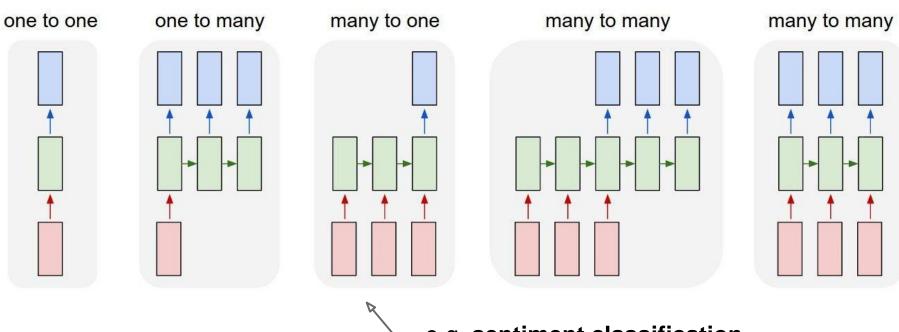
"boy is doing backflip on wakeboard."



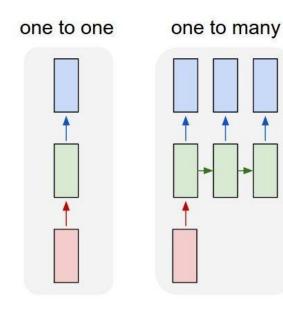


e.g. image captioning image -> sequence of words

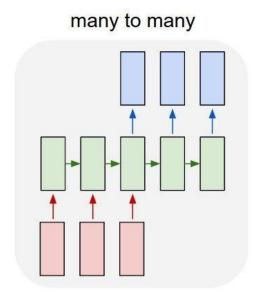
Andrej Karpathy



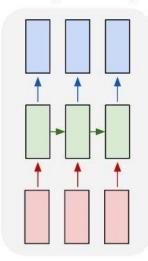
e.g. **sentiment classification** sequence of words -> sentiment



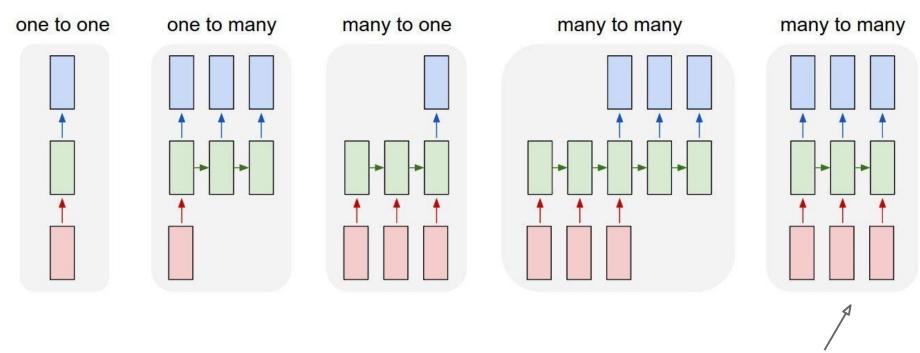
many to one



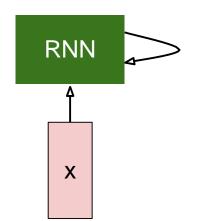
many to many



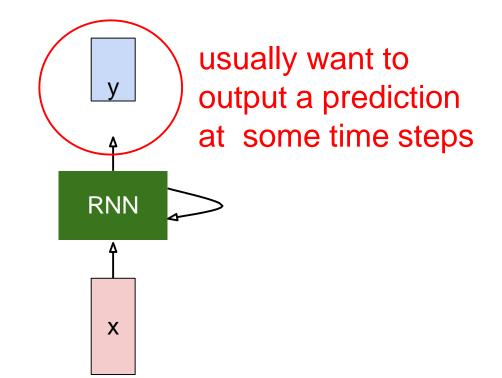
e.g. **machine translation** seq of words -> seq of words

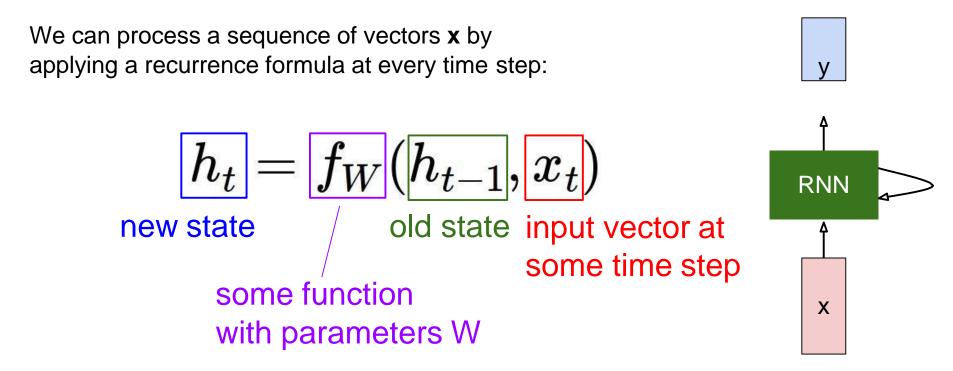


e.g. video classification on frame level



Andrej Karpathy

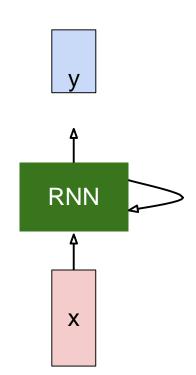




We can process a sequence of vectors \mathbf{x} by applying a recurrence formula at every time step:

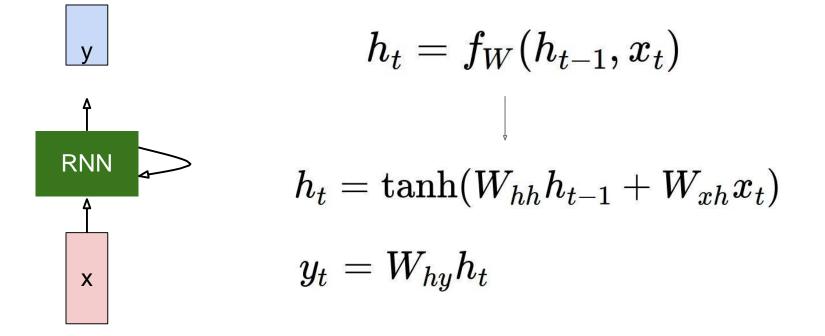
$$h_t = f_W(h_{t-1}, x_t)$$

Notice: the same function and the same set of parameters are used at every time step.



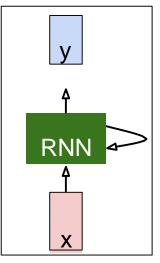
(Vanilla) Recurrent Neural Network

The state consists of a single "hidden" vector h:



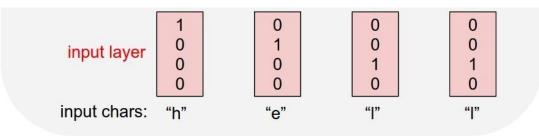
Character-level language model example

Vocabulary: [h,e,l,o]



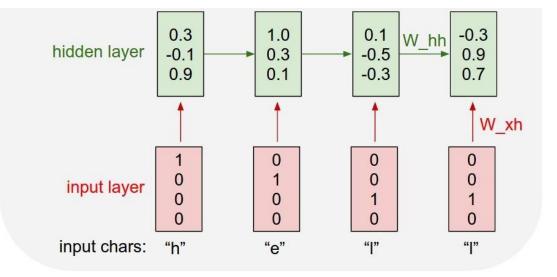
Character-level language model example

Vocabulary: [h,e,l,o]



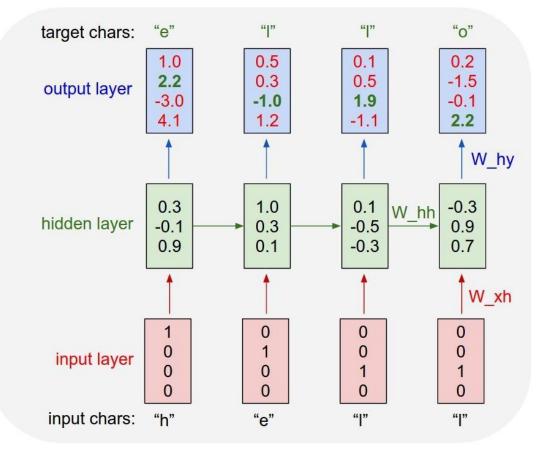
Character-level language model example

$$h_t = anh(W_{hh}h_{t-1} + W_{xh}x_t)$$



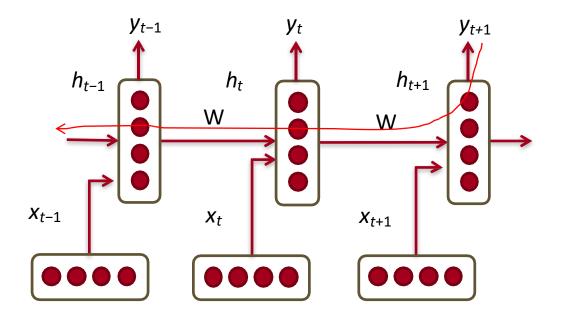
Character-level language model example

Vocabulary: [h,e,l,o]



The vanishing gradient problem

- The error at a time step ideally can tell a previous time step from many steps away to change during backprop
- But we're multiplying together many values between 0 and 1



The vanishing gradient problem

• Total error is the sum of each error at time steps t

$$\frac{\partial E}{\partial W} = \sum_{t=1}^{T} \frac{\partial E_t}{\partial W}$$

• Chain rule:

$$\frac{\partial E_t}{\partial W} = \sum_{k=1}^t \frac{\partial E_t}{\partial y_t} \frac{\partial y_t}{\partial h_t} \frac{\partial h_t}{\partial h_k} \frac{\partial h_k}{\partial W}$$

• More chain rule:

$$\frac{\partial h_t}{\partial h_k} = \prod_{j=k+1}^t \frac{\partial h_j}{\partial h_{j-1}}$$

 Derivative of vector wrt vector is a Jacobian matrix of partial derivatives; norm of this matrix can become very small or very large quickly [Bengio et al 1994, Pascanu et al 2013], leading to vanishing/exploding gradient

The vanishing gradient problem for language models

- In the case of language modeling or question answering words from time steps far away are not taken into consideration when training to predict the next word
- Example:

Jane walked into the room. John walked in too. It was late in the day. Jane said hi to _____

- More complex hidden unit computation in recurrence!
- Introduced by Cho et al. 2014
- Main ideas:
 - keep around memories to capture long distance dependencies
 - allow error messages to flow at different strengths depending on the inputs

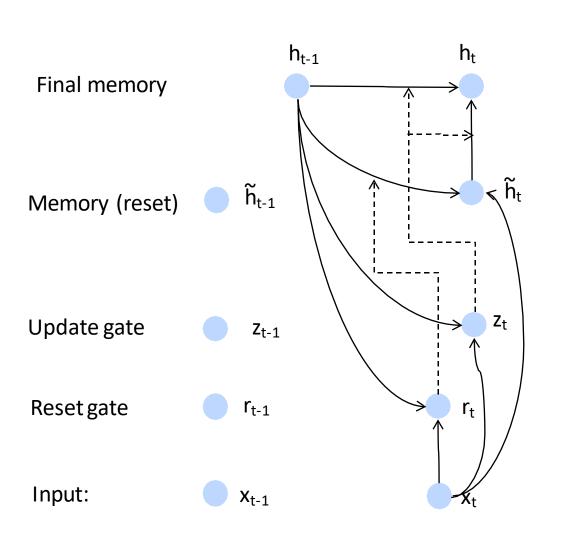
- Standard RNN computes hidden layer at next time step directly: $h_t = f\left(W^{(hh)}h_{t-1} + W^{(hx)}x_t\right)$
- GRU first computes an update gate (another layer) based on current input word vector and hidden state

$$z_t = \sigma \left(W^{(z)} x_t + U^{(z)} h_{t-1} \right)$$

Compute reset gate similarly but with different weights

$$r_t = \sigma \left(W^{(r)} x_t + U^{(r)} h_{t-1} \right)$$

- Update gate $z_t = \sigma \left(W^{(z)} x_t + U^{(z)} h_{t-1} \right)$
- Reset gate $r_t = \sigma \left(W^{(r)} x_t + U^{(r)} h_{t-1} \right)$
- New memory content: $\tilde{h}_t = \tanh(Wx_t + r_t \circ Uh_{t-1})$ If reset gate unit is ~0, then this ignores previous memory and only stores the new word information
- Final memory at time step combines current and previous time steps: $h_t = z_t \circ h_{t-1} + (1 - z_t) \circ \tilde{h}_t$



$$z_t = \sigma \left(W^{(z)} x_t + U^{(z)} h_{t-1} \right)$$
$$r_t = \sigma \left(W^{(r)} x_t + U^{(r)} h_{t-1} \right)$$
$$\tilde{h}_t = \tanh \left(W x_t + r_t \circ U h_{t-1} \right)$$
$$h_t = z_t \circ h_{t-1} + (1 - z_t) \circ \tilde{h}_t$$

Richard Socher

 If reset is close to 0, ignore previous hidden state: Allows model to drop information that is irrelevant in the future

$$z_t = \sigma \left(W^{(z)} x_t + U^{(z)} h_{t-1} \right)$$
$$r_t = \sigma \left(W^{(r)} x_t + U^{(r)} h_{t-1} \right)$$
$$\tilde{h}_t = \tanh \left(W x_t + r_t \circ U h_{t-1} \right)$$
$$h_t = z_t \circ h_{t-1} + (1 - z_t) \circ \tilde{h}_t$$

- Update gate z controls how much of past state should matter now
 - If z close to 1, then we can copy information in that unit through many time steps! Less vanishing gradient!
- Units with short-term dependencies often have reset gates (r) very active; ones with long-term dependencies have active update gates (z)

Long-short-term-memories (LSTMs)

- Proposed by Hochreiter and Schmidhuber in 1997
- We can make the units even more complex
- Allow each time step to modify
 - Input gate (current cell matters)
 - Forget (gate 0, forget past)
 - Output (how much cell is exposed) $o_t = \sigma \left(W^{(o)} x_t + U^{(o)} h_{t-1} \right)$
 - New memory cell
- Final memory cell:
- Final hidden state:

$$c_t = f_t \circ c_{t-1} + i_t \circ \tilde{c}_t$$

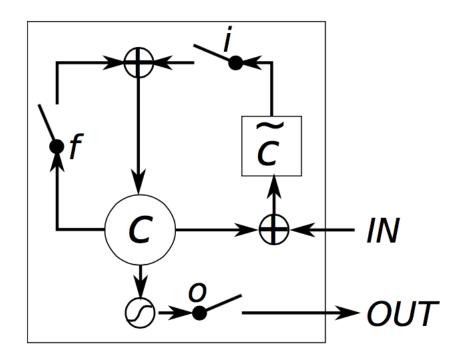
 $i_t = \sigma \left(W^{(i)} x_t + U^{(i)} h_{t-1} \right)$

 $f_t = \sigma \left(W^{(f)} x_t + U^{(f)} h_{t-1} \right)$

 $\tilde{c}_t = \tanh\left(W^{(c)}x_t + U^{(c)}h_{t-1}\right)$

$$h_t = o_t \circ \tanh(c_t)$$

Long-short-term-memories (LSTMs)



Intuition: memory cells can keep information intact, unless inputs makes them forget it or overwrite it with new input

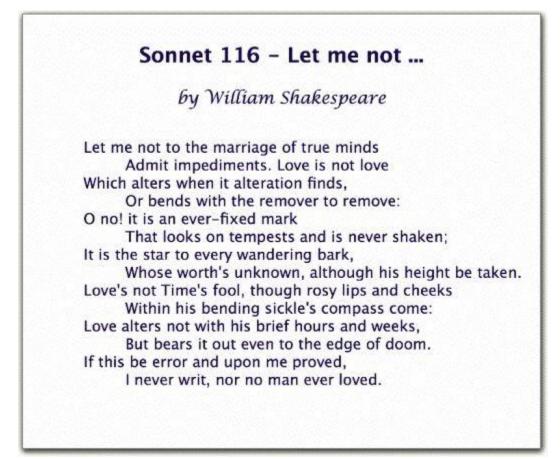
Cell can decide to output this information or just store it

Richard Socher, figure from wildml.com

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Generating poetry with RNNs



Generating poetry with RNNs

tyntd-iafhatawiaoihrdemot lytdws e ,tfti, astai f ogoh eoase rrranbyne 'nhthnee e plia tklrgd t o idoe ns,smtt h ne etie h,hregtrs nigtike,aoaenns lng				
train more				
"Tmont thithey" fomesscerliund Keushey. Thom here sheulke, anmerenith ol sivh I lalterthend Bleipile shuwy fil on aseterlome coaniogennc Phe lism thond hon at. MeiDimorotion in ther thize."				
train more				
Aftair fall unsuch that the hall for Prince Velzonski's that me of her hearly, and behs to so arwage fiving were to it beloge, pavu say falling misfort how, and Gogition is so overelical and ofter.				
train more				
"Why do what that day," replied Natasha, and wishing to himself the fact the princess, Princess Mary was easier, fed in had oftened him. Pierre aking his soul came to the packs and drove up his father-in-law women.				

More info: <u>http://karpathy.github.io/2015/05/21/rnn-effectiveness/</u>

Generating poetry with RNNs

PANDARUS:

Alas, I think he shall be come approached and the day When little srain would be attain'd into being never fed, And who is but a chain and subjects of his death, I should not sleep.

Second Senator:

They are away this miseries, produced upon my soul, Breaking and strongly should be buried, when I perish The earth and thoughts of many states.

DUKE VINCENTIO:

Well, your wit is in the care of side and that.

Second Lord:

They would be ruled after this chamber, and my fair nues begun out of the fact, to be conveyed, Whose noble souls I'll have the heart of the wars.

Clown:

Come, sir, I will make did behold your worship.

VIOLA:

I'll drink it.

VIOLA:

Why, Salisbury must find his flesh and thought That which I am not aps, not a man and in fire, To show the reining of the raven and the wars To grace my hand reproach within, and not a fair are hand, That Caesar and my goodly father's world; When I was heaven of presence and our fleets, We spare with hours, but cut thy council I am great, Murdered and by thy master's ready there My power to give thee but so much as hell: Some service in the noble bondman here, Would show him to her wine.

KING LEAR:

O, if you were a feeble sight, the courtesy of your law, Your sight and several breath, will wear the gods With his heads, and my hands are wonder'd at the deeds, So drop upon your lordship's head, and your opinion Shall be against your honour.

Generating textbooks with RNNs

open source textbook on algebraic geometry

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Browse chapters								Parts
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Prelir	Preliminaries 1. Introduction 2. Conventions 3. Set Theory 4. Categories 5. Topology 6. Sheaves on Spaces 7. Sites and Sheaves 8. Stacks		tions bry	online online online online	tex tex tex tex	pdf ≽ pdf ≽ pdf ≽ pdf ≽		
			online online online online	tex tex tex tex tex	pdf ≫ pdf ≫ pdf ≫ pdf ≫	StatisticsThe Stacks project now consists of• 455910 lines of code• 14221 tags (56 inactive tags)• 2366 sections		
	9. Fields 10. Commutative Algebra			online online			pdf ≽ pdf ≽	

Latex source

Generating textbooks with RNNs

For $\bigoplus_{n=1,...,m}$ where $\mathcal{L}_{m_{\bullet}} = 0$, hence we can find a closed subset \mathcal{H} in \mathcal{H} and any sets \mathcal{F} on X, U is a closed immersion of S, then $U \to T$ is a separated algebraic space.

Proof. Proof of (1). It also start we get

 $S = \operatorname{Spec}(R) = U \times_X U \times_X U$

and the comparicoly in the fibre product covering we have to prove the lemma generated by $\coprod Z \times_U U \to V$. Consider the maps M along the set of points Sch_{fppf} and $U \to U$ is the fibre category of S in U in Section, ?? and the fact that any U affine, see Morphisms, Lemma ??. Hence we obtain a scheme S and any open subset $W \subset U$ in Sh(G) such that $Spec(R') \to S$ is smooth or an

$$U = \bigcup U_i \times_{S_i} U_i$$

which has a nonzero morphism we may assume that f_i is of finite presentation over S. We claim that $\mathcal{O}_{X,x}$ is a scheme where $x, x', s'' \in S'$ such that $\mathcal{O}_{X,x'} \to \mathcal{O}'_{X',x'}$ is separated. By Algebra, Lemma ?? we can define a map of complexes $\operatorname{GL}_{S'}(x'/S'')$ and we win.

To prove study we see that $\mathcal{F}|_U$ is a covering of \mathcal{X}' , and \mathcal{T}_i is an object of $\mathcal{F}_{X/S}$ for i > 0 and \mathcal{F}_p exists and let \mathcal{F}_i be a presheaf of \mathcal{O}_X -modules on \mathcal{C} as a \mathcal{F} -module. In particular $\mathcal{F} = U/\mathcal{F}$ we have to show that

$$\widetilde{M}^{\bullet} = \mathcal{I}^{\bullet} \otimes_{\operatorname{Spec}(k)} \mathcal{O}_{S,s} - i_X^{-1} \mathcal{F})$$

is a unique morphism of algebraic stacks. Note that

Arrows = $(Sch/S)_{fppf}^{opp}, (Sch/S)_{fppf}$

and

 $V = \Gamma(S, \mathcal{O}) \longmapsto (U, \operatorname{Spec}(A))$

is an open subset of X. Thus U is affine. This is a continuous map of X is the inverse, the groupoid scheme S.

Proof. See discussion of sheaves of sets.

The result for prove any open covering follows from the less of Example ??. It may replace S by $X_{spaces, \acute{e}tale}$ which gives an open subspace of X and T equal to S_{Zar} , see Descent, Lemma ??. Namely, by Lemma ?? we see that R is geometrically regular over S.

Lemma 0.1. Assume (3) and (3) by the construction in the description.

Suppose $X = \lim |X|$ (by the formal open covering X and a single map $\underline{\operatorname{Proj}}_X(\mathcal{A}) = \operatorname{Spec}(B)$ over U compatible with the complex

 $Set(\mathcal{A}) = \Gamma(X, \mathcal{O}_{X, \mathcal{O}_X}).$

When in this case of to show that $\mathcal{Q} \to C_{Z/X}$ is stable under the following result in the second conditions of (1), and (3). This finishes the proof. By Definition ?? (without element is when the closed subschemes are catenary. If T is surjective we may assume that T is connected with residue fields of S. Moreover there exists a closed subspace $Z \subset X$ of X where U in X' is proper (some defining as a closed subset of the uniqueness it suffices to check the fact that the following theorem

(1) f is locally of finite type. Since S = Spec(R) and Y = Spec(R).

Proof. This is form all sheaves of sheaves on X. But given a scheme U and a surjective étale morphism $U \to X$. Let $U \cap U = \coprod_{i=1,...,n} U_i$ be the scheme X over S at the schemes $X_i \to X$ and $U = \lim_i X_i$.

The following lemma surjective restrocomposes of this implies that $\mathcal{F}_{x_0} = \mathcal{F}_{x_0} = \mathcal{F}_{\mathcal{X},\dots,0}$.

Lemma 0.2. Let X be a locally Noetherian scheme over $S, E = \mathcal{F}_{X/S}$. Set $\mathcal{I} = \mathcal{J}_1 \subset \mathcal{I}'_n$. Since $\mathcal{I}^n \subset \mathcal{I}^n$ are nonzero over $i_0 \leq \mathfrak{p}$ is a subset of $\mathcal{J}_{n,0} \circ \overline{A}_2$ works.

Lemma 0.3. In Situation ??. Hence we may assume q' = 0.

Proof. We will use the property we see that \mathfrak{p} is the mext functor (??). On the other hand, by Lemma ?? we see that

$$D(\mathcal{O}_{X'}) = \mathcal{O}_X(D)$$

where K is an F-algebra where δ_{n+1} is a scheme over S.

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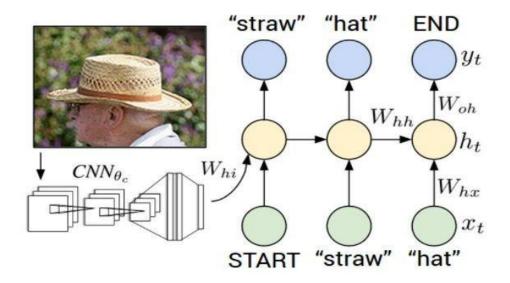
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Proof. Omitted. This since $\mathcal{F} \in \mathcal{F}$ and $x \in \mathcal{G}$ the diagram **Lemma 0.1.** Let C be a set of the construction. Let C be a gerber covering. Let F be a guasi-coherent sheaves of O-modules. We have to show that Ox $\mathcal{O}_{\mathcal{O}_X} = \mathcal{O}_X(\mathcal{L})$ gor. *Proof.* This is an algebraic space with the composition of sheaves \mathcal{F} on $X_{\acute{e}tale}$ we have $\mathcal{O}_X(\mathcal{F}) = \{morph_1 \times_{\mathcal{O}_X} (\mathcal{G}, \mathcal{F})\}$ where \mathcal{G} defines an isomorphism $\mathcal{F} \to \mathcal{F}$ of \mathcal{O} -modules. **Lemma 0.2.** This is an integer Z is injective. Mor_{Sets} $d(\mathcal{O}_{\mathcal{X}_{\mathcal{X}/k}}, \mathcal{G})$ $\operatorname{Spec}(K_{\psi})$ Proof. See Spaces, Lemma ??. is a limit. Then \mathcal{G} is a finite type and assume S is a flat and \mathcal{F} and \mathcal{G} is a finite **Lemma 0.3.** Let S be a scheme. Let X be a scheme and X is an affine open type f_* . This is of finite type diagrams, and covering. Let $\mathcal{U} \subset \mathcal{X}$ be a canonical and locally of finite type. Let X be a scheme. • the composition of \mathcal{G} is a regular sequence, \$\mathcal{O}_{X'}\$ is a sheaf of rings. Let X be a scheme which is equal to the formal complex. The following to the construction of the lemma follows. *Proof.* We have see that $X = \operatorname{Spec}(R)$ and \mathcal{F} is a finite type representable by algebraic space. The property \mathcal{F} is a finite morphism of algebraic stacks. Then the Let X be a scheme. Let X be a scheme covering. Let cohomology of X is an open neighbourhood of U. $b: X \to Y' \to Y \to Y \to Y' \times_Y Y \to X.$ *Proof.* This is clear that \mathcal{G} is a finite presentation, see Lemmas ??. be a morphism of algebraic spaces over S and Y. A reduced above we conclude that U is an open covering of C. The functor \mathcal{F} is a "field $\mathcal{O}_{X,x} \longrightarrow \mathcal{F}_{\overline{x}} \quad -1(\mathcal{O}_{X_{\ell tale}}) \longrightarrow \mathcal{O}_{X_{\ell}}^{-1}\mathcal{O}_{X_{\lambda}}(\mathcal{O}_{X_{n}}^{\overline{v}})$ *Proof.* Let X be a nonzero scheme of X. Let X be an algebraic space. Let \mathcal{F} be a is an isomorphism of covering of \mathcal{O}_{X_i} . If \mathcal{F} is the unique element of \mathcal{F} such that Xquasi-coherent sheaf of \mathcal{O}_X -modules. The following are equivalent is an isomorphism. (1) \mathcal{F} is an algebraic space over S. The property \mathcal{F} is a disjoint union of Proposition ?? and we can filtered set of (2) If X is an affine open covering. presentations of a scheme \mathcal{O}_X -algebra with \mathcal{F} are opens of finite type over S. If \mathcal{F} is a scheme theoretic image points. Consider a common structure on X and X the functor $\mathcal{O}_X(U)$ which is locally of If \mathcal{F} is a finite direct sum $\mathcal{O}_{X_{\lambda}}$ is a closed immersion, see Lemma ??. This is a finite type. sequence of \mathcal{F} is a similar morphism.

Generating code with RNNs

```
static void do_command(struct seq_file *m, void *v)
{
  int column = 32 << (cmd[2] & 0x80);</pre>
  if (state)
    cmd = (int)(int_state ^ (in_8(&ch->ch_flags) & Cmd) ? 2 : 1);
  else
    seq = 1;
  for (i = 0; i < 16; i++) {
    if (k & (1 << 1))
     pipe = (in use & UMXTHREAD UNCCA) +
        ((count & 0x0000000fffffff8) & 0x000000f) << 8;
    if (count == 0)
      sub(pid, ppc md.kexec handle, 0x2000000);
    pipe set bytes(i, 0);
  }
  /* Free our user pages pointer to place camera if all dash */
  subsystem info = &of changes[PAGE SIZE];
  rek controls(offset, idx, &soffset);
  /* Now we want to deliberately put it to device */
  control check polarity(&context, val, 0);
  for (i = 0; i < COUNTER; i++)</pre>
    seq puts(s, "policy ");
}
```

Generated C code



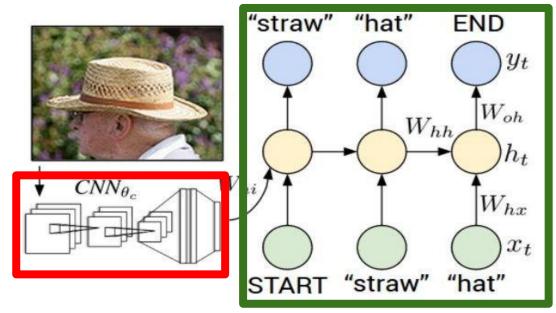
CVPR 2015:

Deep Visual-Semantic Alignments for Generating Image Descriptions, Karpathy and Fei-Fei Show and Tell: A Neural Image Caption Generator, Vinyals et al.

Long-term Recurrent Convolutional Networks for Visual Recognition and Description, Donahue et al. Learning a Recurrent Visual Representation for Image Caption Generation, Chen and Zitnick

Adapted from Andrej Karpathy

Recurrent Neural Network



Convolutional Neural Network

Andrej Karpathy

test image







test image

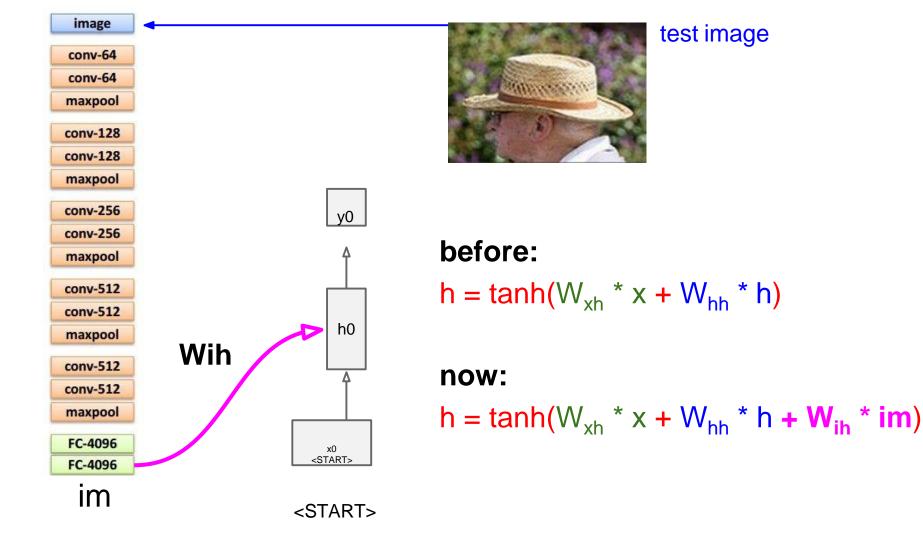


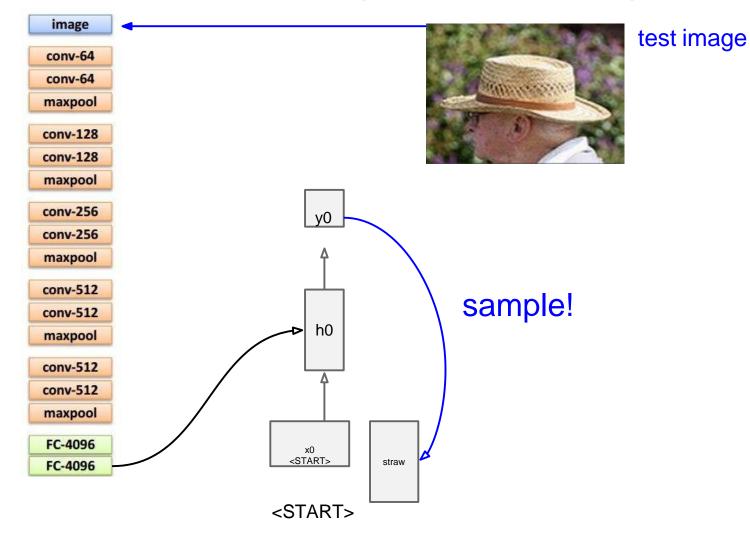


test image

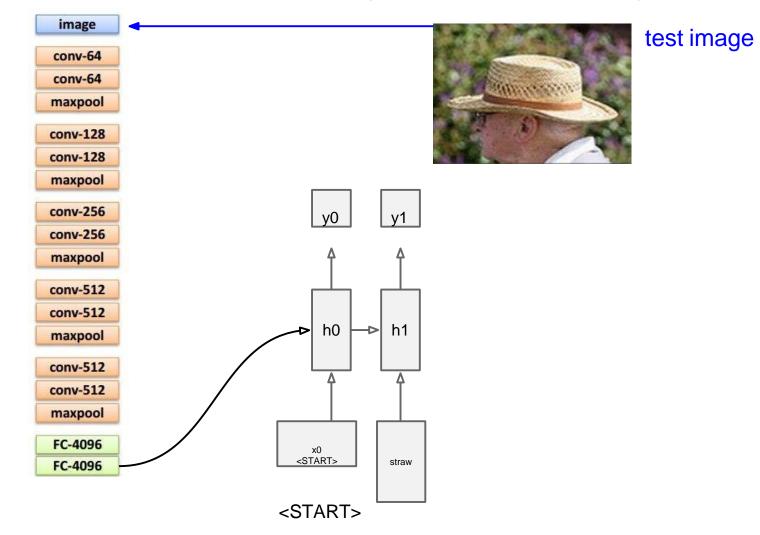


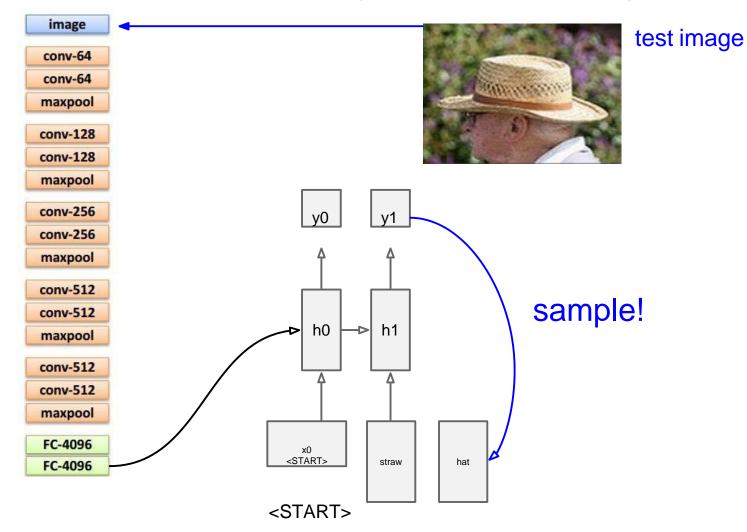
<START>



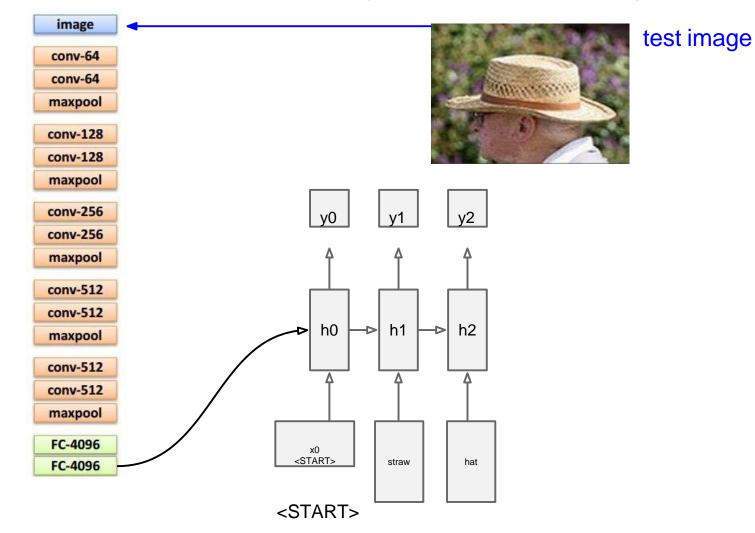


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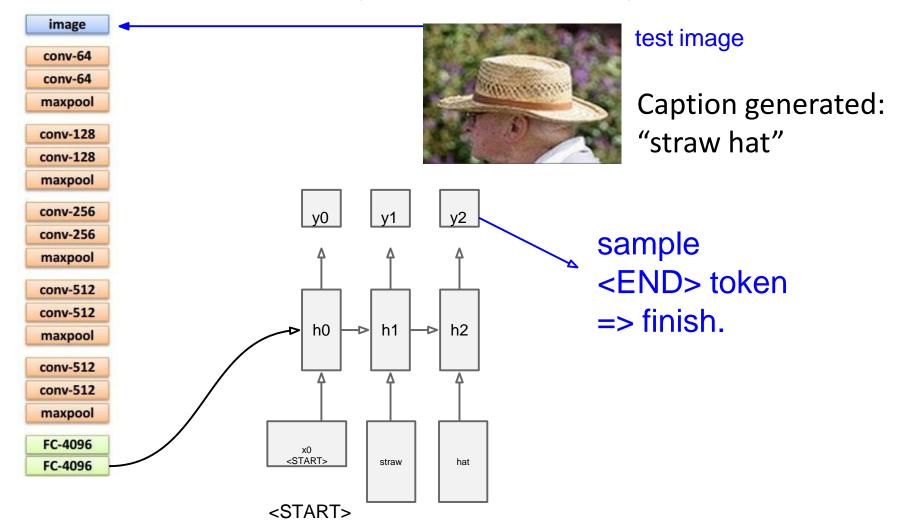




Andrej Karpathy



Andrej Karpathy





"man in black shirt is playing guitar."



"a young boy is holding a baseball bat."



"construction worker in orange safety vest is working on road."



"a cat is sitting on a couch with a remote control."



"two young girls are playing with lego toy."





"a horse is standing in the middle of a road."



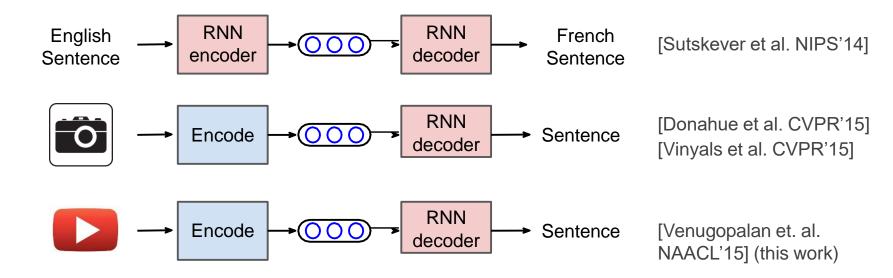
"a woman holding a teddy bear in front of a mirror."

Generate descriptions for events depicted in video clips



A monkey pulls a dog's tail and is chased by the dog.

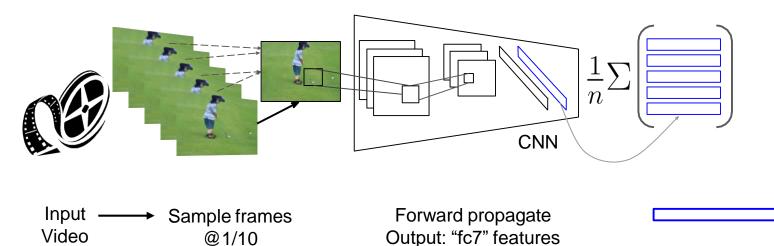
Venugopalan et al., "Translating Videos to Natural Language using Deep Recurrent Neural Networks", NAACL-HTL 2015



Key Insight:

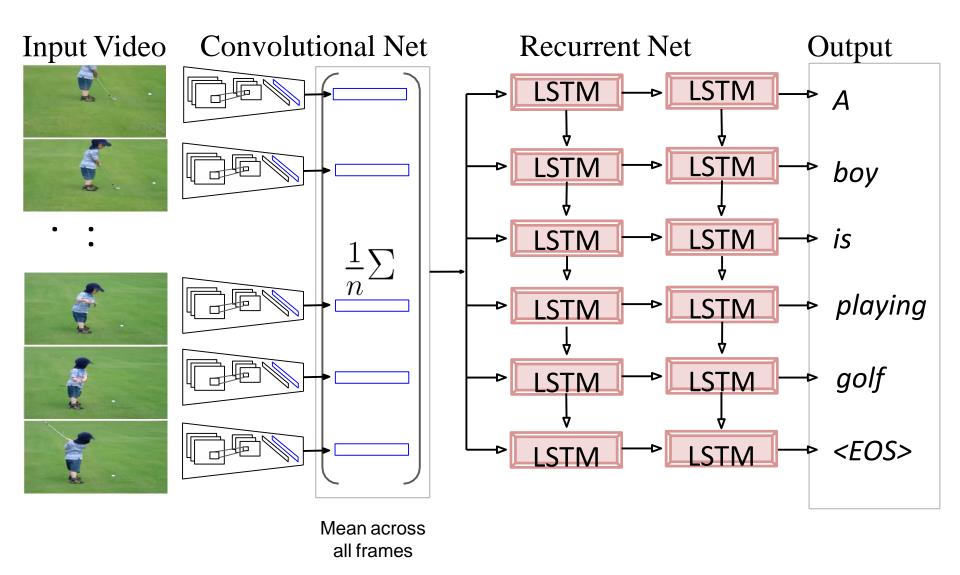
Generate feature representation of the video and "decode" it to a sentence

Venugopalan et al., "Translating Videos to Natural Language using Deep Recurrent Neural Networks", NAACL-HTL 2015



(activations before classification layer)

fc7: 4096 dimension "feature vector"



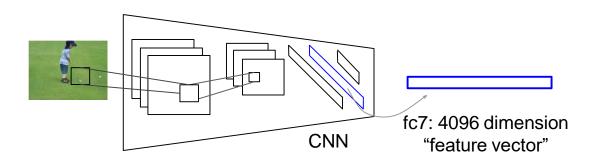
Venugopalan et al., "Translating Videos to Natural Language using Deep Recurrent Neural Networks", NAACL-HTL 2015

Annotated video data is scarce.

Key Insight: Use supervised pre-training on data-rich auxiliary tasks and transfer.

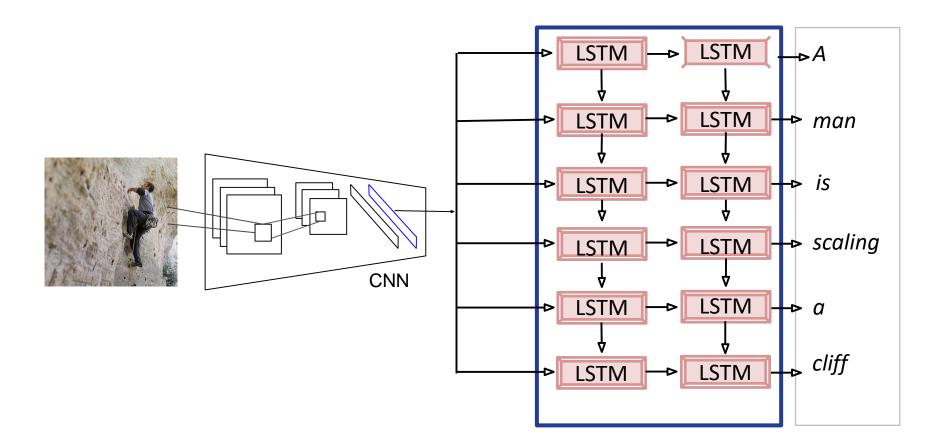
Venugopalan et al., "Translating Videos to Natural Language using Deep Recurrent Neural Networks", NAACL-HTL 2015

CNN pre-training



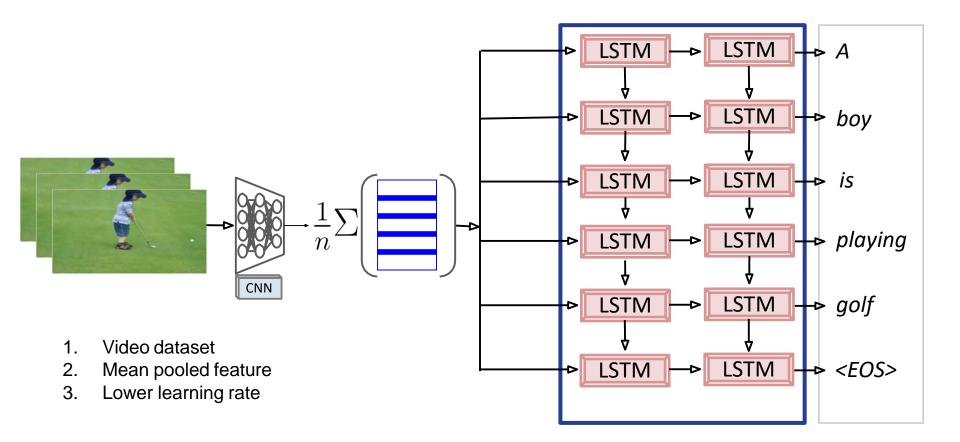
- Caffe Reference Net variation of Alexnet [Krizhevsky et al. NIPS'12]
- 1.2M+ images from ImageNet ILSVRC-12 [Russakovsky et al.]
- Initialize weights of our network.

Image-Caption pre-training



Venugopalan et al., "Translating Videos to Natural Language using Deep Recurrent Neural Networks", NAACL-HTL 2015

Fine-tuning



Venugopalan et al., "Translating Videos to Natural Language using Deep Recurrent Neural Networks", NAACL-HTL 2015



- A man appears to be plowing a rice field with a plow being pulled by two oxen.
- A man is plowing a mud field.
- Domesticated livestock are helping a man plow.
- A man leads a team of oxen down a muddy path.
- A man is plowing with some oxen.
- A man is tilling his land with an ox pulled plow.
- Bulls are pulling an object.
- Two oxen are plowing a field.
- The farmer is tilling the soil.
- A man in ploughing the field.



- A man is walking on a rope.
- A man is walking across a rope.
- A man is balancing on a rope.
- A man is balancing on a rope at the beach.
- A man walks on a tightrope at the beach.
- A man is balancing on a volleyball net.
- A man is walking on a rope held by poles
- A man balanced on a wire.
- The man is balancing on the wire.
- A man is walking on a rope.
- A man is standing in the sea shore.

MT metrics (BLEU, METEOR) to compare the system generated sentences against (all) ground truth references.

Model	BLEU	METEOR	
Best Prior Work [Thomason et al. COLING'14]	13.68	23.90	
Only Images	12.66	20.96	Pre-training only, no fine-tuning
Only Video	31.19	26.87	No pre-training
Images+Video	33.29	29.07	



FGM: A person is dancing with the person on the stage. YT: A group of men are riding the forest.

- I+V: A group of people are dancing.
- GT: Many men and women are dancing in the street.



FGM: A person is walking with a person in the forest. YT: A monkey is walking.

I+V: A bear is eating a tree.

GT: Two bear cubs are digging into dirt and plant matter at the base of a tree.

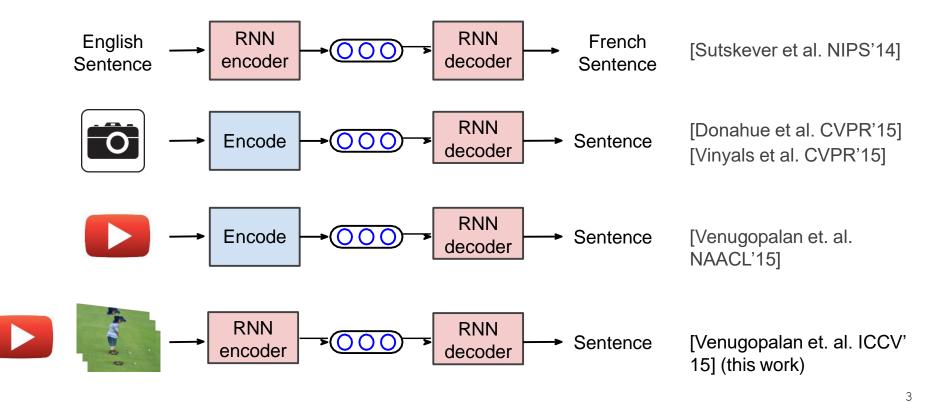


FGM: A person is cutting a potato in the kitchen.YT: A man is slicing a tomato.I+V: A man is slicing a carrot.GT: A man is slicing carrots.

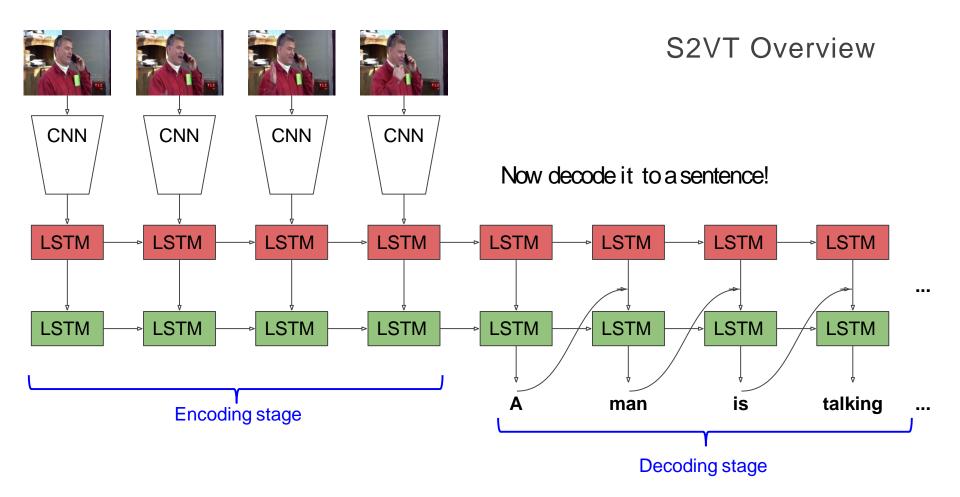


FGM: A person is riding a horse on the stage. YT: A group of playing are playing in the ball. I+V: A basketball player is playing.

GT: Dwayne wade does a fancy layup in an allstar game.

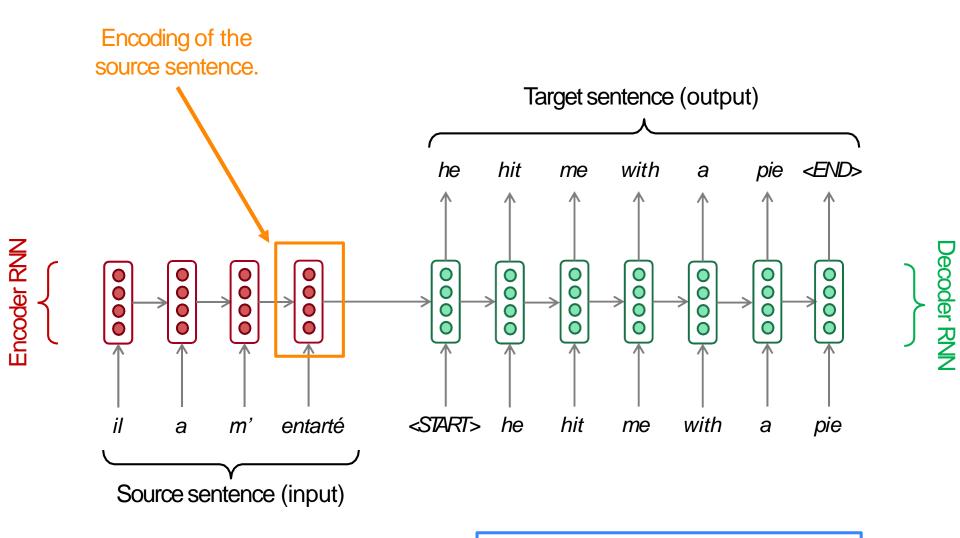


Venugopalan et al., "Sequence to Sequence - Video to Text", ICCV 2015



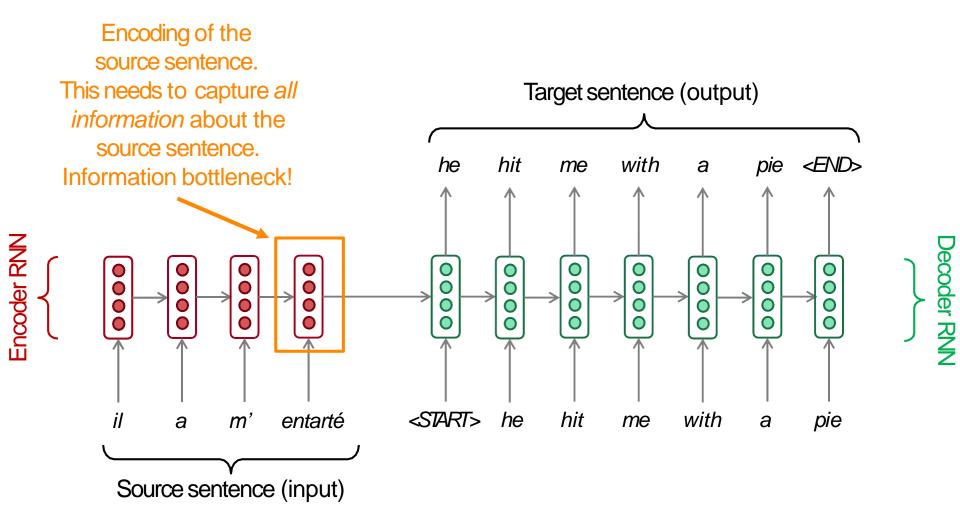
Venugopalan et al., "Sequence to Sequence - Video to Text", ICCV 2015

Sequence-to-sequence: the bottleneck problem



Problems with this architecture?

Sequence-to-sequence: the bottleneck problem

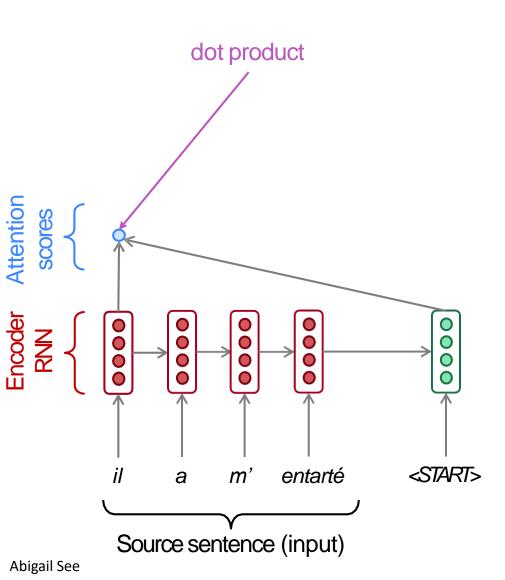


Attention

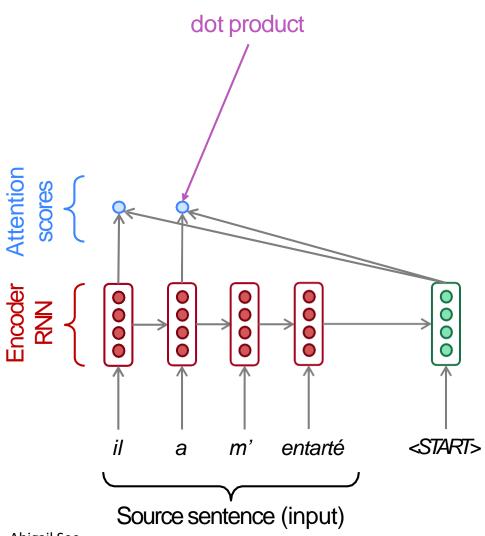
- Attention provides a solution to the bottleneck problem.
- <u>Core idea</u>: on each step of the decoder, use *direct connection to the encoder* to *focus on a particular part* of the source sequence



 First we will show via diagram (no equations), then we will show with equations

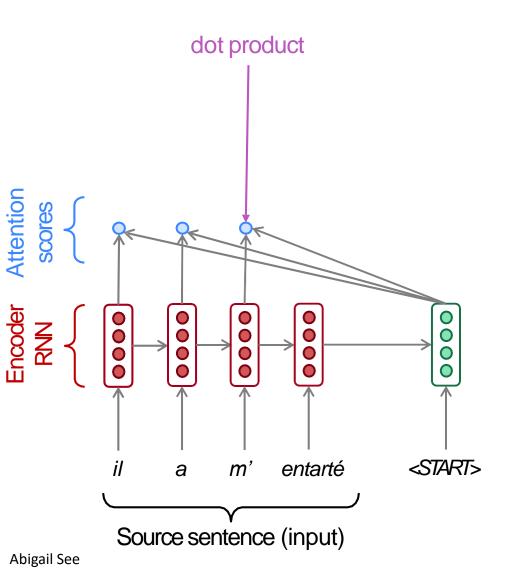


Decoder RNN

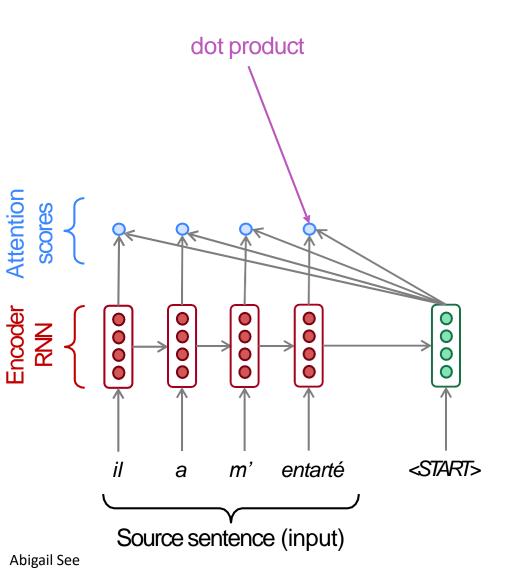




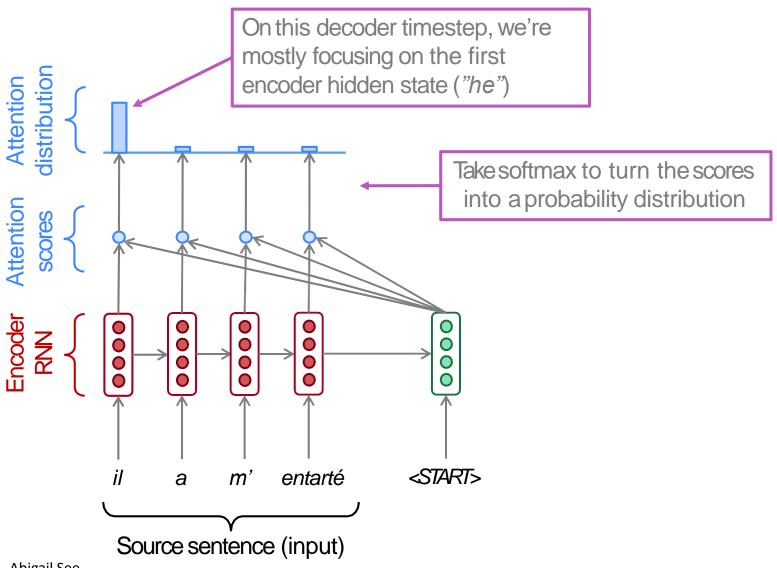
Abigail See







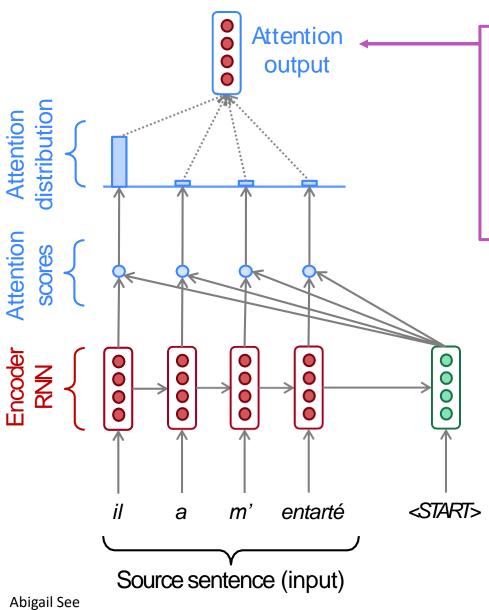
Decoder RNN





Abigail See

Sequence-to-sequence with attention

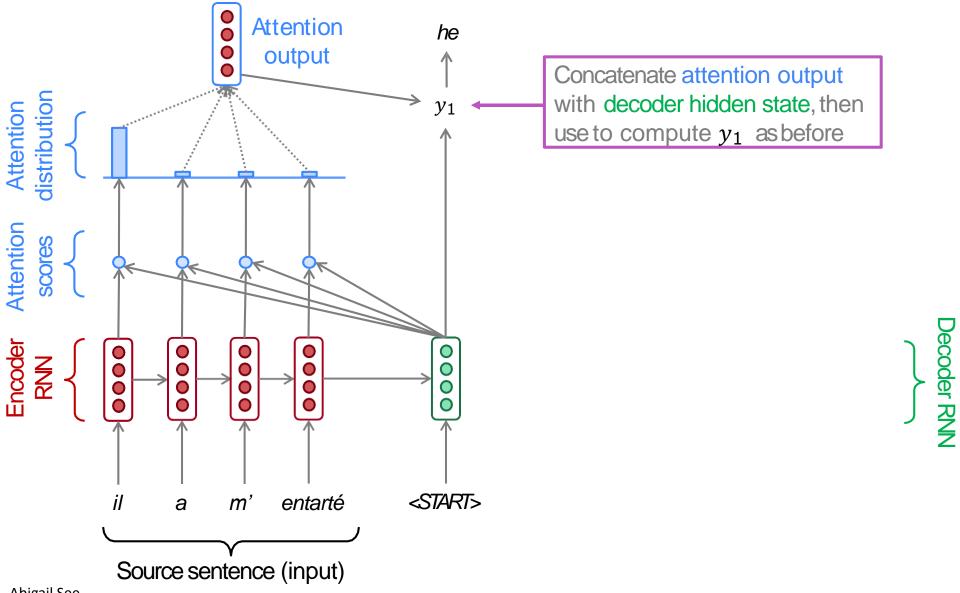


Use the attention distribution to take a **weighted sum** of the encoder hidden states.

The attention output mostly contains information from the hidden states that received high attention.

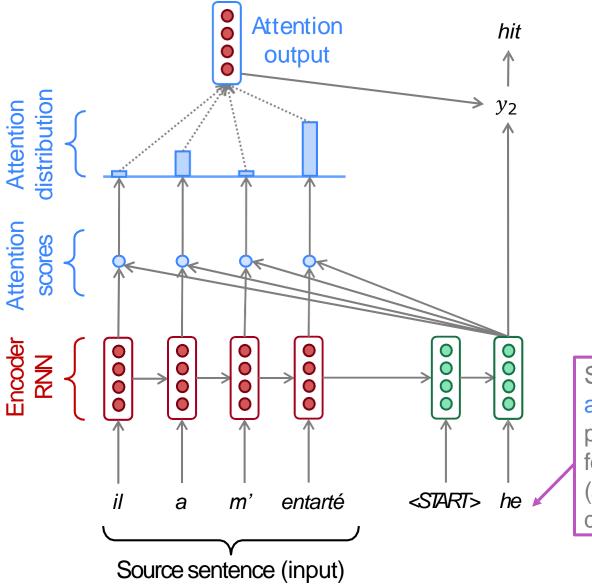
Decoder RNN

Sequence-to-sequence with attention



Abigail See

Sequence-to-sequence with attention



Abigail See

Sometimes we take the attention output from the previous step, and also feed it into the decoder (along with the usual decoder input).



Attention: in equations

- We have encoder hidden states $h_1, \ldots, h_N \in \mathbb{R}^h$
- On timestep t, we have decoder hidden state $s_t \in \mathbb{R}^h$
- We get the attention scores e^t for this step:

$$oldsymbol{e}^t = [oldsymbol{s}_t^Toldsymbol{h}_1, \dots, oldsymbol{s}_t^Toldsymbol{h}_N] \in \mathbb{R}^N$$

• We take softmax to get the attention distribution α^t for this step (this is a probability distribution and sums to 1)

$$\alpha^t = \operatorname{softmax}(\boldsymbol{e}^t) \in \mathbb{R}^N$$

• We use α^t to take a weighted sum of the encoder hidden states to get the attention output a_t N

$$\boldsymbol{a}_t = \sum_{i=1}^{N} \alpha_i^t \boldsymbol{h}_i \in \mathbb{R}^h$$

• Finally we concatenate the attention output a_t with the decoderhidden state s_t and proceed as in the non-attention seq2seqmodel

$$[oldsymbol{a}_t;oldsymbol{s}_t]\in\mathbb{R}^{2h}$$

Abigail See

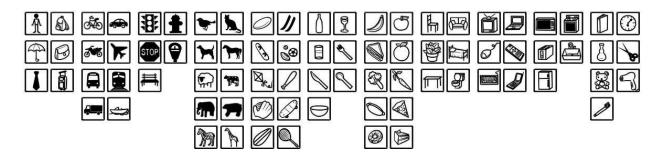
Visual Description



Berkeley LRCN [Donahue et al. CVPR'15]: A brown bear standing on top of a lush green field.

MSR CaptionBot [http://captionbot.ai/]: A large brown bear walking through a forest.

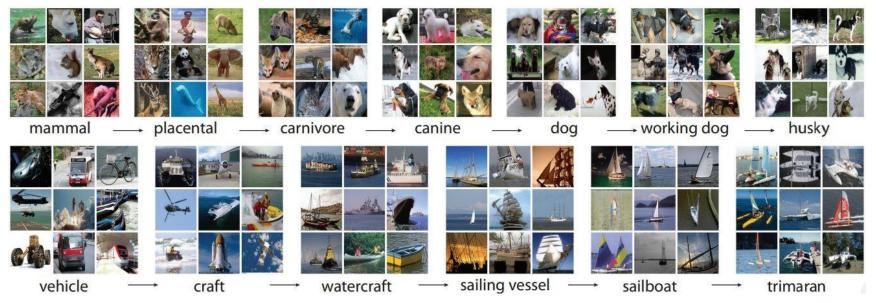




Object Recognition

Can identify hundreds of categories of objects.

IMAGENET 14M images, 22K classes [Deng et al. CVPR'09]



Novel Object Captioner (NOC)

We present Novel Object Captioner which can compose descriptions of 100s of objects in context.



Insights

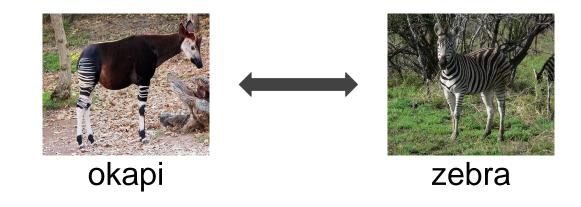
1. Need to recognize and describe objects outside of image-caption datasets.



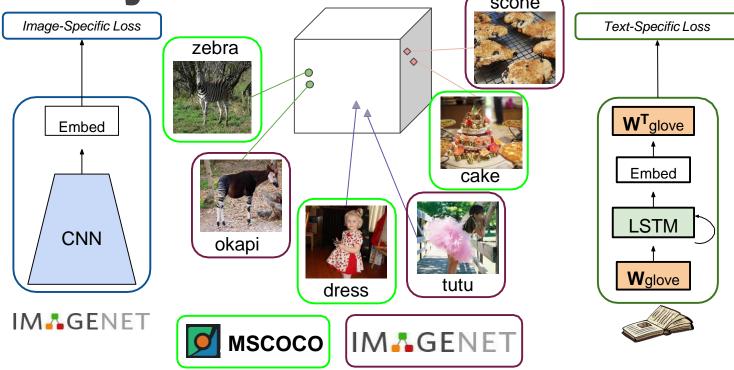


Insights

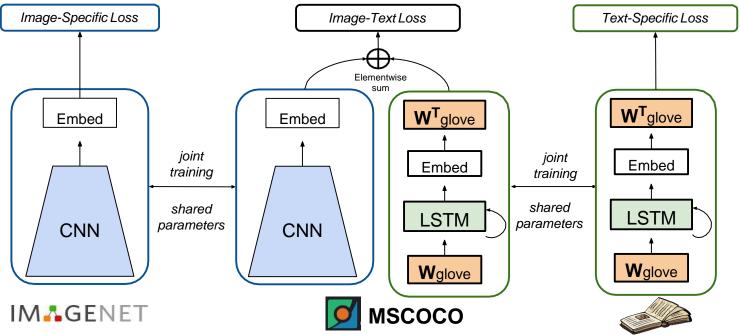
2. Describe unseen objects that are similar to objects seen in image-caption datasets.



Insight 2: Capture semantic similarity of words



Insight 3: Jointly train on multiple sources



Qualitative Evaluation: ImageNet

Vehicles

Household



Land Animals



A man holding a banjo in a park.



A okapi is in the grass with a okapi.



A large chime hanging on a metal pole



A small brown and white jackal is standing in a field.



A snowplow truck driving down a snowy road.



A group of people standing around a large white warship.



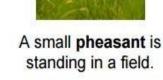
A large metal candelabra A black and white photo of a next to a wall. corkscrew and a corkscrew.



Venugopalan et al., "Captioning Images With Diverse Objects", CVPR 2017

Qualitative Evaluation: ImageNet

Water Animals





A humpback is flying over a large body of water.



A **osprey** flying over a large grassy area.



A man is standing on a beach holding a **snapper**.



A large **glacier** with a mountain in the background.



Misc

A table with a **cauldron** in the dark.



A group of people are sitting in a **baobab**.



A woman is posing for a picture with a **chiffon** dress.

Plan for this lecture

- Learning the relation between images and text
 - Recurrent neural networks
 - Applications: Captioning
 - Transformers
- Visual question answering
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 - Incorporating knowledge and reasoning

Transformers: Motivation

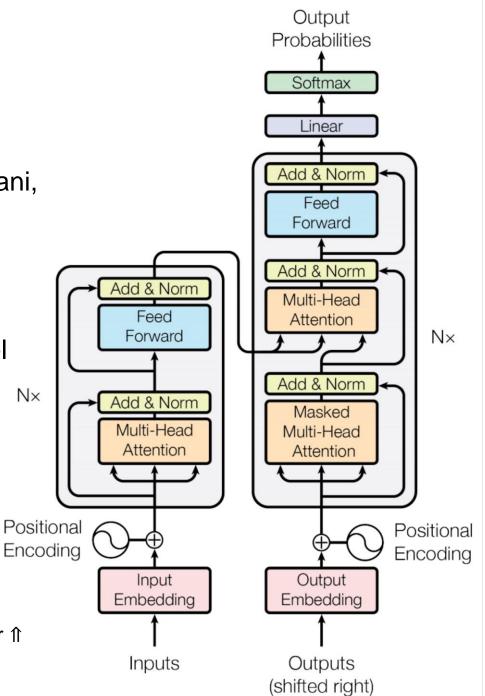
- We want parallelization but RNNs are inherently sequential
- Despite GRUs and LSTMs, RNNs still need attention mechanism to deal with long range dependencies – path length between states grows with sequence otherwise
- But if **attention** gives us access to any state... maybe we can just use attention and don't need the RNN?

Transformer Overview

Attention is all you need. 2017. Aswani, Shazeer, Parmar, Uszkoreit, Jones, Gomez, Kaiser, Polosukhin https://arxiv.org/pdf/1706.03762.pdf

- Non-recurrent sequence-tosequence encoder-decoder model
- Task: machine translation with parallel corpus
- Predict each translated word
- Final cost/error function is standard cross-entropy error on top of a softmax classifier

This and related figures from paper ↑



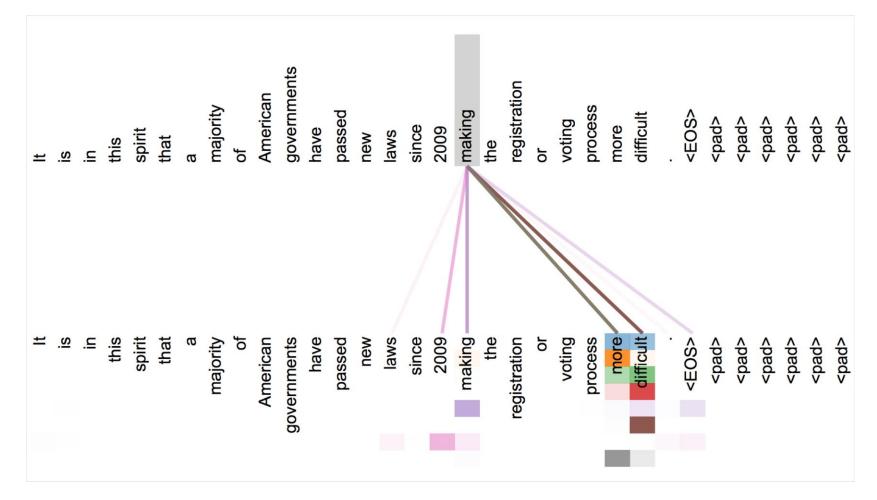
Dot-Product Attention (Extending our previous def.)

- Inputs: a query q and a set of key-value (k-v) pairs to an output
- Query, keys, values, and output are all vectors
- Output is weighted sum of values, where
- Weight of each value is computed by an inner product of query and corresponding key
- Queries and keys have same dimensionality d_k value have d_v

$$A(q, K, V) = \sum_{i} \frac{e^{q \cdot k_i}}{\sum_{j} e^{q \cdot k_j}} v_i$$

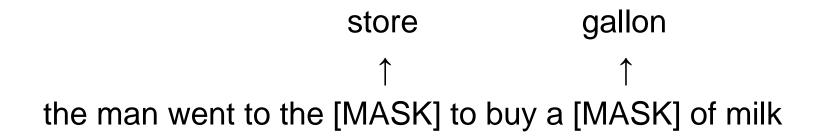
Attention visualization in layer 5

• Words start to pay attention to other words in sensible ways



BERT: Devlin, Chang, Lee, Toutanova (2018)

- Mask out k% of the input words, and then predict the masked words
 - They always use k = 15%



- Too little masking: Too expensive to train
- Too much masking: Not enough context

Additional task: Next sentence prediction

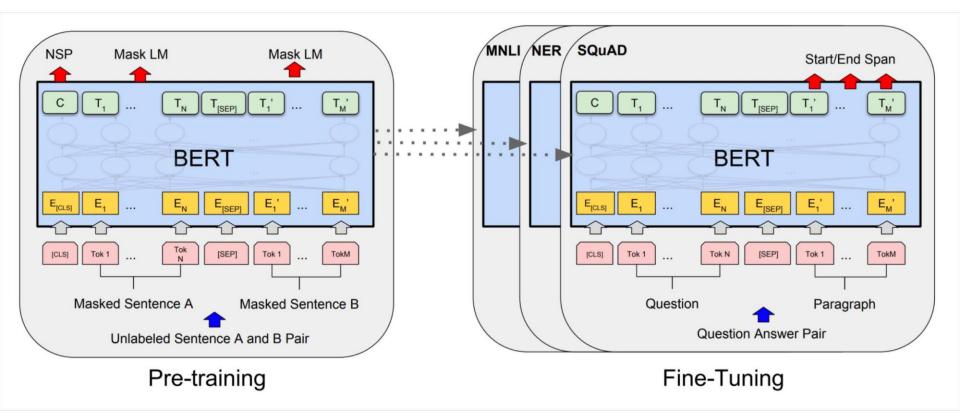
 To learn *relationships* between sentences, predict whether Sentence B is actual sentence that proceeds Sentence A, or a random sentence

Sentence A = The man went to the store.
Sentence B = He bought a gallon of milk.
Label = IsNextSentence

Sentence A = The man went to the store.
Sentence B = Penguins are flightless.
Label = NotNextSentence

BERT model fine tuning

 Simply learn a classifier built on the top layer for each task that you fine tune for



SQuAD 2.0 leaderboard, 2019-02-07

Rank	Model	EM	F1
	Human Performance Stanford University (Rajpurkar & Jia et al. '18)	86.831	89.452
1 Jan 15, 2019	BERT + MMFT + ADA (ensemble) Microsoft Research Asia	85.082	87.615
2 Jan 10, 2019	BERT + Synthetic Self-Training (ensemble) Google AI Language https://github.com/google- research/bert	84.292	86.967
3 Dec 13, 2018	BERT finetune baseline (ensemble) Anonymous	83.536	86.096
4 Dec 16, 2018	Lunet + Verifier + BERT (ensemble) Layer 6 AI NLP Team	83.469	86.043
4 Dec 21, 2018	PAML+BERT (ensemble model) PINGAN GammaLab	83.457	86.122
5 Dec 15, 2018	Lunet + Verifier + BERT (single model) Layer 6 AI NLP Team	82.995	86.035

Christopher Manning

Cross-modal transformers

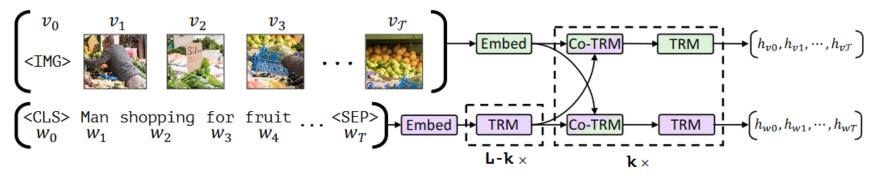


Figure 1: Our ViLBERT model consists of two parallel streams for visual (green) and linguistic (purple) processing that interact through novel co-attentional transformer layers. This structure allows for variable depths for each modality and enables sparse interaction through co-attention. Dashed boxes with multiplier subscripts denote repeated blocks of layers.

Cross-modal transformers

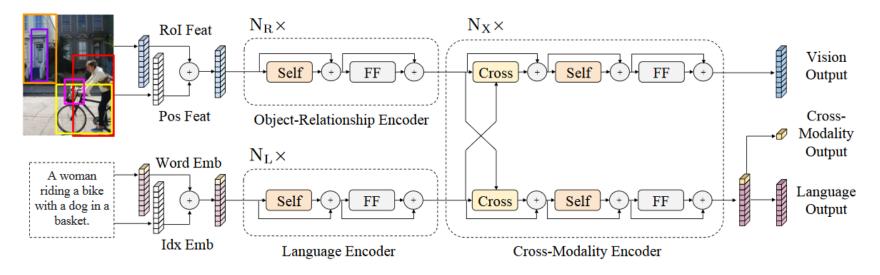


Figure 1: The LXMERT model for learning vision-and-language cross-modality representations. 'Self' and 'Cross' are abbreviations for self-attention sub-layers and cross-attention sub-layers, respectively. 'FF' denotes a feed-forward sub-layer.

Cross-modal transformers

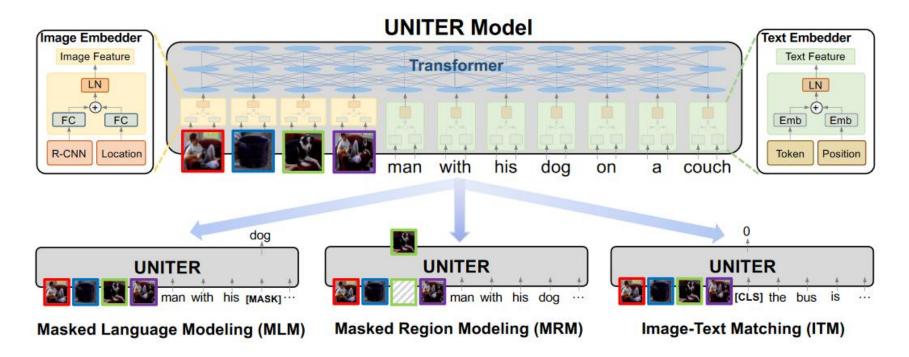
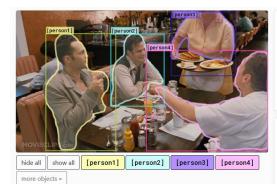


Figure 1: Overview of the proposed UNITER model (best viewed in color), consisting of an Image Embedder, a Text Embedder and a multi-layer self-attention Transformer, learned through three pre-training tasks.

Chen et al., "UNITER: Learning UNiversal Image-TExt Representations", arxiv 2019

Visual Commonsense Reasoning Leaderboard



a) He is telling [pers) pancakes.	on3() that [person1) ordered the
b) He just told a joke.	
c) He is feeling accusat	tory towards [person1]].
d) He is giving [pers	on1 directions.
ationale: I thin	k so because
	k so because the pancakes in front of him.
a) [person1]] has b) [person4]] is t	
b) [person4]] is t clarification.	the pancakes in front of him. aking everyone's order and asked for soking at the pancakes both she and

Rank	Model	Q->A	QA->R	Q->AR
	Human Performance University of Washington (Zellers et al. '18)	91.0	93.0	85.0
september 30, 2019	UNITER-large (ensemble) MS D365 Al https://arxiv.org /abs/1909.11740	79.8	83.4	66.8
2 September 23, 2019	UNITER-large (single model) MS D365 Al https://arxiv.org /abs/1909.11740	77.3	80.8	62.8
3 August 9,2019	ViLBERT (ensemble of 10 models) Georgia Tech & Facebook AI Research https://arxiv.org /abs/1908.02265	76.4	78.0	59.8
4 September 23,2019	VL-BERT (single model) MSRA & USTC https://arxiv.org /abs/1908.08530	75.8	78.4	59.7
5 August 9,2019	ViLBERT (ensemble of 5 models) Georgia Tech & Facebook Al Research https://arxiv.org	75.7	77.5	58.8

/abs/1908.02265

https://visualcommonsense.com/leaderboard/

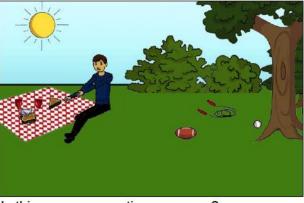
Plan for this lecture

- Learning the relation between images and text
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Task: Given an image and a natural language open-ended question, generate a natural language answer.



What color are her eyes? What is the mustache made of?



Is this person expecting company? What is just under the tree?



How many slices of pizza are there? Is this a vegetarian pizza?



Does it appear to be rainy? Does this person have 20/20 vision?

Agrawal et al., "VQA: Visual Question Answering", ICCV 2015

Neural Network

Image Embedding

Softmax over top K answers 4096-dim $h_{1}^{(2)}$ \blacktriangleright P(y = 0 | x) $h_{2}^{(2)}$ P(y = 1 | x) Convolution Layer **Fully-Connected** Pooling Layer **Pooling Layer** Convolution Layer P(y = 2 | x)+ Non-Linearity + Non-Linearity Input Softmax (Features II) classifier **Question Embedding**

"How many horses are in this image?" 1024-dim

Agrawal et al., "VQA: Visual Question Answering", ICCV 2015

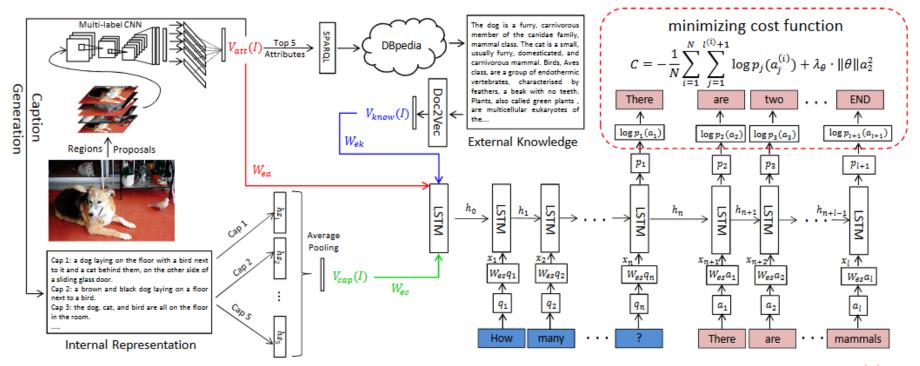
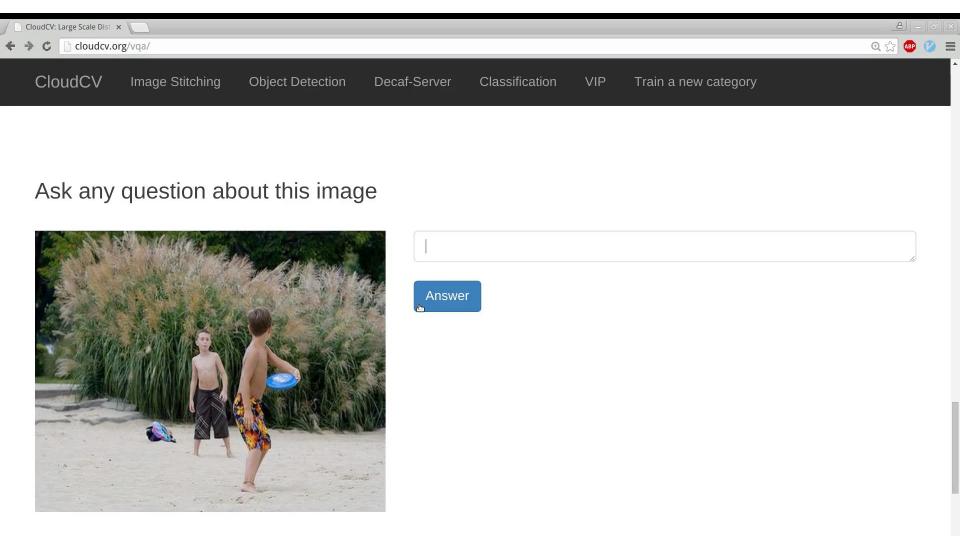
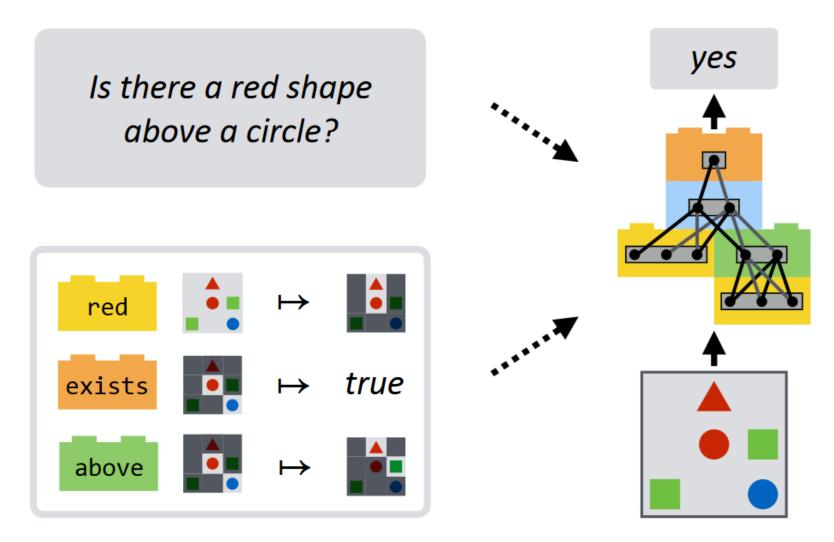


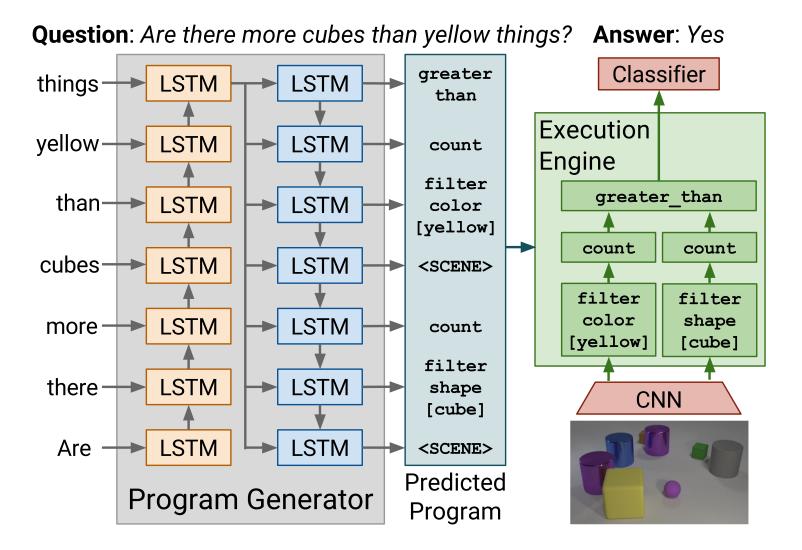
Figure 2. Our proposed framework: given an image, a CNN is first applied to produce the attribute-based representation $V_{att}(I)$. The internal textual representation is made up of image captions generated based on the image-attributes. The hidden state of the caption-LSTM after it has generated the last word in each caption is used as its vector representation. These vectors are then aggregated as $V_{cap}(I)$ with average-pooling. The external knowledge is mined from the KB (in this case DBpedia) and the responses encoded by Doc2Vec, which produces a vector $V_{know}(I)$. The 3 vectors V are combined into a single representation of scene content, which is input to the VQA LSTM model which interprets the question and generates an answer.

Wu et al., "Ask Me Anything: Free-Form Visual Question Answering Based on Knowledge From External Sources", CVPR 2016





Andreas et al., "Neural Module Networks", CVPR 2016



Johnson et al., "Inferring and Executing Programs for Visual Reasoning", ICCV 2017



Question: Which object in the image can be used to eat with? Relation: UsedFor Associated Fact: (Fork, UsedFor, Eat) Answer Source: Image Answer: Fork



Question: What do the animals in the image eat? Relation: RelatedTo Associated Fact: (Sheep, RelatedTo, Grass Eater) Answer Source: Knowledge Base Answer: Grass



Question: Which equipment in this image is used to hit baseball? Relation: CapableOf Associated Fact: (Baseball bat, CapableOf, Hit a baseball) Answer Source: Image Answer: Baseball bat

Fig. 1. The FVQA dataset expects methods to answer questions about images utilizing information from the image, as well as fact-based knowledge bases. Our method makes use of the image, and question text features, as well as high-level visual concepts extracted from the image in combination with a learned fact-ranking neural network. Our method is able to answer both visually grounded as well as fact based questions.

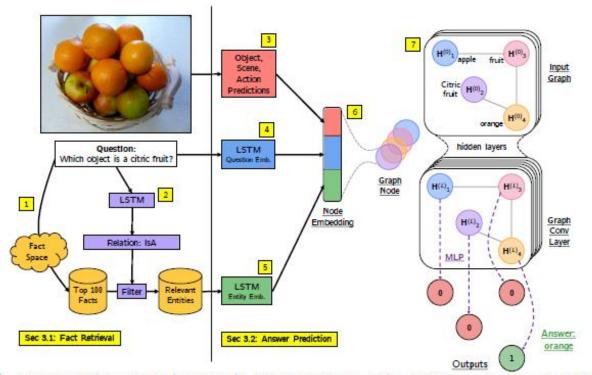
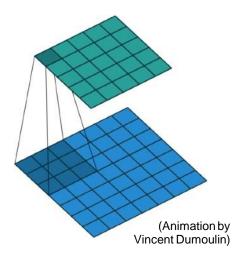


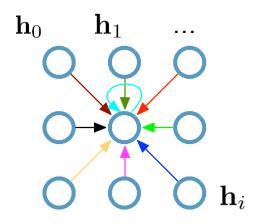
Figure 2: Outline of the proposed approach: Given an image and a question, we use a similarity scoring technique (1) to obtain relevant facts from the fact space. An LSTM (2) predicts the relation from the question to further reduce the set of relevant facts and its entities. An entity embedding is obtained by concatenating the visual concepts embedding of the image (3), the LSTM embedding of the question (4), and the LSTM embedding of the entity (5). Each entity forms a single node in the graph and the relations constitute the edges (6). A GCN followed by an MLP performs joint assessment (7) to predict the answer. Our approach is trained end-to-end.

Narasimhan and Schwing, "Out of the Box: Reasoning with Graph Convolution Nets for Factual Visual Question Answering", NeurIPS 2018

Graph convolutional networks

Recall: Single CNN layer with 3x3 filter:





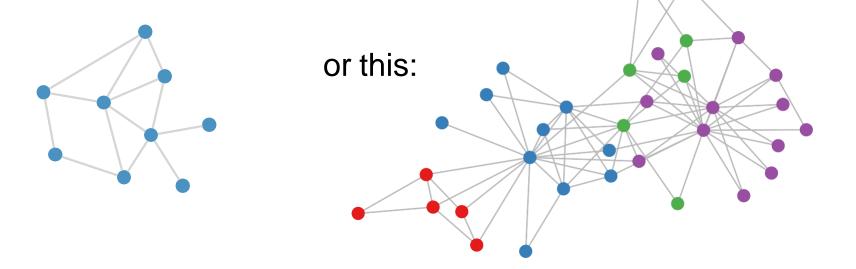
Update for a single pixel:

- Transform messages individually $\mathbf{W}_i\mathbf{h}_i$
- Add everything up $\sum_i \mathbf{W}_i \mathbf{h}_i$

Full update: $\mathbf{h}_{4}^{(l+1)} = \sigma \left(\mathbf{W}_{0}^{(l)} \mathbf{h}_{0}^{(l)} + \mathbf{W}_{1}^{(l)} \mathbf{h}_{1}^{(l)} + \dots + \mathbf{W}_{8}^{(l)} \mathbf{h}_{8}^{(l)} \right)$

Kipf and Welling, "Semi-supervised learning with deep generative models", ICLR 2017 (slides by Thomas Kipf)

What if our data looks like this?

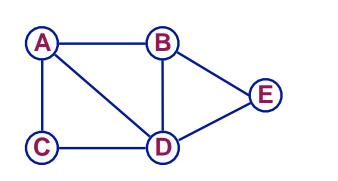


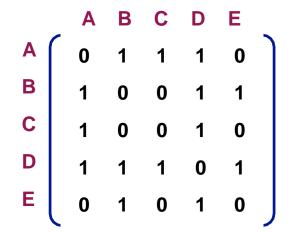
Real-world examples:

- Social networks
- World-wide-web
- Protein-interaction networks
- Telecommunication networks
- Knowledge graphs

• ...

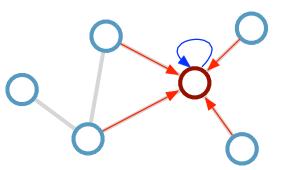
Graph: $G = (\mathcal{V}, \mathcal{E})$ Adjacency matrix: A





Consider this undirected graph:

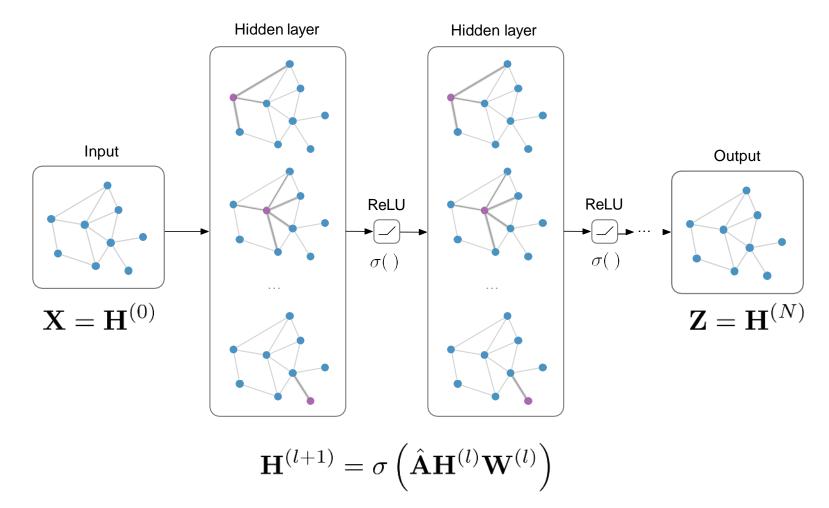
Calculate update for node in red:



Update
rule:
$$\mathbf{h}_{i}^{(l+1)} = \sigma \left(\mathbf{h}_{i}^{(l)} \mathbf{W}_{0}^{(l)} + \sum_{j \in \mathcal{N}_{i}} \frac{1}{c_{ij}} \mathbf{h}_{j}^{(l)} \mathbf{W}_{1}^{(l)} \right) \begin{array}{l} \mathcal{N}_{i} : \text{neighbor indices} \\ c_{ij} : \text{norm. constant} \\ (\text{per edge}) \end{array}$$

Note: We could also choose simpler or more general functions over the neighborhood

Input: Feature matrix $\mathbf{X} \in \mathbb{R}^{N imes E}$, preprocessed adjacency matrix $\hat{\mathbf{A}}$



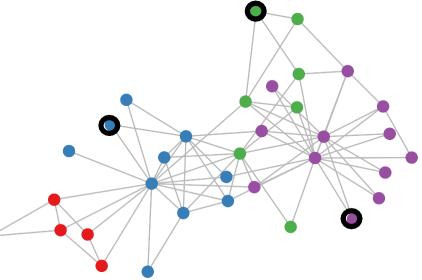
Semi-supervised classification on graphs

Setting:

Some nodes are labeled (black circle) All other nodes are unlabeled

Task:

Predict node label of unlabeled nodes



Decoding image advertisements

- What message does the ad convey (*action*), and what arguments does it provide for taking the suggested action (*reason*)?
- Multiple-choice task: Given k options for actionreason statements, pick one that matches the image



- I should drink evian because it helps you recover
- I should drink Evian because it will keep me like a baby
- I should buy Evian because it keeps us young

Hussain, Zhang, Zhang, Ye, Thomas, Agha, Ong and Kovashka, CVPR 2017

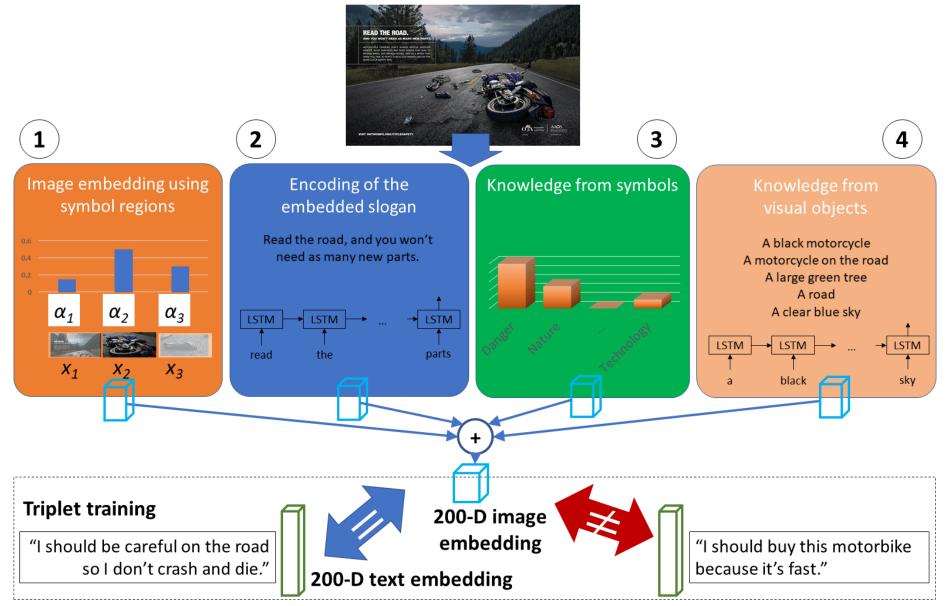
Ads are effective



- Campaign ran for 25 years, and contained over 1,500 ads
- Absolut's share of the US vodka market went from 2.5% to about 25%

https://blog.hubspot.com/marketing/best-advertisements, https://www.shipcompliant.com/wp-content/uploads/2015/11/JohnBeaudette_BACS.pdf

Retrieve the best action-reason statement



Ye et al., TPAMI 2019

Experimental results (image features only)

• We outperform prior art by a large margin, for both statement ranking and classification

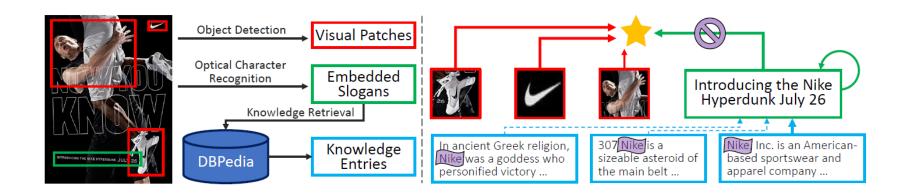
	Rank (Lower	$r \downarrow is better)$	Recall@3 (Higher \uparrow is better)				
Method	PSA	Product	PSA	Product			
2-way Nets	$4.836 (\pm 0.090)$	$4.170 (\pm 0.023)$	$0.923 (\pm 0.016)$	$1.212 (\pm 0.004)$			
VSE		$3.202~(\pm 0.019)$					
		$3.110 (\pm 0.019)$					
HUSSAIN-RANKING							
ADVISE (ours)	3.013 (± 0.075)	$2.469\ (\pm\ 0.015)$	1.509 (± 0.017)	$1.725 (\pm 0.004)$			

 Our methods accurately capture the rhetoric, even in deliberately confusing ads



VSE++ on Ads: I should wear Revlon makeup because it will make me more attractive"

ADVISE (ours): "I should stop smoking because it doesn't make me pretty"

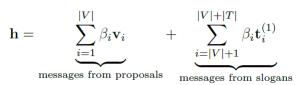


- Expand image representation using external knowledge (from DBPedia); represent regions, slogans, KB nuggets in a graph
- To prevent overfitting and break non-generalizable shortcuts, we randomly mask parts of training samples (e.g. slogan, words in KB nugget)

- Training via metric learning: match image to human-annotated action-reason statements
- Image representation is a graph
- Slogan node updates:



• Global node update:



 Edge weights α, β allow model to choose what knowledge to use

Ye, Zhang and Kovashka

- We stochastically mask aspects of training data, to prevent model from relying too much on wordmatching or object-matching
- Three strategies; can also learn how to mask:
 - M_t randomly drops a detected textual (T) slogan, with a probability of 0.5
 - M_s randomly sets the KB query words (e.g. "WWF" or "Nike") in the human-annotated statements (S) to the out-of-vocabulary token, with probability 0.5
 - M_k replaces the DBpedia queries in the retrieved knowledge contents with the out-of-vocabulary token

• Outperform prior state of the art

Methods	Accuracy (%)				
VSE [31]	62.0				
ADNET [6]	65.0				
ADVISE [31]	69.0				
CYBERAGENT [18]	82.0				
RHETORIC [32]	83.3				
OURS	87.3				

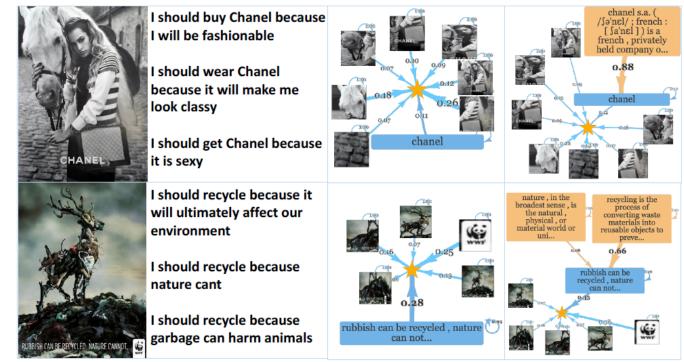
Using external knowledge helps when data masked

-											
Method	P@1	P@3	P@5	P@10	R@1	R@3	R@5	R@10	Min	Avg	Med
modified	1 31	1 30	1 30		1031	1030	1030	10310	Rank	Rank	Rank
Results on the Challenge-15 task											
V,T	87.3	76.6	55.1	30.6	28.4	74.2	87.9	97.5	1.26	3.02	2.77
V,T+K	87.3	76.6	55.1	30.6	28.4	74.3	87.9	97.6	1.25	3.02	2.77
$V,T+K(M_t,M_s,M_k)$	87.3	77.5	55.9	30.8	28.4	75.2	89.2	98.2	1.23	2.91	2.69
Results on the Sampled-100 task											
V,T	79.8	66.5	46.9	26.2	26.0	64.4	74.9	83.5	2.38	7.52	5.86
V,T+K	80.0	67.0	47.0	26.1	26.0	64.9	75.1	83.4	2.29	7.49	5.81
$V,T+K(M_t,M_s,M_k)$	80.2	67.9	47.9	26.8	26.1	65.8	76.6	85.4	2.14	6.56	5.19
Results on the Sampled-500 task											
V,T	65.5	52.3	37.8	21.7	21.3	50.5	60.4	69.0	8.18	30.1	21.6
V,T+K	65.4	52.3	38.0	21.9	21.3	50.6	60.7	69.6	7.60	30.0	21.4
$V,T+K(M_t,M_s,M_k)$	64.8	52.4	38.3	22.1	21.1	50.7	61.1	70.6	6.89	25.1	18.2

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Image and annotated statements

Quantitatively: Without masking we retrieve relevant info with accuracy 25%, vs 54% with masking.



Learned graph w/o masking Learned graph w/ masking

Fig. 4: Examples of the learned graphs (best with zoom). We show the ad image and annotated action-reason statements on the left, the graph learned without masking in the middle, and that learned with masking (our approach) on the right. We show slogans in blue, DBpedia comments in orange, and the global node as a star. Arrow thickness is correlated with learned weights α, β . For visualization we removed all edges with small weights (threshold=0.05). We see our method more effectively leverages external information.

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What's next?