CS 1678: Intro to Deep Learning

Recurrent Neural Networks

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University of Pittsburgh
February 26, 2024

Plan for this lecture

- Recurrent neural networks
  - Basics
  - Training (backprop through time, vanishing gradient)
  - Recurrent networks with gates (GRU, LSTM)
- Applications in NLP and vision
  - Neural machine translation (beam search, attention)
  - Image/video captioning

Recurrent neural networks

Some pre-RNN captioning results

This is a picture of one sky, one road and one sheep. The gray sky is over the gray road. The gray sheep is by the gray road.

This is a picture of two dogs. The first dog is near the second furry dog.

Here we see one road, one sky and one bicycle. The road is near the blue sky, and near the colorful bicycle. The colorful bicycle is within the blue sky.

Kulkarni et al., CVPR 2011

Results with Recurrent Neural Networks

"man in black shirt is playing guitar."

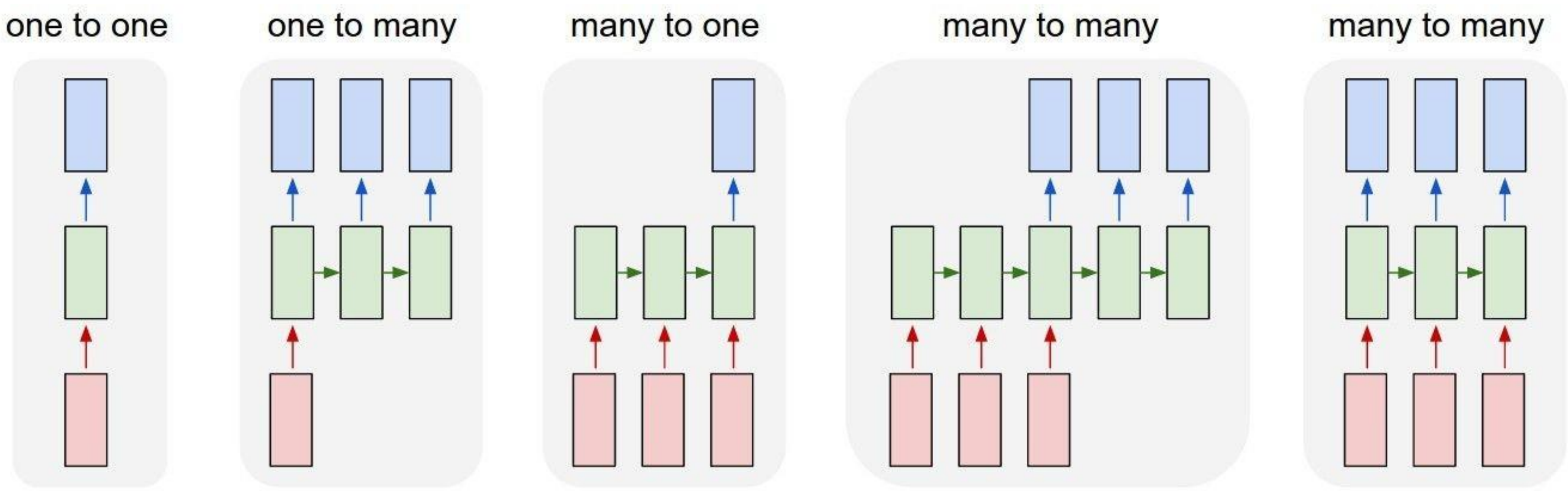
"construction worker in orange safety vest is working on road."

"two young girls are playing with lego toy."

"boy is doing backflip on wakeboard."

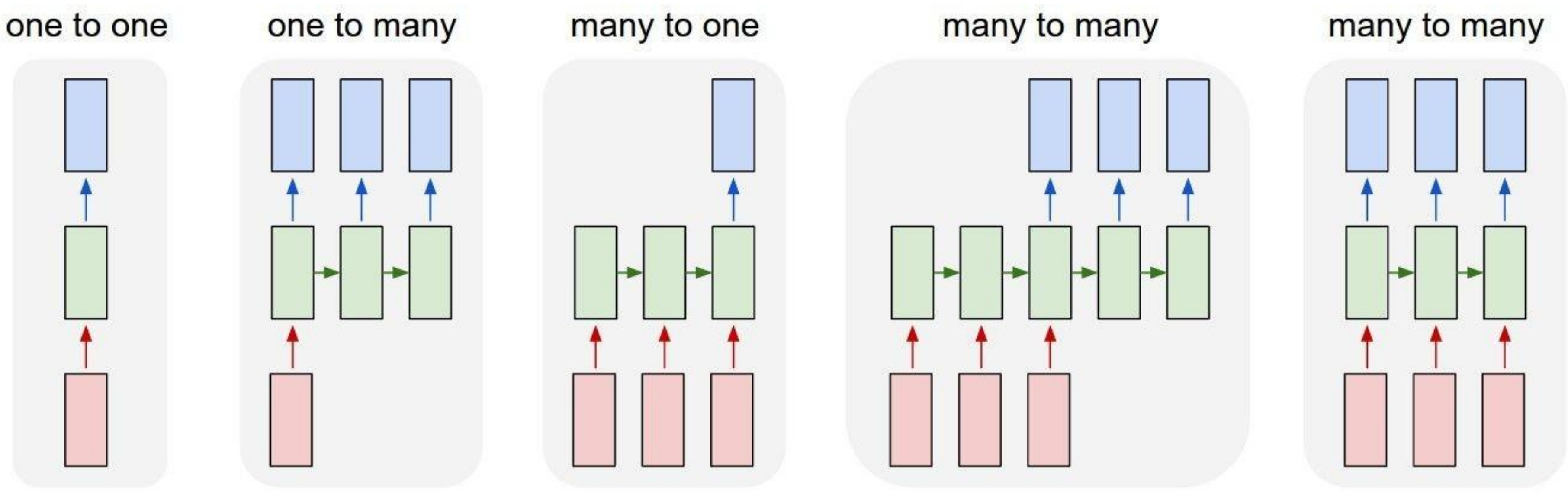
Karpathy and Fei-Fei, CVPR 2015

Recurrent Networks offer a lot of flexibility:



vanilla neural networks

Recurrent Networks offer a lot of flexibility:



e.g. **image captioning**
image -> sequence of words

Andrej Karpathy

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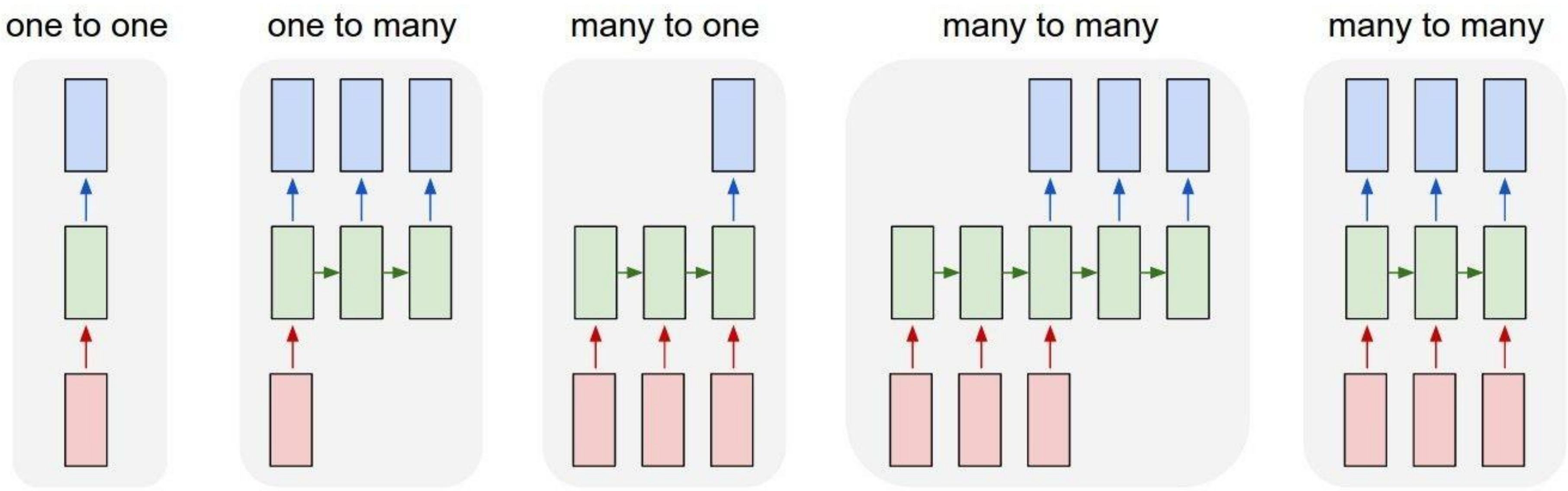
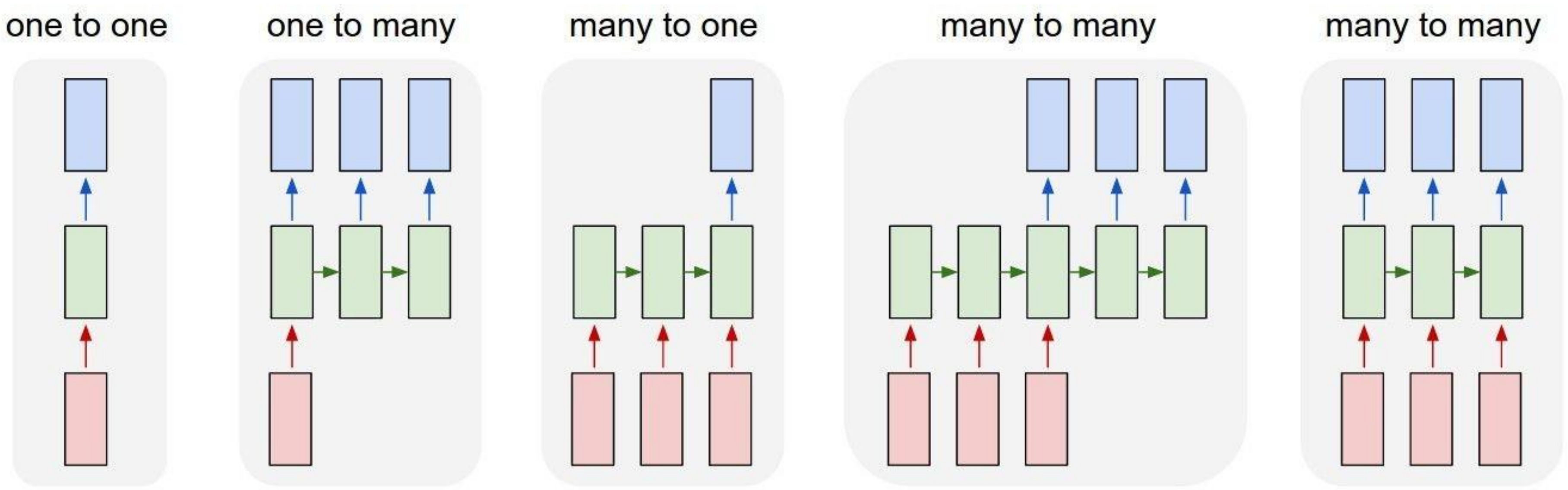


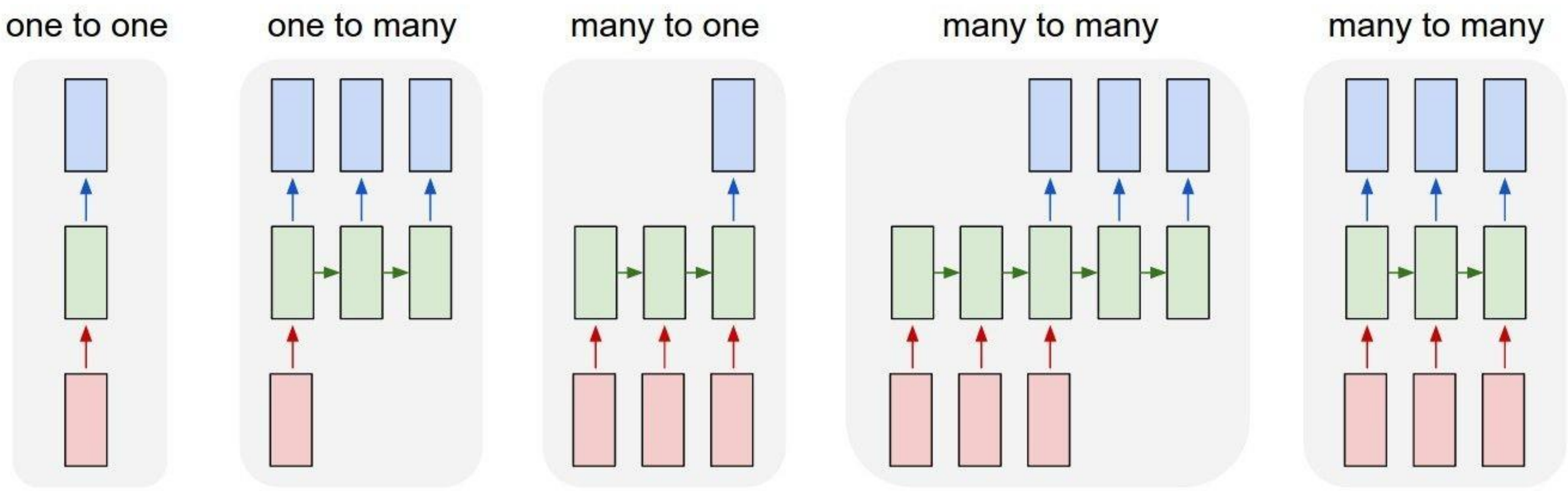
e.g. **sentiment classification**
sequence of words -> sentiment

Recurrent Networks offer a lot of flexibility:



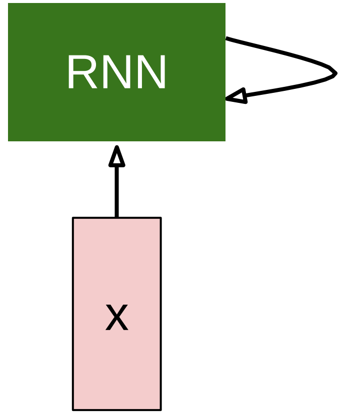
e.g. **machine translation**
seq of words -> seq of words

Recurrent Networks offer a lot of flexibility:



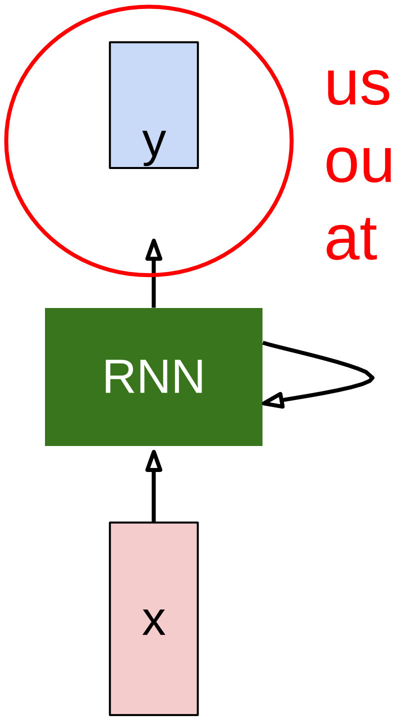
e.g. **video classification on frame level**

Recurrent Neural Network



Andrej Karpathy

Recurrent Neural Network



usually want to output a prediction at some time steps

Adapted from Andrej Karpathy

Recurrent Neural Network

We can process a sequence of vectors **x** by applying a recurrence formula at every time step:

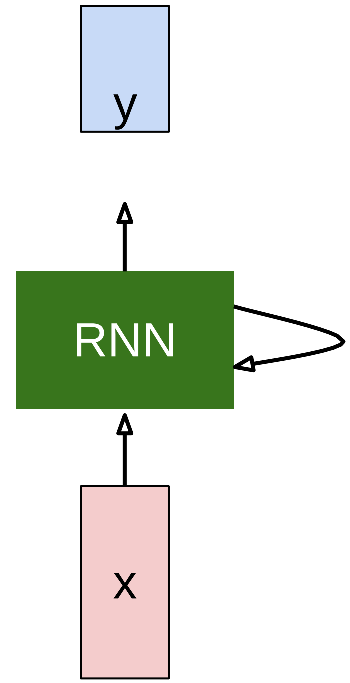
$$\boxed{h_t} = \boxed{f_W}(\boxed{h_{t-1}}, \boxed{x_t})$$

new state

old state

input vector at some time step

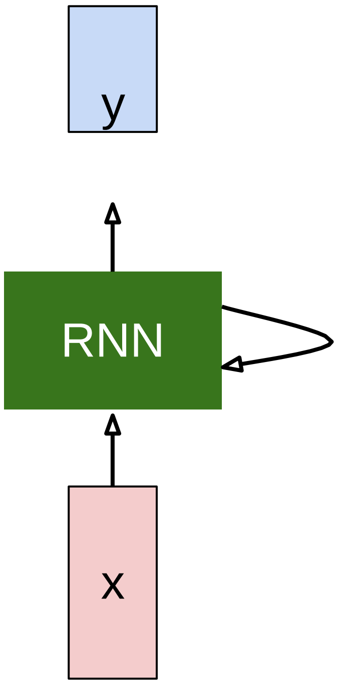
some function with parameters W



Recurrent Neural Network

We can process a sequence of vectors **x** by applying a recurrence formula at every time step:

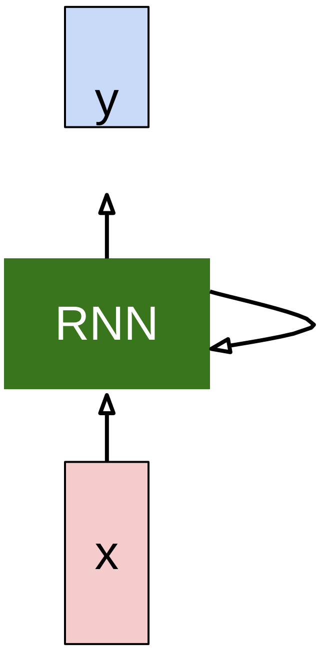
$$h_t = f_W(h_{t-1}, x_t)$$



Notice: the same function and the same set of parameters are used at every time step.

(Vanilla) Recurrent Neural Network

The state consists of a single *"hidden"* vector **h**:



$$h_t = f_W(h_{t-1}, x_t)$$

$$h_t = \tanh(W_{hh} h_{t-1} + W_{xh} x_t)$$

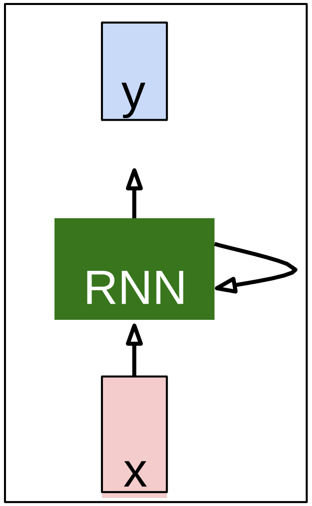
$$y_t = W_{hy} h_t$$

Example

Character-level language model example

Vocabulary:
[h,e,l,o]

Example training sequence:
“hello”



Example

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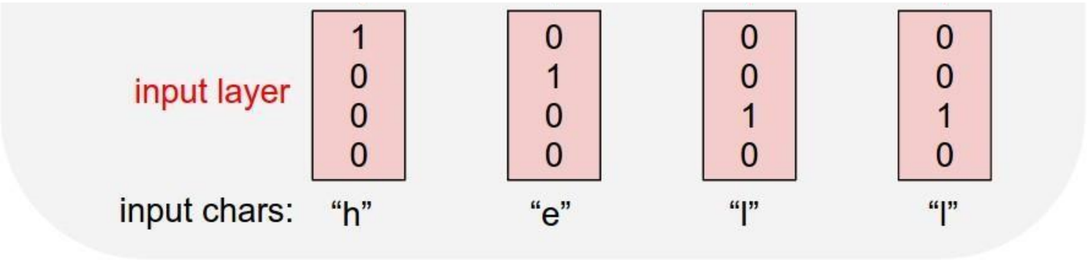


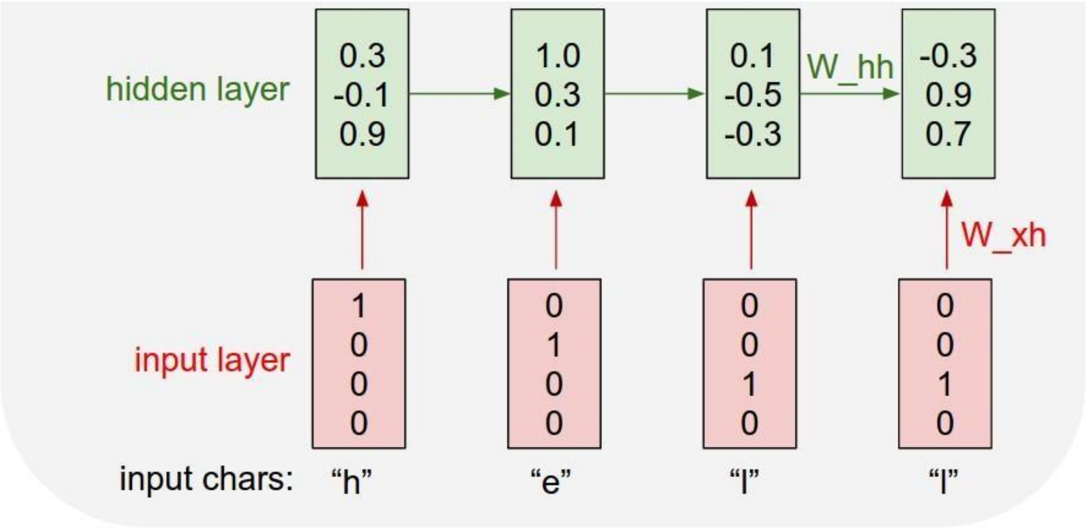
Example

Character-level language model example

Vocabulary: [h,e,l,o]

Example training sequence: **“hello”**

$$h_t = \tanh(W_{hh}h_{t-1} + W_{xh}x_t)$$



Example

Character-level language model example

Vocabulary:
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Example training sequence:
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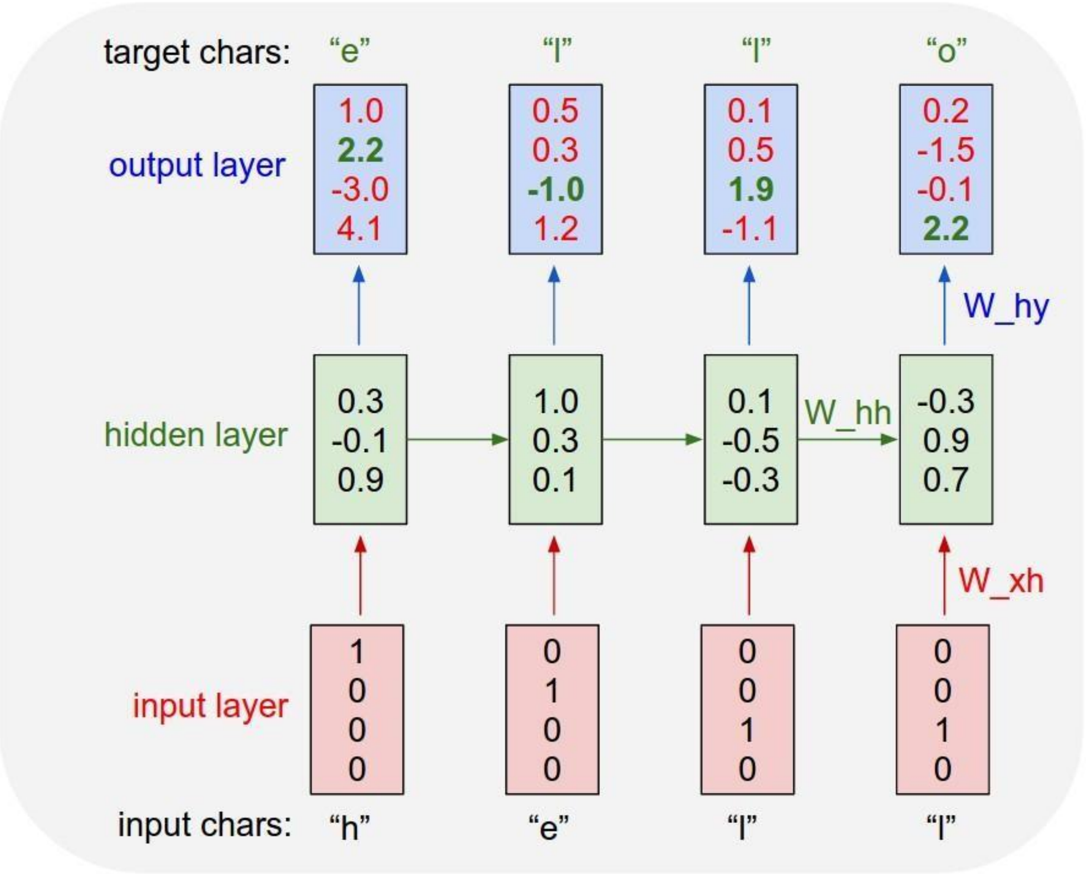


What do we still need to specify, for this to work?

What kind of loss can we formulate?

Training a Recurrent Neural Network

- Get a big corpus of text which is a sequence of words $\boldsymbol{x}^{(1)}, \ldots, \boldsymbol{x}^{(T)}$
- Feed into RNN; compute output distribution $\hat{\boldsymbol{y}}^{(t)}$ for *every step t.*
  - i.e. predict probability distribution of *every word*, given words so far

- Loss function on step *t* is cross-entropy between predicted probability distribution $\hat{\boldsymbol{y}}^{(t)}$, and true next word $\boldsymbol{y}^{(t)}$ (one-hot); V is vocabulary

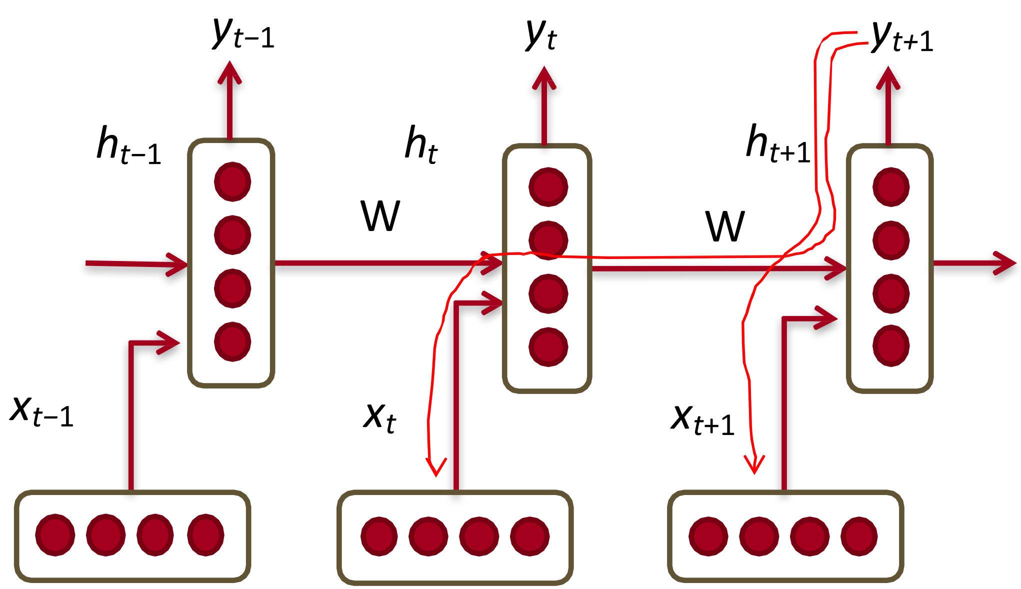
$$J^{(t)}(\theta) = CE(\boldsymbol{y}^{(t)}, \hat{\boldsymbol{y}}^{(t)}) = -\sum_{w \in V} \boldsymbol{y}_w^{(t)} \log \hat{\boldsymbol{y}}_w^{(t)} = -\log \hat{\boldsymbol{y}}_{\boldsymbol{x}_{t+1}}^{(t)}$$

- Average this to get overall loss for entire training set:

$$J(\theta) = \frac{1}{T} \sum_{t=1}^{T} J^{(t)}(\theta) = \frac{1}{T} \sum_{t=1}^{T} -\log \hat{\boldsymbol{y}}_{\boldsymbol{x}_{t+1}}^{(t)}$$

The vanishing/exploding gradient problem

- The error at a time step ideally can tell a previous time step from many steps away to change during backprop
- Multiply the same matrix at each time step during backprop



The vanishing gradient problem

- Total error is the sum of each error at time steps t

$$\frac{\partial E}{\partial W} = \sum_{t=1}^{T} \frac{\partial E_t}{\partial W}$$

- Chain rule:

$$\frac{\partial E_t}{\partial W} = \sum_{k=1}^{t} \frac{\partial E_t}{\partial y_t} \frac{\partial y_t}{\partial h_t} \frac{\partial h_t}{\partial h_k} \frac{\partial h_k}{\partial W}$$

- More chain rule:

$$\frac{\partial h_t}{\partial h_k} = \prod_{j=k+1}^{t} \frac{\partial h_j}{\partial h_{j-1}}$$

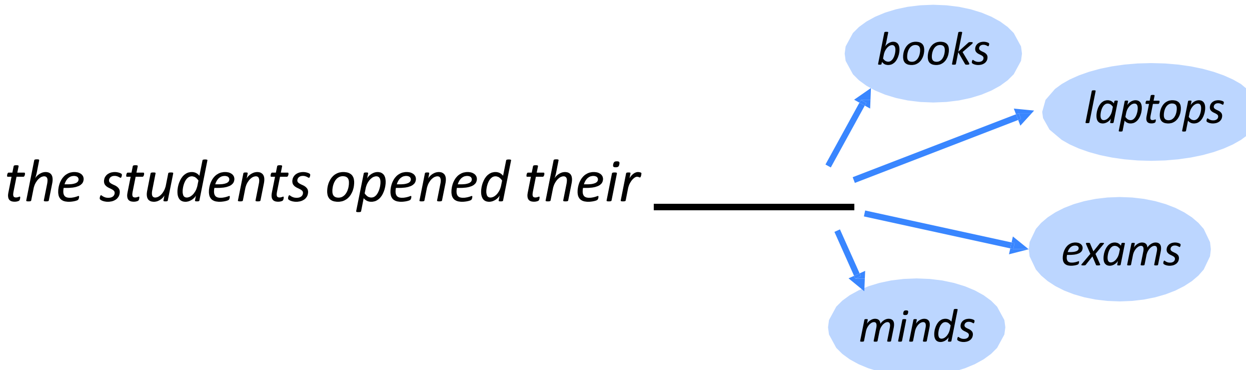
- Derivative of vector wrt vector is a Jacobian matrix of partial derivatives; norm of this matrix can become very small or very large quickly [Bengio et al 1994, Pascanu et al. 2013], leading to vanishing/exploding gradient

Adapted from Richard Socher

Now in more detail…

Language Modeling

- **Language Modeling** is the task of predicting what word comes next.



- More formally: given a sequence of words $\boldsymbol{x}^{(1)}, \boldsymbol{x}^{(2)}, \ldots, \boldsymbol{x}^{(t)}$, compute the probability distribution of the next word $\boldsymbol{x}^{(t+1)}$:

$$P(\boldsymbol{x}^{(t+1)} | \; \boldsymbol{x}^{(t)}, \ldots, \boldsymbol{x}^{(1)})$$

  where $\boldsymbol{x}^{(t+1)}$ can be any word in the vocabulary $V = \{\boldsymbol{w}_1, ..., \boldsymbol{w}_{|V|}\}$

- A system that does this is called a **Language Model**.

n-gram Language Models

- First we make a simplifying assumption: $\boldsymbol{x}^{(t+1)}$ depends only on the preceding *n-1* words.

$$P(\boldsymbol{x}^{(t+1)}|\boldsymbol{x}^{(t)},\ldots,\boldsymbol{x}^{(1)}) = P(\boldsymbol{x}^{(t+1)}|\overbrace{\boldsymbol{x}^{(t)},\ldots,\boldsymbol{x}^{(t-n+2)}}^{n\text{-1 words}})$$

(assumption)

prob of a n-gram

prob of a (n-1)-gram

$$= \frac{\boxed{P(\boldsymbol{x}^{(t+1)},\boldsymbol{x}^{(t)},\ldots,\boldsymbol{x}^{(t-n+2)})}}{\boxed{P(\boldsymbol{x}^{(t)},\ldots,\boldsymbol{x}^{(t-n+2)})}}$$

(definition of conditional prob)

- **<u>Question:</u>** How do we get these *n*-gram and (*n*-1)-gram probabilities?
- **<u>Answer:</u>** By counting them in some large corpus of text!

$$\approx \frac{\text{count}(\boldsymbol{x}^{(t+1)},\boldsymbol{x}^{(t)},\ldots,\boldsymbol{x}^{(t-n+2)})}{\text{count}(\boldsymbol{x}^{(t)},\ldots,\boldsymbol{x}^{(t-n+2)})}$$

(statistical approximation)

Sparsity Problems with n-gram Language Models

Sparsity Problem 1

Problem: What if *"students opened their $\boldsymbol{w}$"* never occurred in data? Then $\boldsymbol{w}$ has probability 0!

(Partial) Solution: Add small δ to the count for every $\boldsymbol{w} \in V$. This is called *smoothing*.

$$P(\boldsymbol{w}|\text{students opened their}) = \frac{\boxed{\text{count(students opened their } \boldsymbol{w})}}{\boxed{\text{count(students opened their)}}}$$

Sparsity Problem 2

Problem: What if *"students opened their"* never occurred in data? Then we can't calculate probability for *any* $\boldsymbol{w}$!

(Partial) Solution: Just condition on *"opened their"* instead. This is called *backoff*.

Note: Increasing *n* makes sparsity problems *worse.* Typically we can't have *n* bigger than 5.

A fixed-window neural Language Model

output distribution

$$\hat{\boldsymbol{y}} = \mathrm{softmax}(\boldsymbol{U}\boldsymbol{h} + \boldsymbol{b}_2) \in \mathbb{R}^{|V|}$$

hidden layer

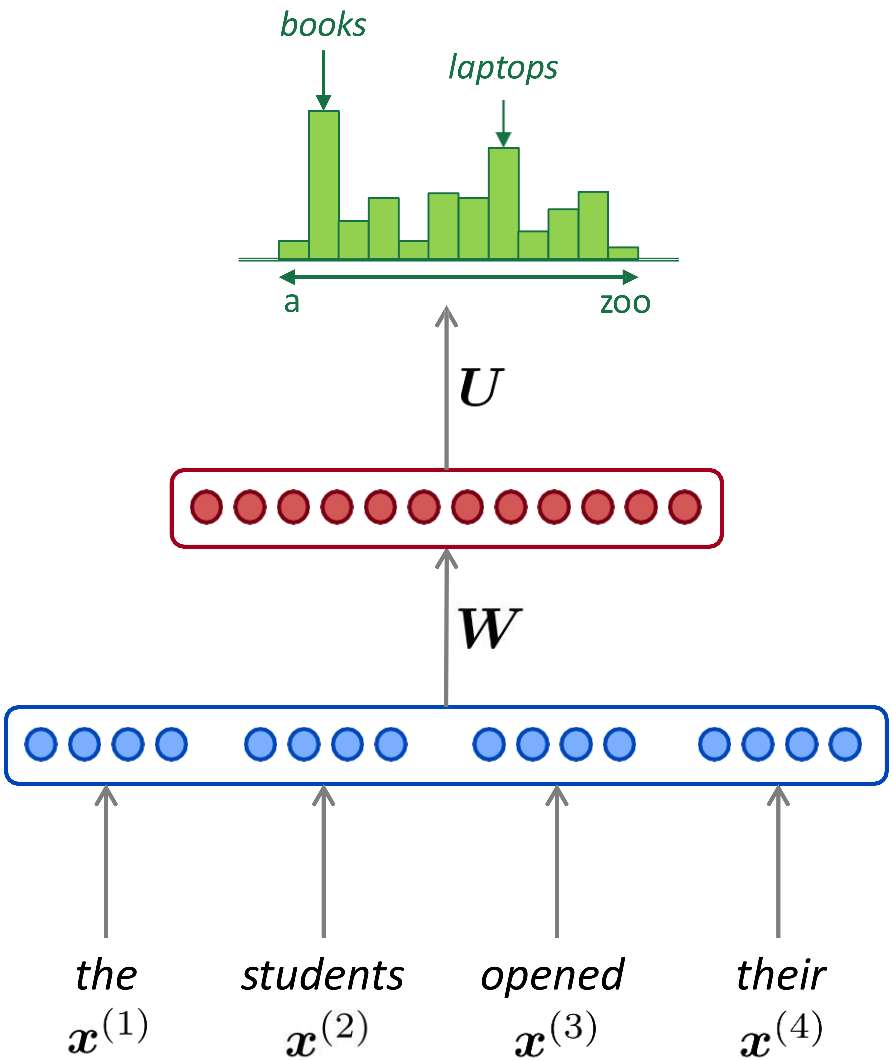
$$\boldsymbol{h} = f(\boldsymbol{W}\boldsymbol{e} + \boldsymbol{b}_1)$$

concatenated word embeddings

$$\boldsymbol{e} = [\boldsymbol{e}^{(1)}; \boldsymbol{e}^{(2)}; \boldsymbol{e}^{(3)}; \boldsymbol{e}^{(4)}]$$

words / one-hot vectors

$$\boldsymbol{x}^{(1)}, \boldsymbol{x}^{(2)}, \boldsymbol{x}^{(3)}, \boldsymbol{x}^{(4)}$$



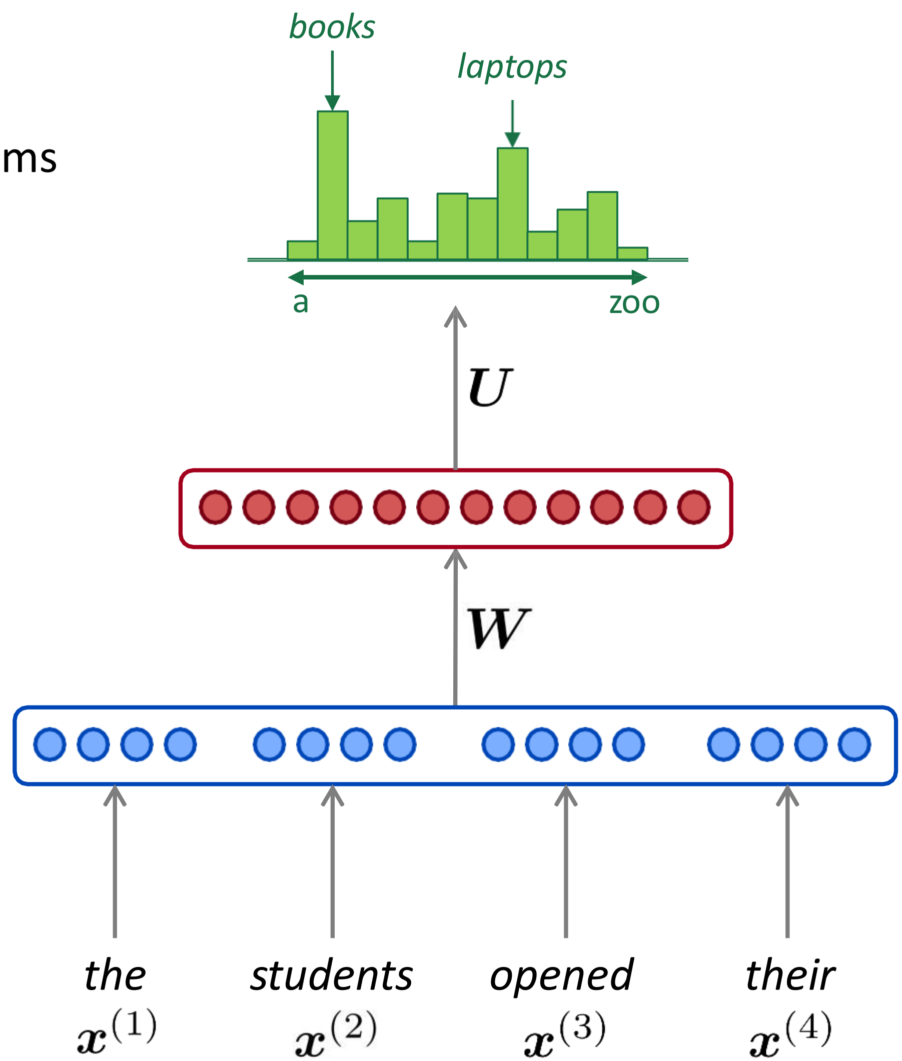
A fixed-window neural Language Model

Improvements over *n*-gram LM:
- No sparsity problem
- Don't need to store all observed *n*-grams

Remaining **problems**:
- Fixed window is too small
- Enlarging window enlarges $\boldsymbol{W}$
- Window can never be large enough!

- $\boldsymbol{x}^{(1)}$ and $\boldsymbol{x}^{(2)}$ are multiplied by completely different weights in $\boldsymbol{W}$. No symmetry in how the inputs are processed.

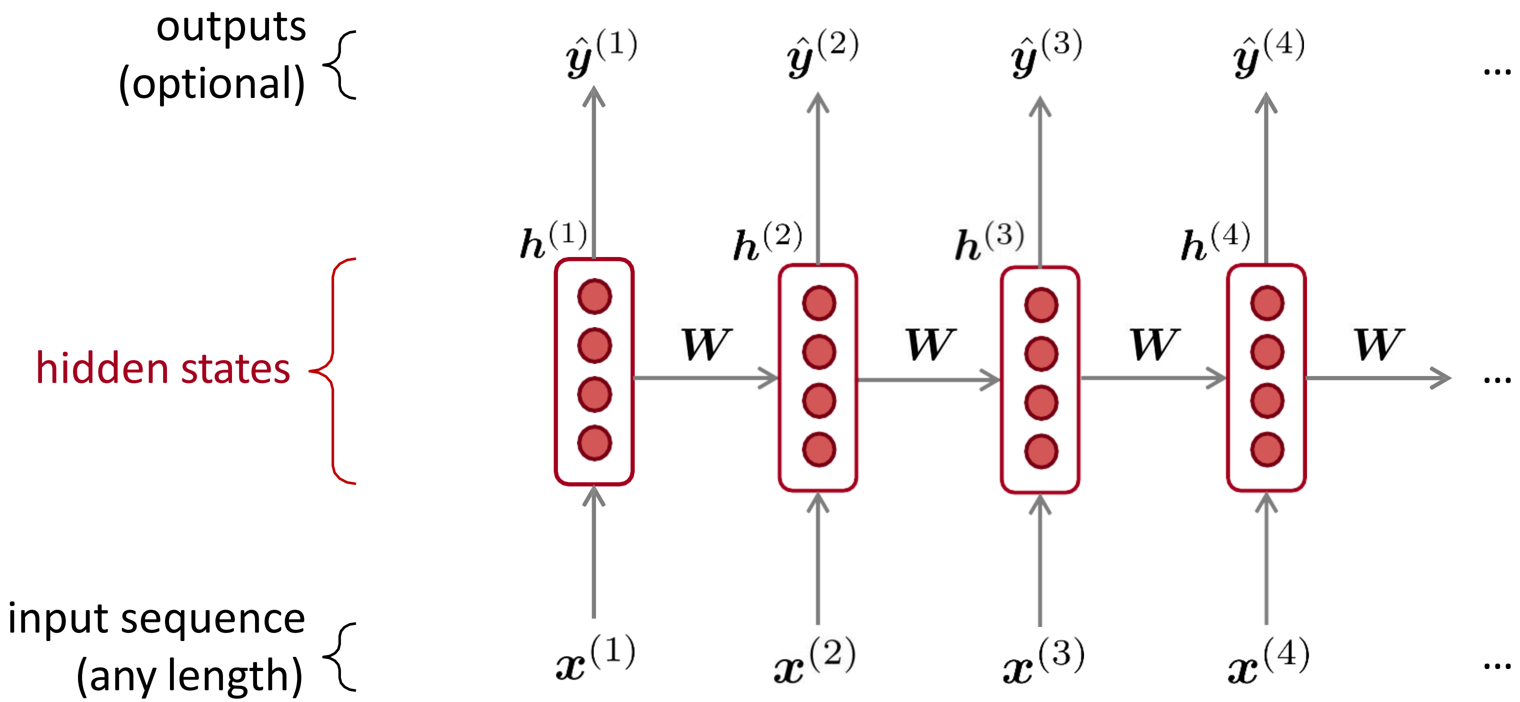
We need a neural architecture that can process *any length input*



Recurrent Neural Networks (RNN)

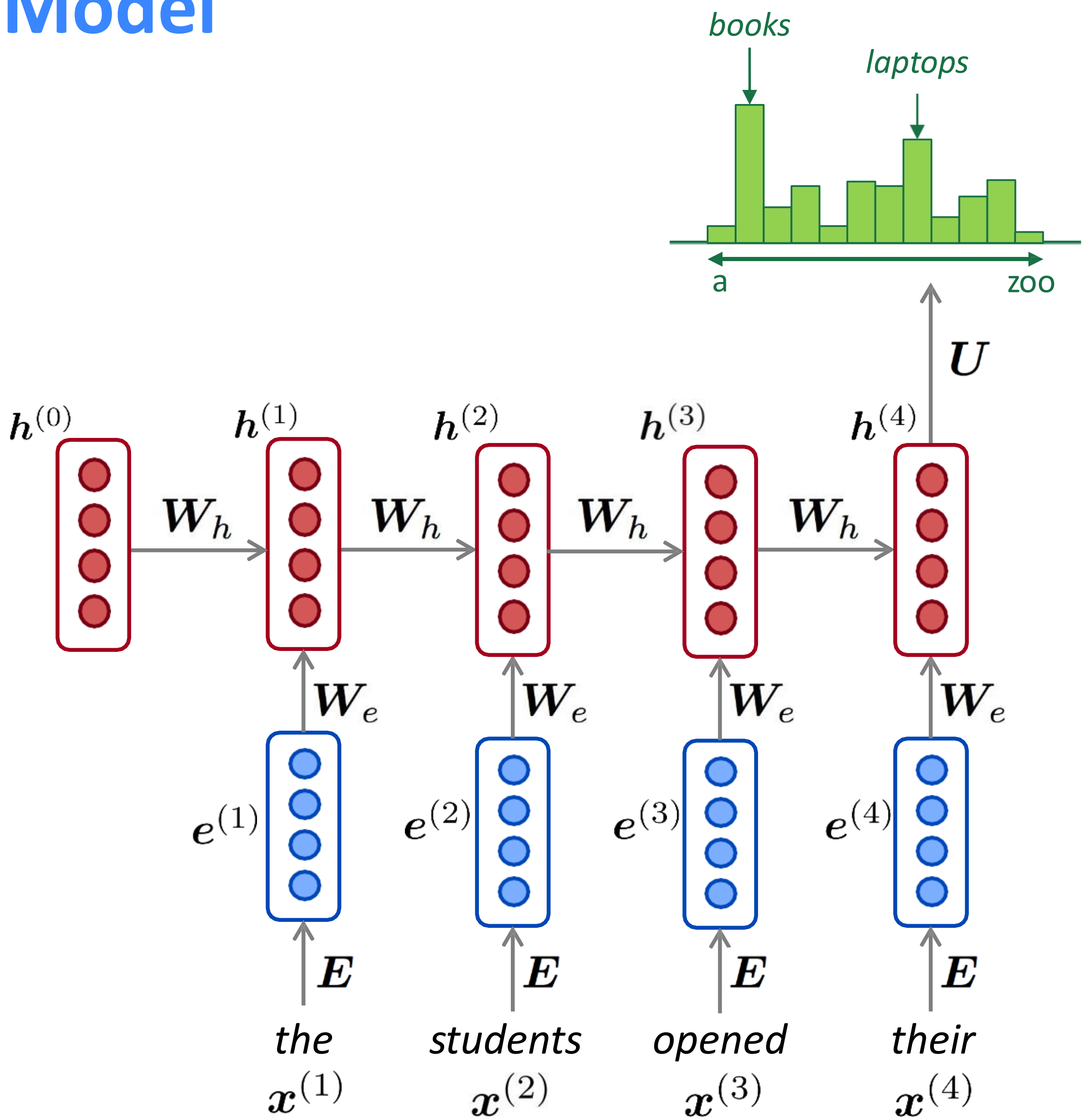
A family of neural architectures

Core idea: Apply the same weights $\boldsymbol{W}$ *repeatedly*



A RNN Language Model

$$\hat{\boldsymbol{y}}^{(4)} = P(\boldsymbol{x}^{(5)}|\text{the students opened their})$$



output distribution

$$\hat{\boldsymbol{y}}^{(t)} = \text{softmax}\left(\boldsymbol{U}\boldsymbol{h}^{(t)} + \boldsymbol{b}_2\right) \in \mathbb{R}^{|V|}$$

hidden states

$$\boldsymbol{h}^{(t)} = \sigma\left(\boldsymbol{W}_h\boldsymbol{h}^{(t-1)} + \boldsymbol{W}_e\boldsymbol{e}^{(t)} + \boldsymbol{b}_1\right)$$

$\boldsymbol{h}^{(0)}$ is the initial hidden state

word embeddings

$$\boldsymbol{e}^{(t)} = \boldsymbol{E}\boldsymbol{x}^{(t)}$$

words / one-hot vectors

$$\boldsymbol{x}^{(t)} \in \mathbb{R}^{|V|}$$

***Note**: this input sequence could be much longer, but this slide doesn't have space!*

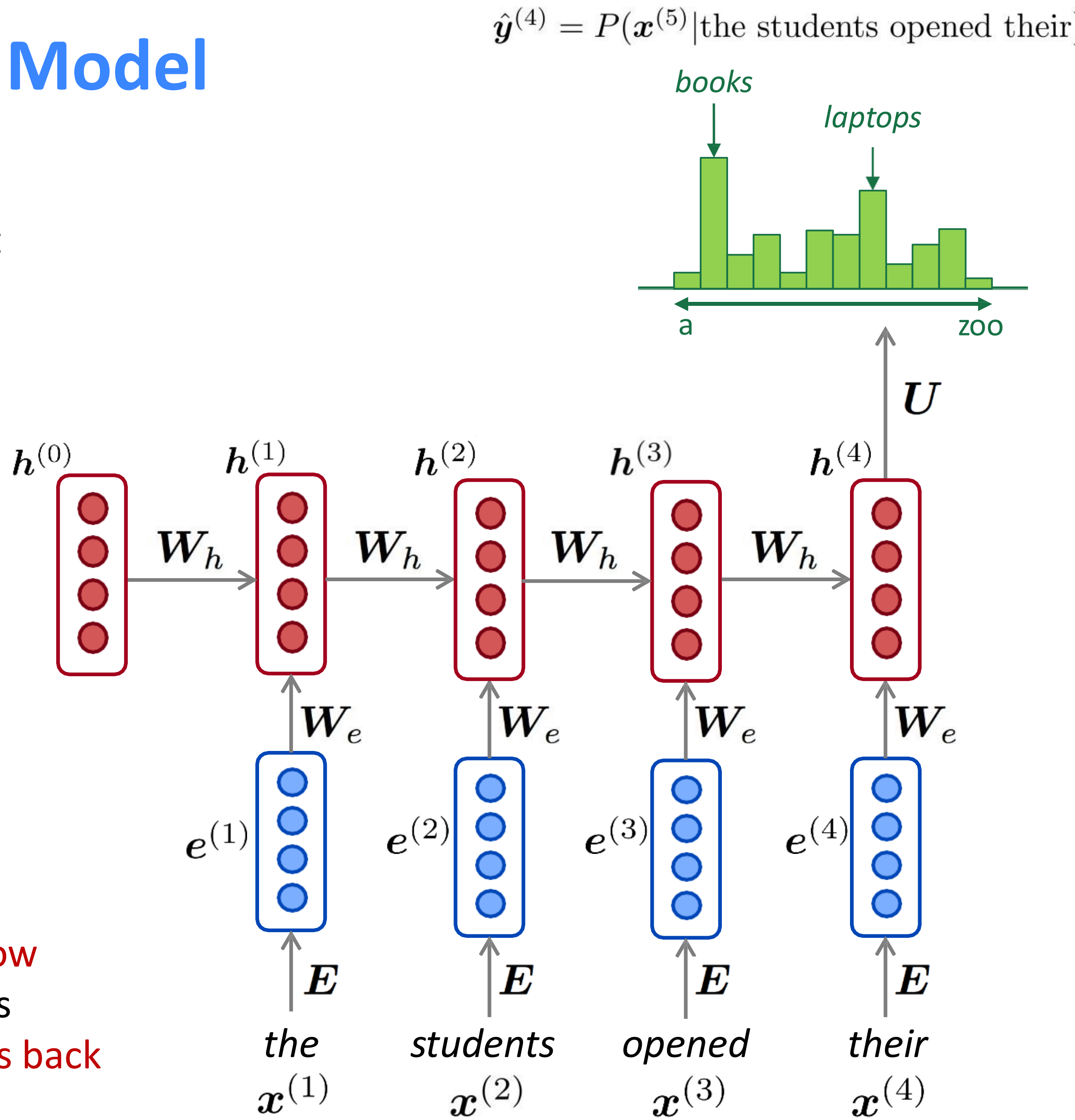
A RNN Language Model

RNN **Advantages**:

- Can process any length input
- Computation for step *t* can (in theory) use information from many steps back
- Model size doesn't increase for longer input
- Same weights applied on every timestep, so there is symmetry in how inputs are processed

RNN **Disadvantages**:

- Recurrent computation is slow
- In practice, difficult to access information from many steps back



Abigail See

Recall: Training a RNN Language Model

- Get a big corpus of text which is a sequence of words $\boldsymbol{x}^{(1)}, \ldots, \boldsymbol{x}^{(T)}$
- Feed into RNN-LM; compute output distribution $\hat{\boldsymbol{y}}^{(t)}$ for *every step t.*
  - i.e. predict probability distribution of *every word*, given words so far

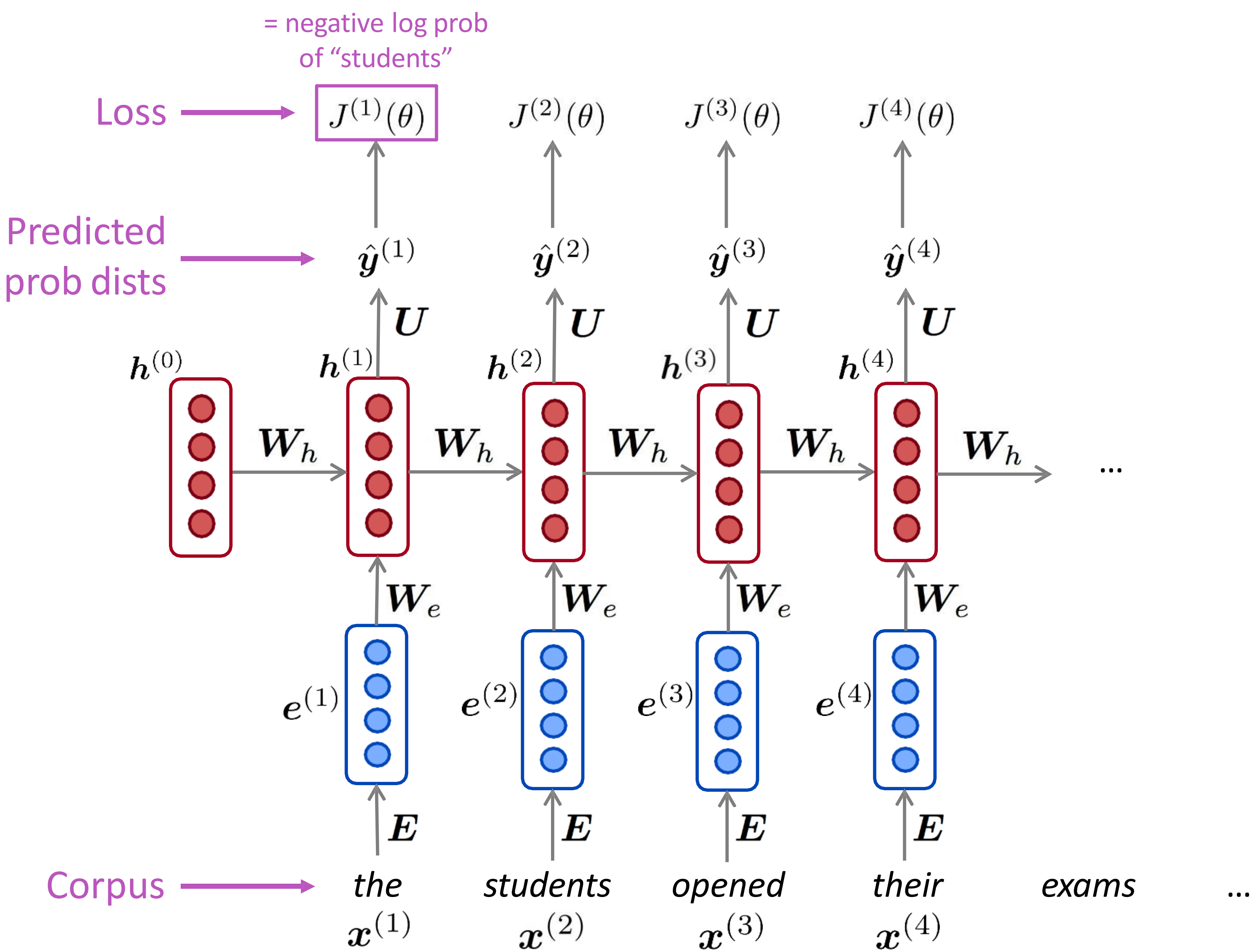
- Loss function on step *t* is cross-entropy between predicted probability distribution $\hat{\boldsymbol{y}}^{(t)}$, and the true next word $\boldsymbol{y}^{(t)}$ (one-hot for $\boldsymbol{x}^{(t+1)}$):

$$J^{(t)}(\theta) = CE(\boldsymbol{y}^{(t)}, \hat{\boldsymbol{y}}^{(t)}) = -\sum_{w \in V} \boldsymbol{y}_w^{(t)} \log \hat{\boldsymbol{y}}_w^{(t)} = -\log \hat{\boldsymbol{y}}_{\boldsymbol{x}_{t+1}}^{(t)}$$

- Average this to get overall loss for entire training set:

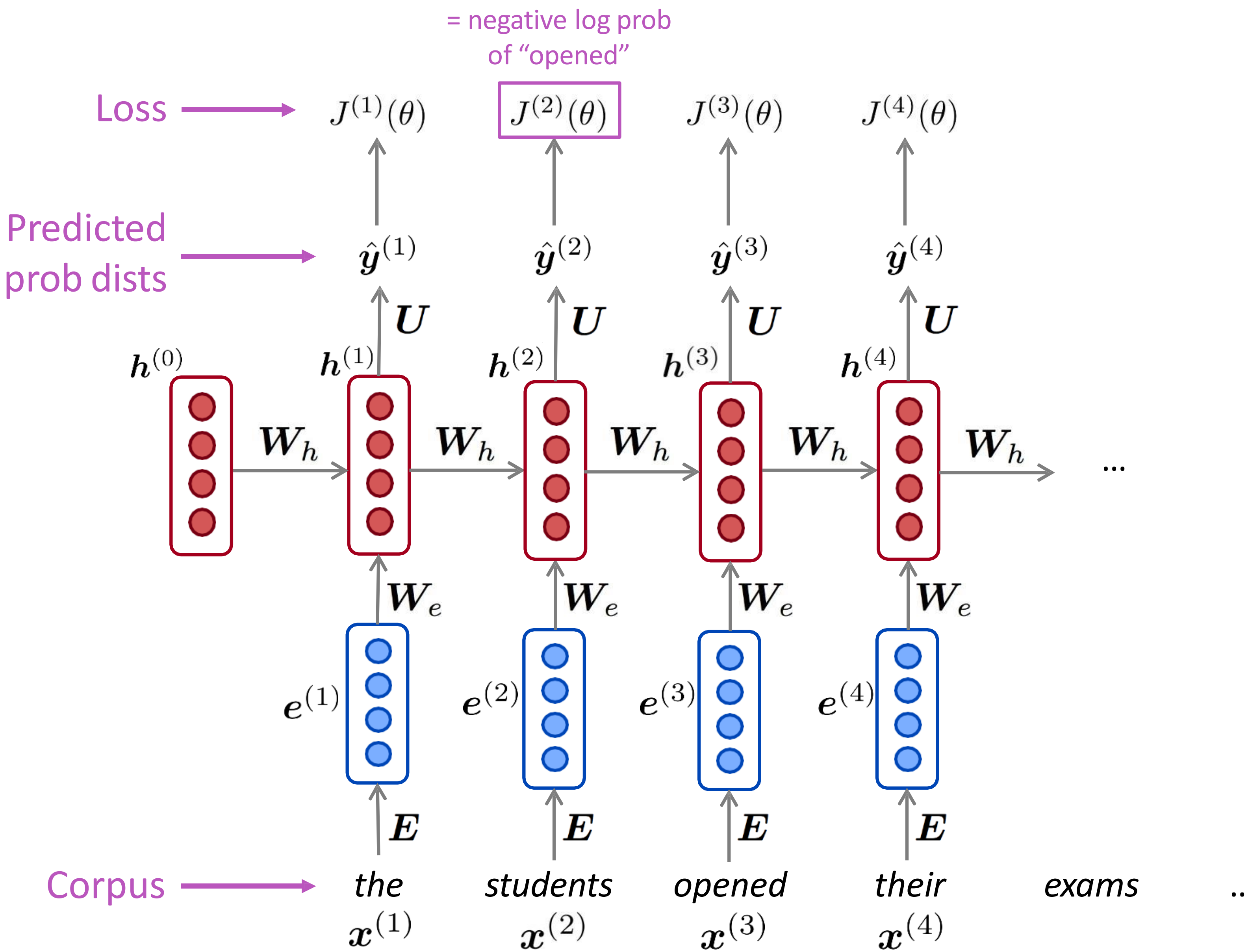
$$J(\theta) = \frac{1}{T} \sum_{t=1}^{T} J^{(t)}(\theta) = \frac{1}{T} \sum_{t=1}^{T} -\log \hat{\boldsymbol{y}}_{\boldsymbol{x}_{t+1}}^{(t)}$$

Training a RNN Language Model



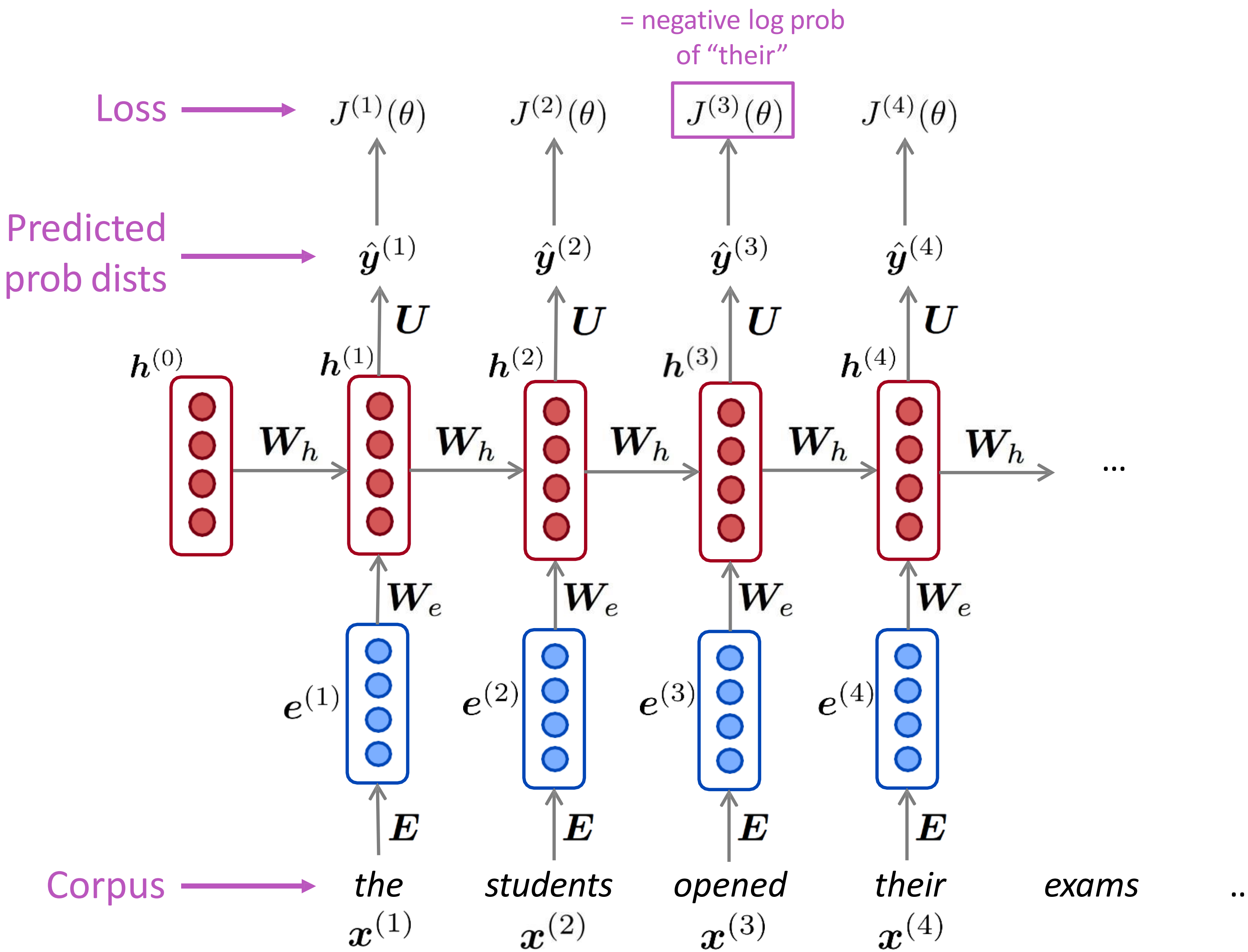
Abigail See

Training a RNN Language Model



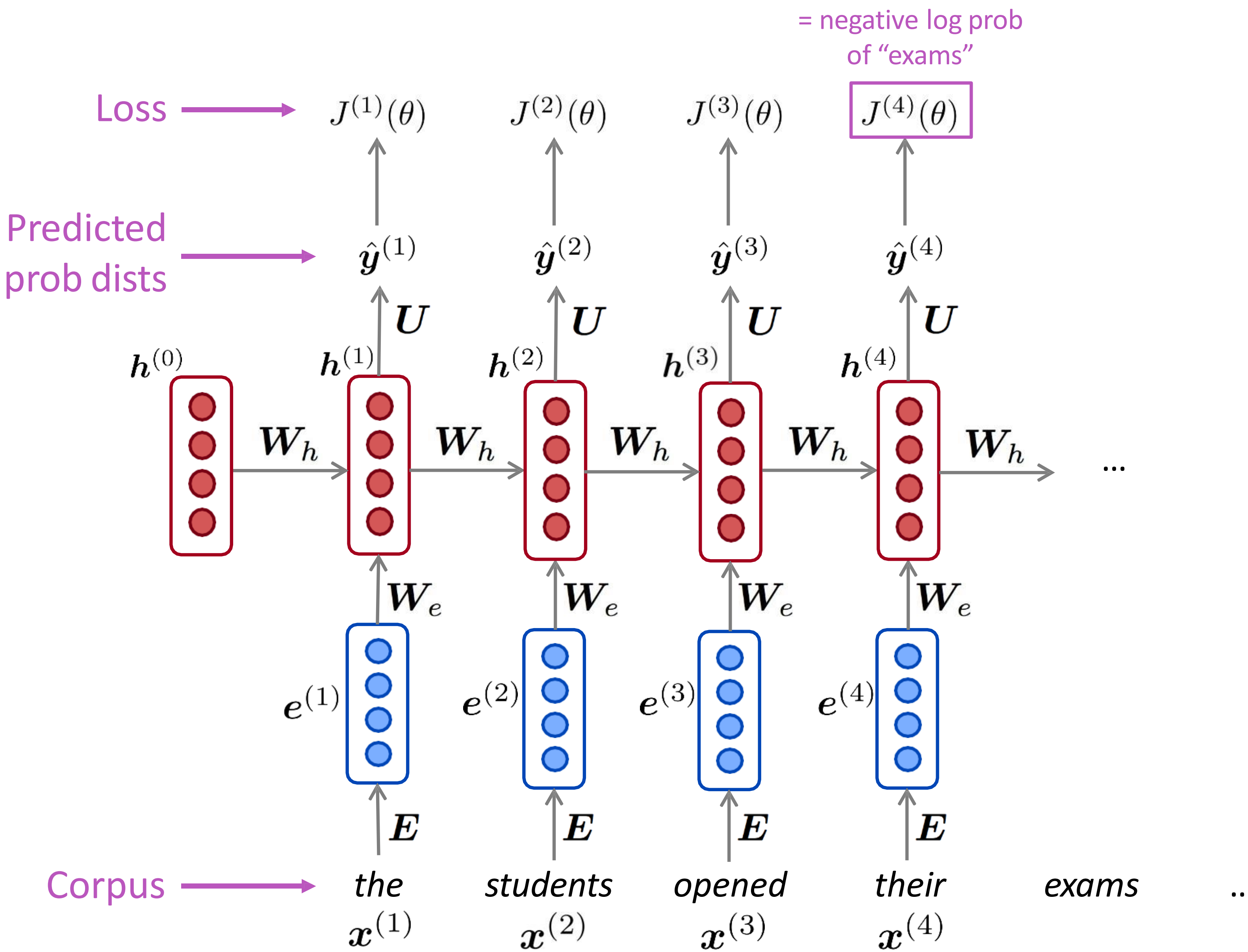
Abigail See

Training a RNN Language Model



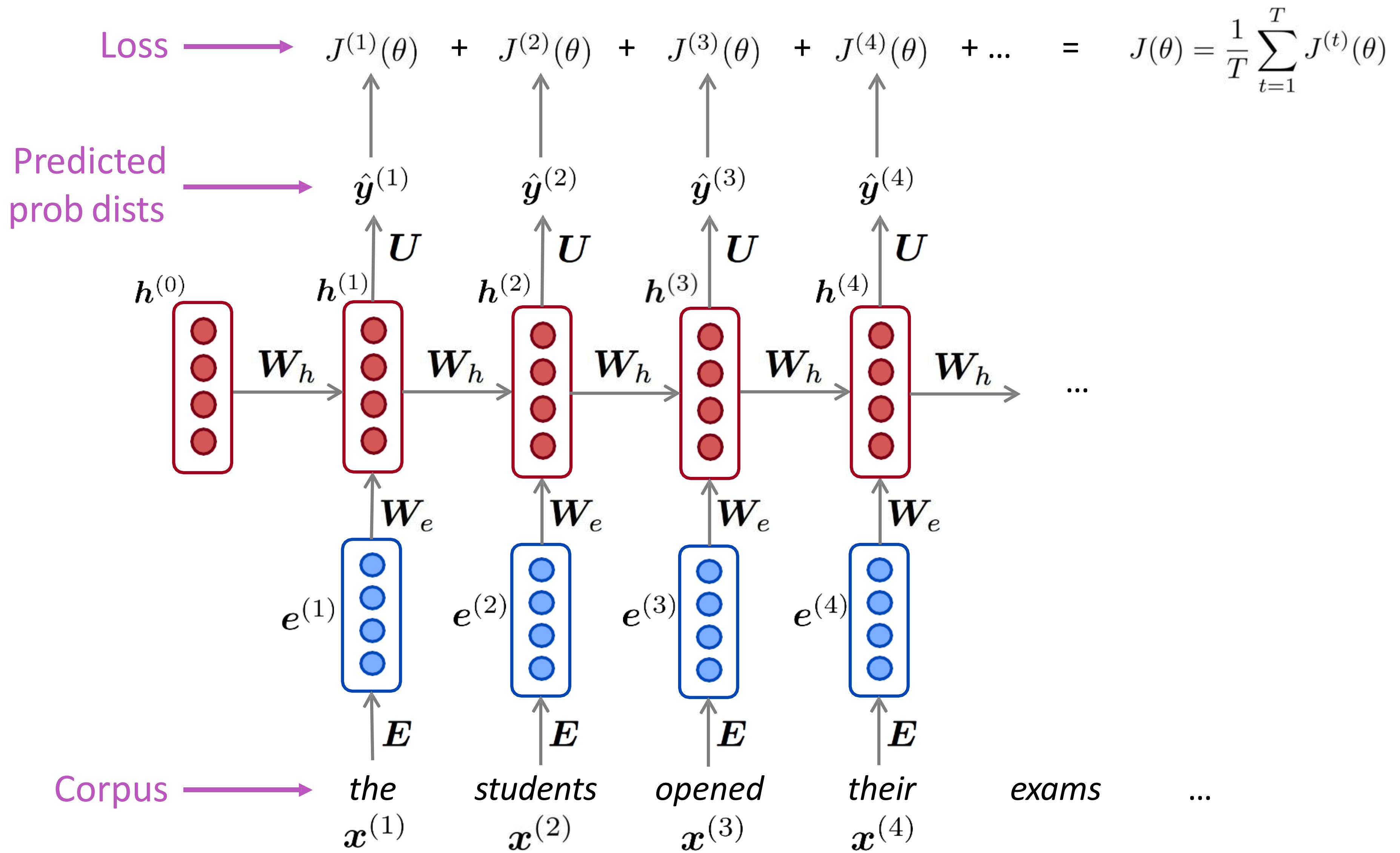
Abigail See

Training a RNN Language Model

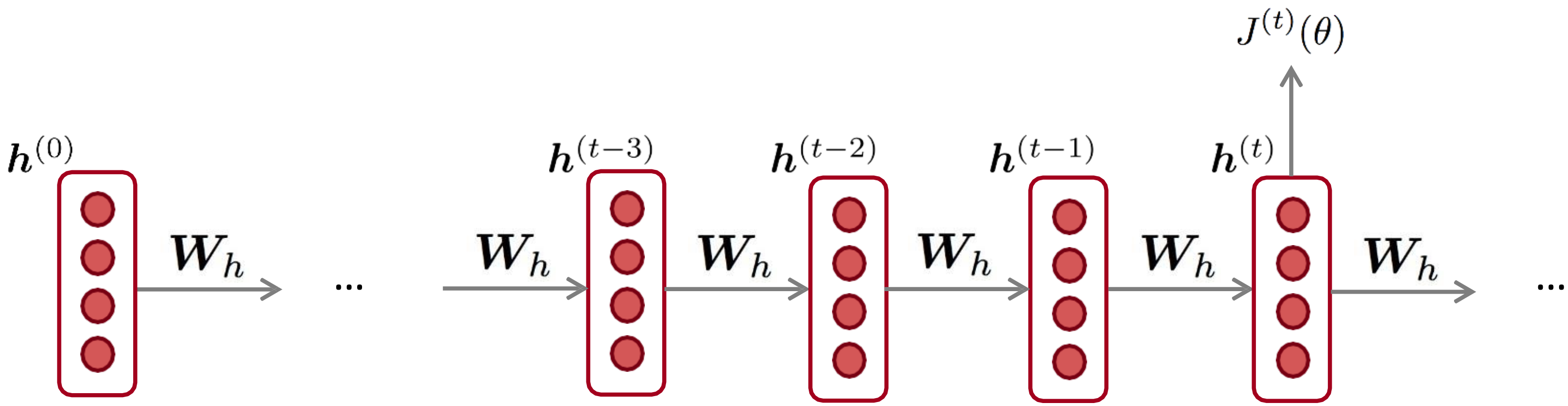


Abigail See

Training a RNN Language Model



Backpropagation for RNNs



Question: What's the derivative of $J^{(t)}(\theta)$ w.r.t. the repeated weight matrix $\boldsymbol{W}_h$?

Answer: $$\frac{\partial J^{(t)}}{\partial \boldsymbol{W_h}} = \sum_{i=1}^{t} \left. \frac{\partial J^{(t)}}{\partial \boldsymbol{W_h}} \right|_{(i)}$$

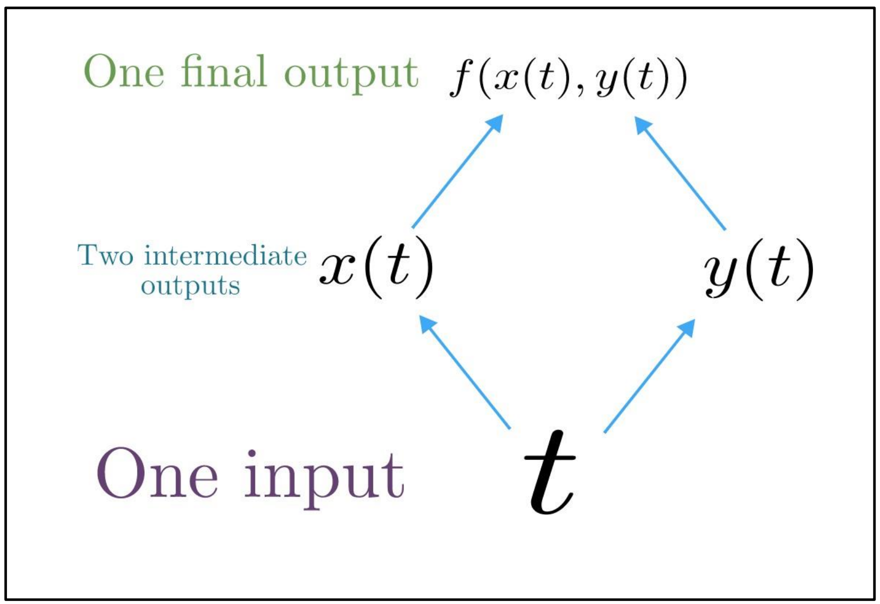
"The gradient w.r.t. a repeated weight is the sum of the gradient w.r.t. each time it appears"

Abigail See

Multivariable Chain Rule

- Given a multivariable function $f(x, y)$, and two single variable functions $x(t)$ and $y(t)$, here's what the multivariable chain rule says:

$$\underbrace{\frac{d}{dt} f(x(t), y(t))}_{\text{Derivative of composition function}} = \frac{\partial f}{\partial x}\frac{dx}{dt} + \frac{\partial f}{\partial y}\frac{dy}{dt}$$



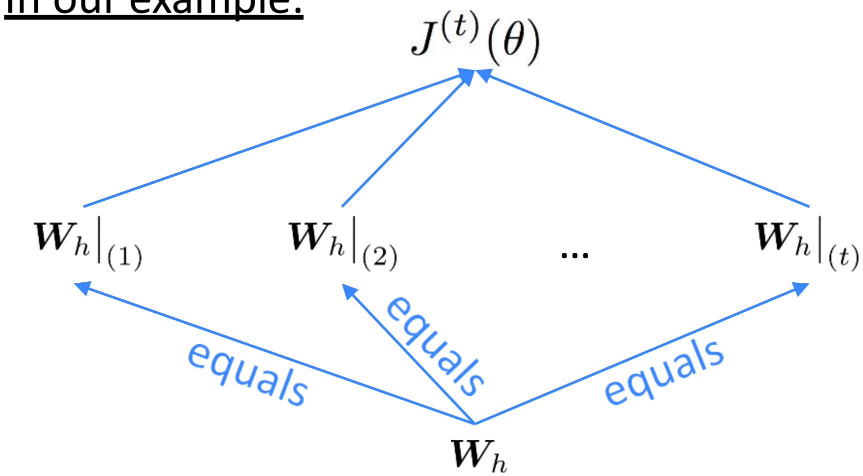
Source:
https://www.khanacademy.org/math/multivariable-calculus/multivariable-derivatives/differentiating-vector-valued-functions/a/multivariable-chain-rule-simple-version

Backpropagation for RNNs: Proof sketch

- Given a multivariable function $f(x, y)$, and two single variable functions $x(t)$ and $y(t)$, here's what the multivariable chain rule says:

$$\underbrace{\frac{d}{dt} f(x(t), y(t))}_{\text{Derivative of composition function}} = \frac{\partial f}{\partial x}\frac{dx}{dt} + \frac{\partial f}{\partial y}\frac{dy}{dt}$$

<u>In our example:</u>



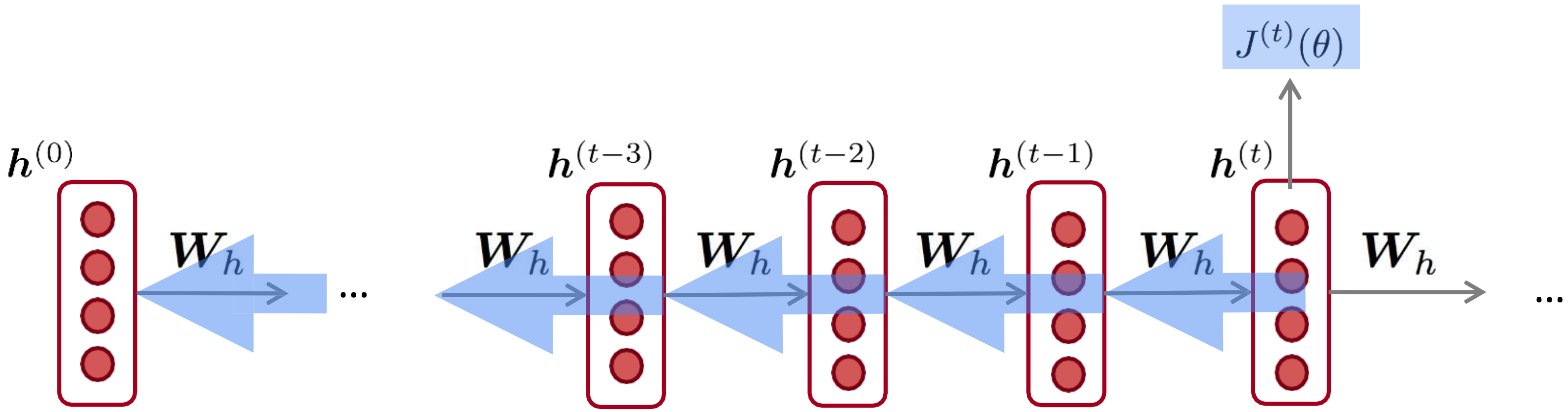
<u>Apply the multivariable chain rule:</u>

$$\frac{\partial J^{(t)}}{\partial \boldsymbol{W}_h} = \sum_{i=1}^{t} \frac{\partial J^{(t)}}{\partial \boldsymbol{W}_h}\bigg|_{(i)} \overset{= 1}{\boxed{\frac{\partial \boldsymbol{W}_h\big|_{(i)}}{\partial \boldsymbol{W}_h}}}$$

$$= \sum_{i=1}^{t} \frac{\partial J^{(t)}}{\partial \boldsymbol{W}_h}\bigg|_{(i)}$$

<u>Source:</u>
https://www.khanacademy.org/math/multivariable-calculus/multivariable-derivatives/differentiating-vector-valued-functions/a/multivariable-chain-rule-simple-version

Backpropagation for RNNs

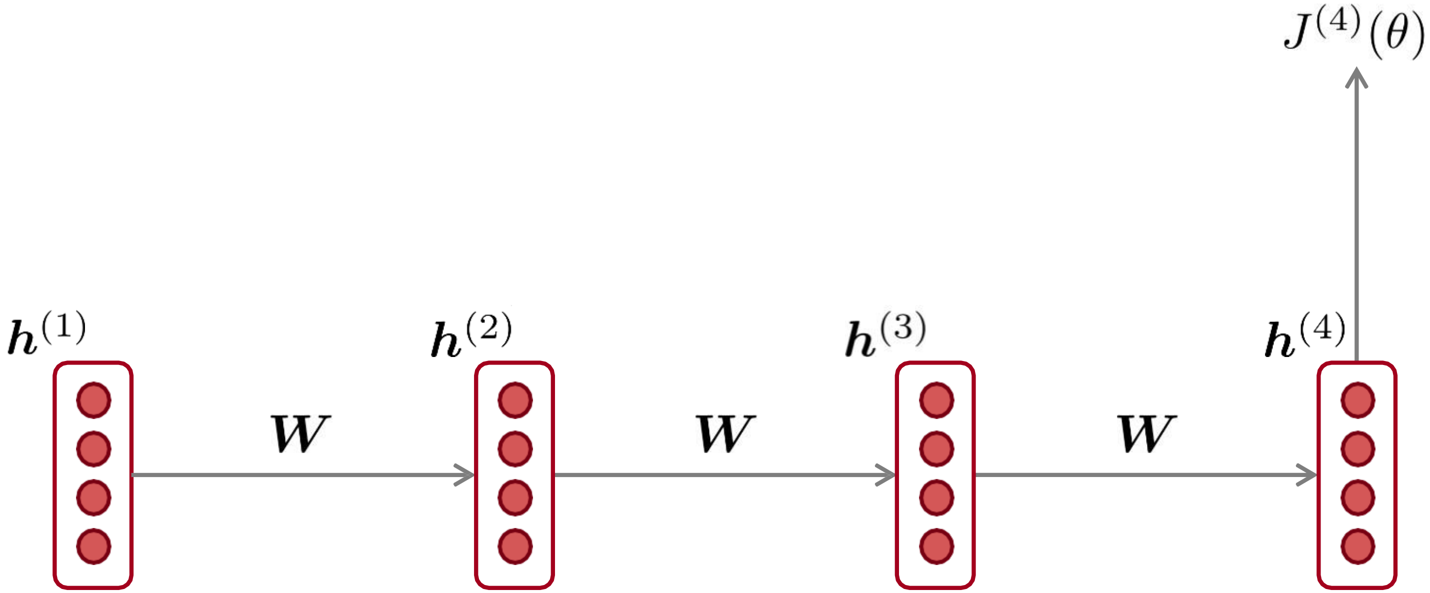


$$\frac{\partial J^{(t)}}{\partial \boldsymbol{W_h}} = \boxed{\sum_{i=1}^{t} \left. \frac{\partial J^{(t)}}{\partial \boldsymbol{W_h}} \right|_{(i)}}$$

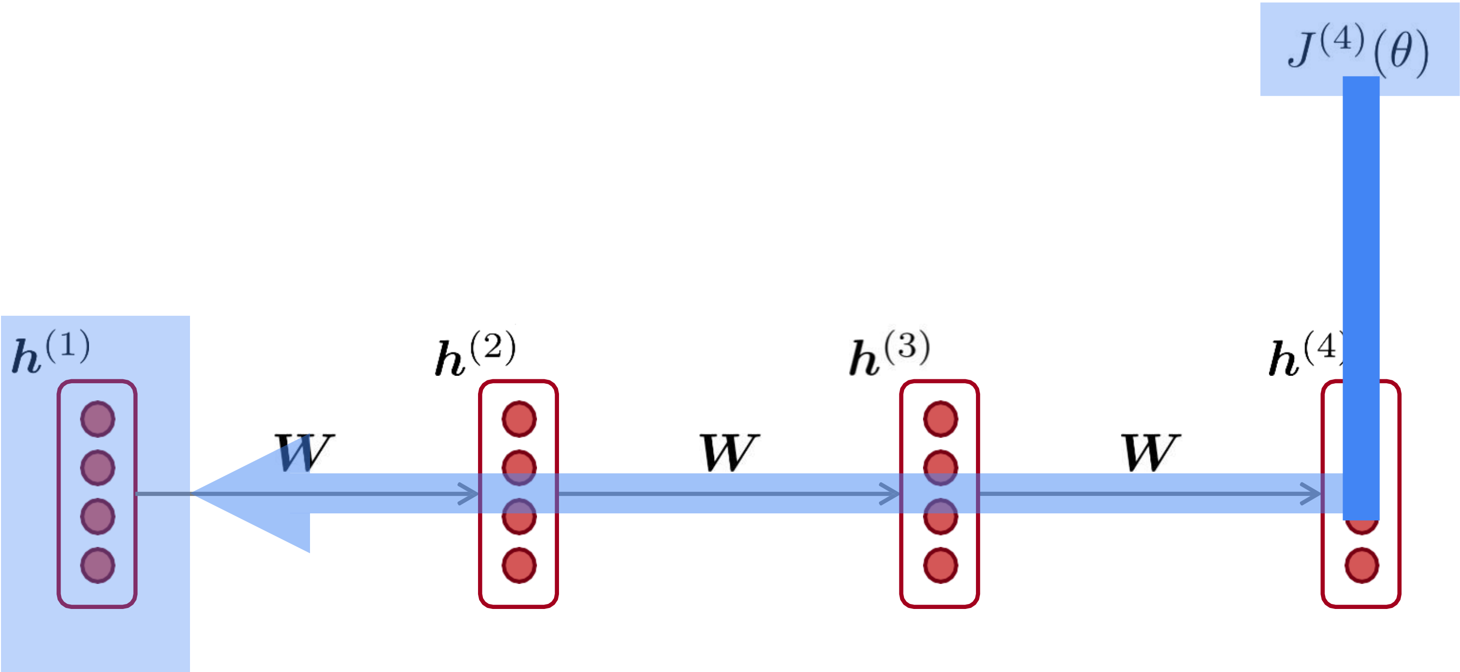
Question: How do we calculate this?

Answer: Backpropagate over timesteps *i=t,…,*0, summing gradients as you go.
This algorithm is called **"backpropagation through time"**

Vanishing gradient intuition

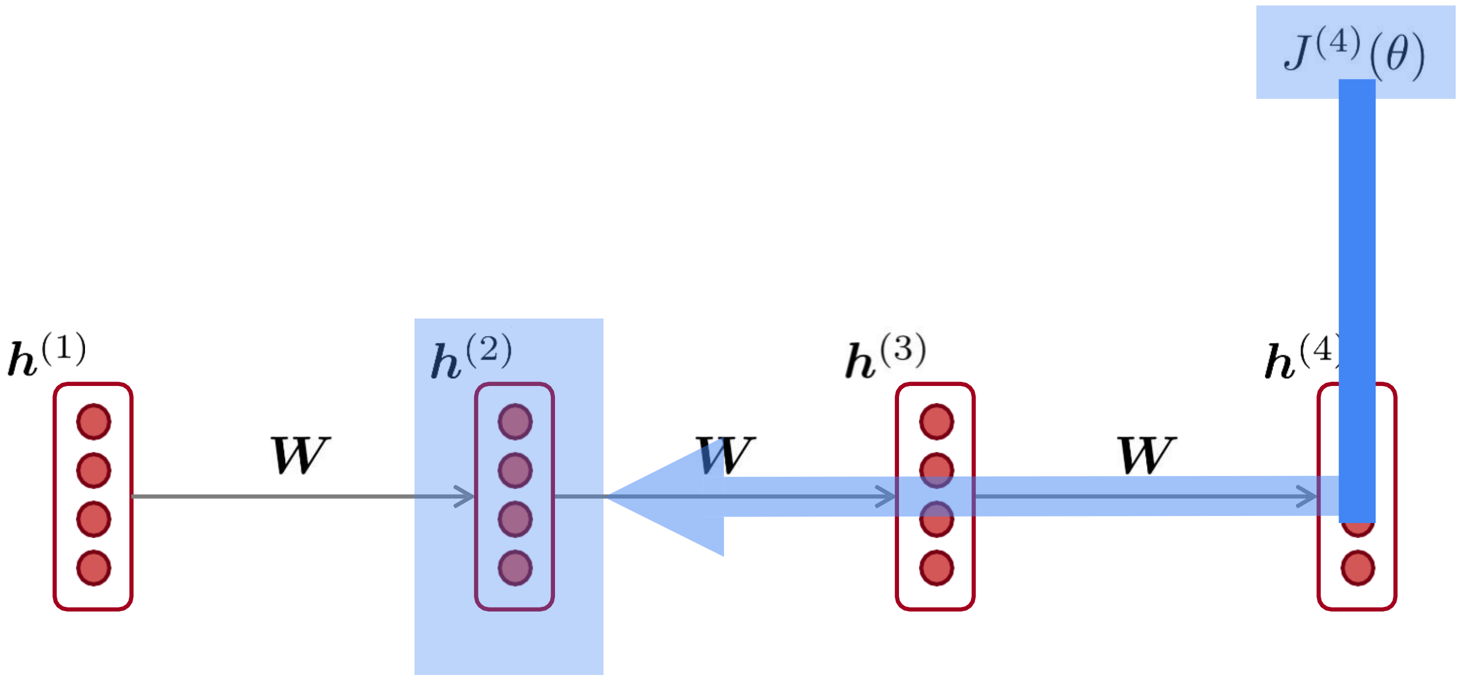


Vanishing gradient intuition



$$\frac{\partial J^{(4)}}{\partial \boldsymbol{h}^{(1)}} = \ ?$$

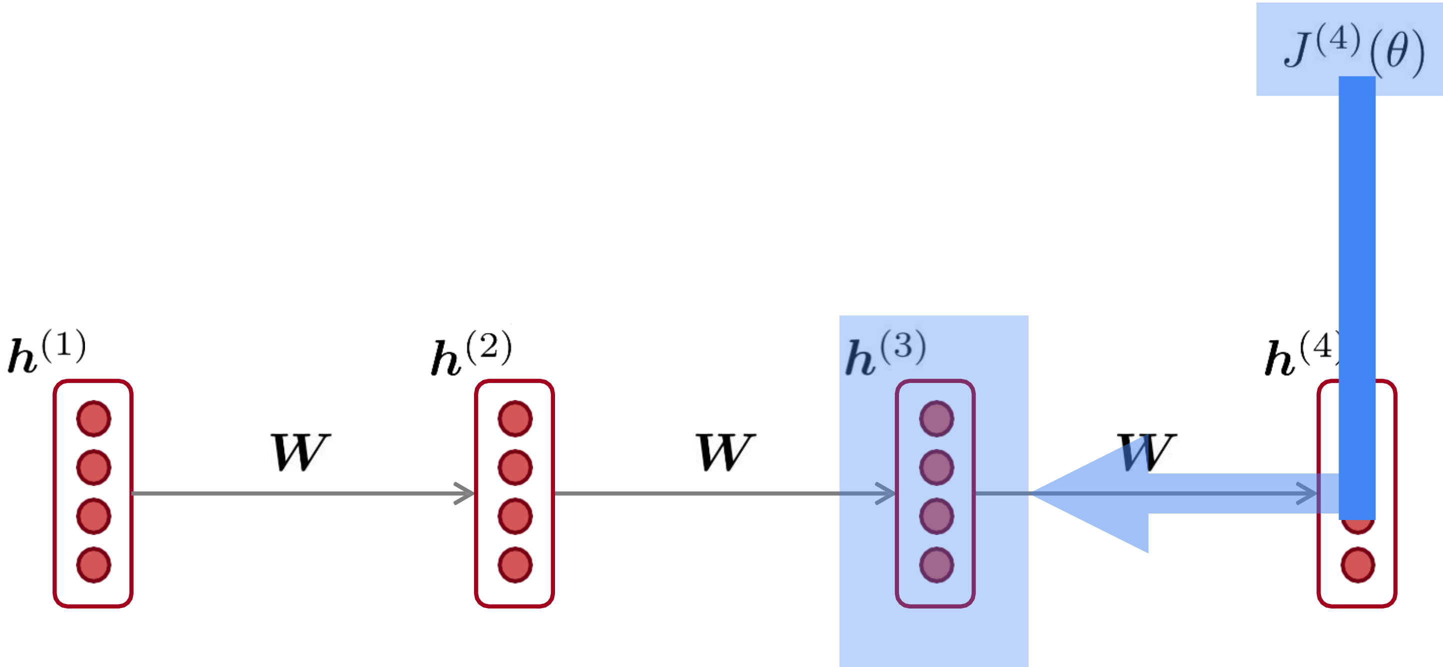
Vanishing gradient intuition



$$\frac{\partial J^{(4)}}{\partial \boldsymbol{h}^{(1)}} = \frac{\partial \boldsymbol{h}^{(2)}}{\partial \boldsymbol{h}^{(1)}} \times \frac{\partial J^{(4)}}{\partial \boldsymbol{h}^{(2)}}$$

chain rule!

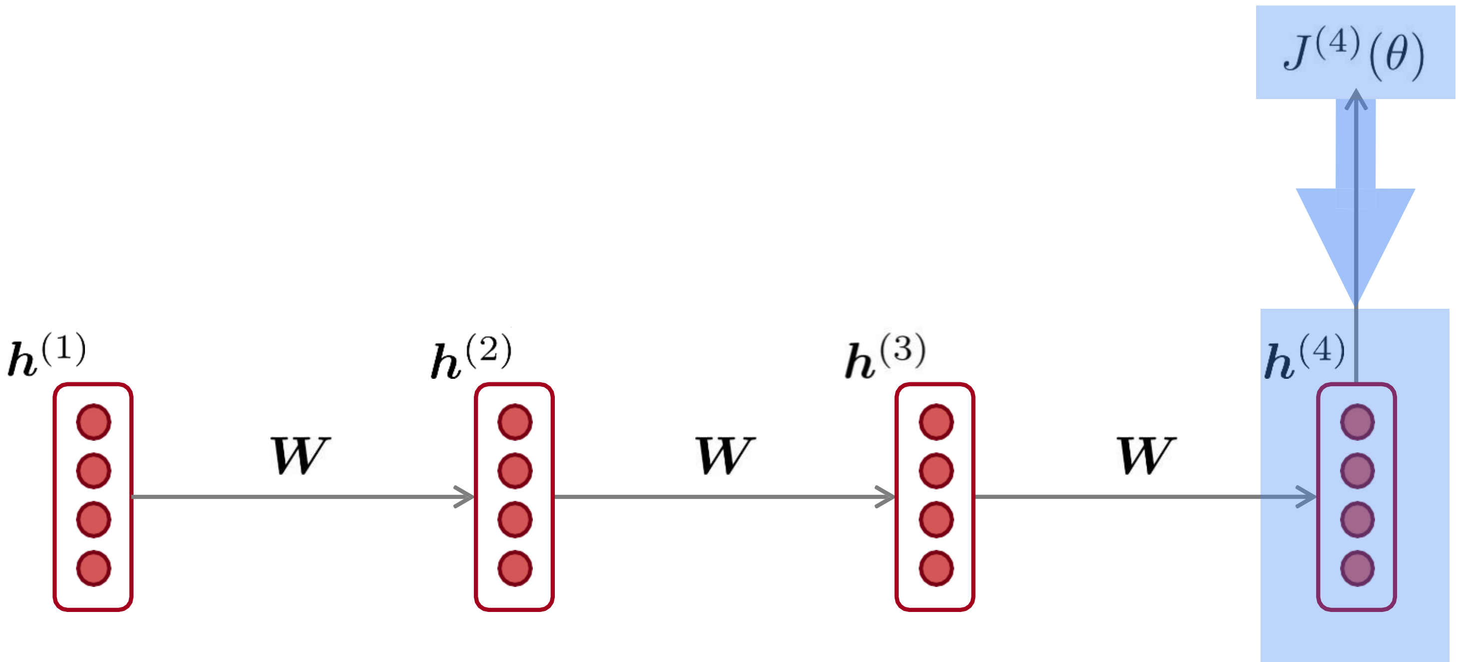
Vanishing gradient intuition



$$\frac{\partial J^{(4)}}{\partial \boldsymbol{h}^{(1)}} = \frac{\partial \boldsymbol{h}^{(2)}}{\partial \boldsymbol{h}^{(1)}} \times \qquad \frac{\partial \boldsymbol{h}^{(3)}}{\partial \boldsymbol{h}^{(2)}} \times \frac{\partial J^{(4)}}{\partial \boldsymbol{h}^{(3)}}$$

chain rule!

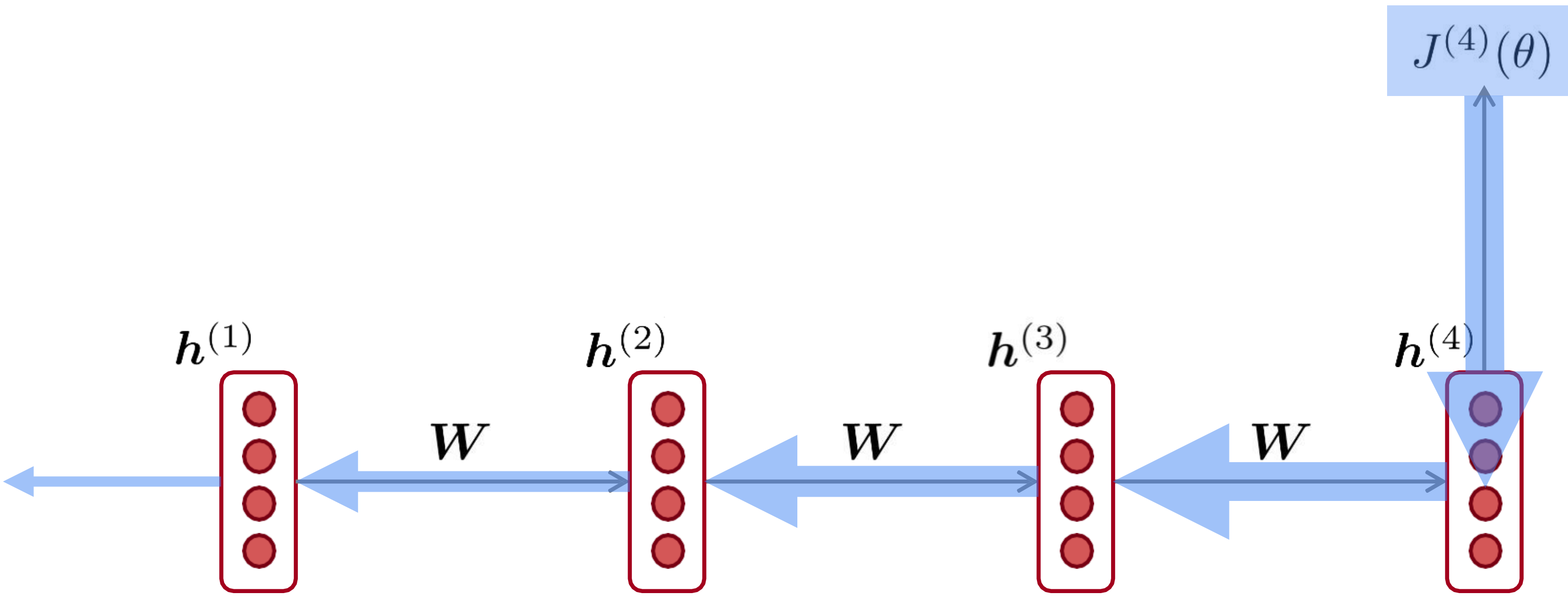
Vanishing gradient intuition



$$\frac{\partial J^{(4)}}{\partial \boldsymbol{h}^{(1)}} = \frac{\partial \boldsymbol{h}^{(2)}}{\partial \boldsymbol{h}^{(1)}} \times \frac{\partial \boldsymbol{h}^{(3)}}{\partial \boldsymbol{h}^{(2)}} \times \frac{\partial \boldsymbol{h}^{(4)}}{\partial \boldsymbol{h}^{(3)}} \times \frac{\partial J^{(4)}}{\partial \boldsymbol{h}^{(4)}}$$

chain rule!

Vanishing gradient intuition



$$\frac{\partial J^{(4)}}{\partial \boldsymbol{h}^{(1)}} = \boxed{\frac{\partial \boldsymbol{h}^{(2)}}{\partial \boldsymbol{h}^{(1)}}} \times \boxed{\frac{\partial \boldsymbol{h}^{(3)}}{\partial \boldsymbol{h}^{(2)}}} \times \boxed{\frac{\partial \boldsymbol{h}^{(4)}}{\partial \boldsymbol{h}^{(3)}}} \times \frac{\partial J^{(4)}}{\partial \boldsymbol{h}^{(4)}}$$

What happens if these are small?

<u>Vanishing gradient problem:</u>
When these are small, the gradient signal gets smaller and smaller as it backpropagates further

Abigail See

Vanishing gradient proof sketch

- Recall: $$\boldsymbol{h}^{(t)} = \sigma\left(\boldsymbol{W}_h \boldsymbol{h}^{(t-1)} + \boldsymbol{W}_x \boldsymbol{x}^{(t)} + \boldsymbol{b}_1\right)$$
- Therefore: $$\frac{\partial \boldsymbol{h}^{(t)}}{\partial \boldsymbol{h}^{(t-1)}} = \operatorname{diag}\left(\sigma'\left(\boldsymbol{W}_h \boldsymbol{h}^{(t-1)} + \boldsymbol{W}_x \boldsymbol{x}^{(t)} + \boldsymbol{b}_1\right)\right)\boldsymbol{W}_h$$ (chain rule)
- Consider the gradient of the loss $J^{(i)}(\theta)$ on step *i*, with respect to the hidden state $\boldsymbol{h}^{(j)}$ on some previous step *j*.

$$\frac{\partial J^{(i)}(\theta)}{\partial \boldsymbol{h}^{(j)}} = \frac{\partial J^{(i)}(\theta)}{\partial \boldsymbol{h}^{(i)}} \prod_{j<t\leq i} \frac{\partial \boldsymbol{h}^{(t)}}{\partial \boldsymbol{h}^{(t-1)}}$$ (chain rule)

$$= \frac{\partial J^{(i)}(\theta)}{\partial \boldsymbol{h}^{(i)}} \boxed{\boldsymbol{W}_h^{(i-j)}} \prod_{j<t\leq i} \operatorname{diag}\left(\sigma'\left(\boldsymbol{W}_h \boldsymbol{h}^{(t-1)} + \boldsymbol{W}_x \boldsymbol{x}^{(t)} + \boldsymbol{b}_1\right)\right)$$ (value of $\frac{\partial \boldsymbol{h}^{(t)}}{\partial \boldsymbol{h}^{(t-1)}}$)

If W_h is small, then this term gets vanishingly small as *i* and *j* get further apart

Source: "On the difficulty of training recurrent neural networks", Pascanu et al, 2013. http://proceedings.mlr.press/v28/pascanu13.pdf

Vanishing gradient proof sketch

- Consider matrix L2 norms:

$$\left\|\frac{\partial J^{(i)}(\theta)}{\partial \boldsymbol{h}^{(j)}}\right\| \leq \left\|\frac{\partial J^{(i)}(\theta)}{\partial \boldsymbol{h}^{(i)}}\right\| \|\boldsymbol{W}_h\|^{(i-j)} \prod_{j<t\leq i} \left\|\operatorname{diag}\left(\sigma'\left(\boldsymbol{W}_h \boldsymbol{h}^{(t-1)} + \boldsymbol{W}_x \boldsymbol{x}^{(t)} + \boldsymbol{b}_1\right)\right)\right\|$$

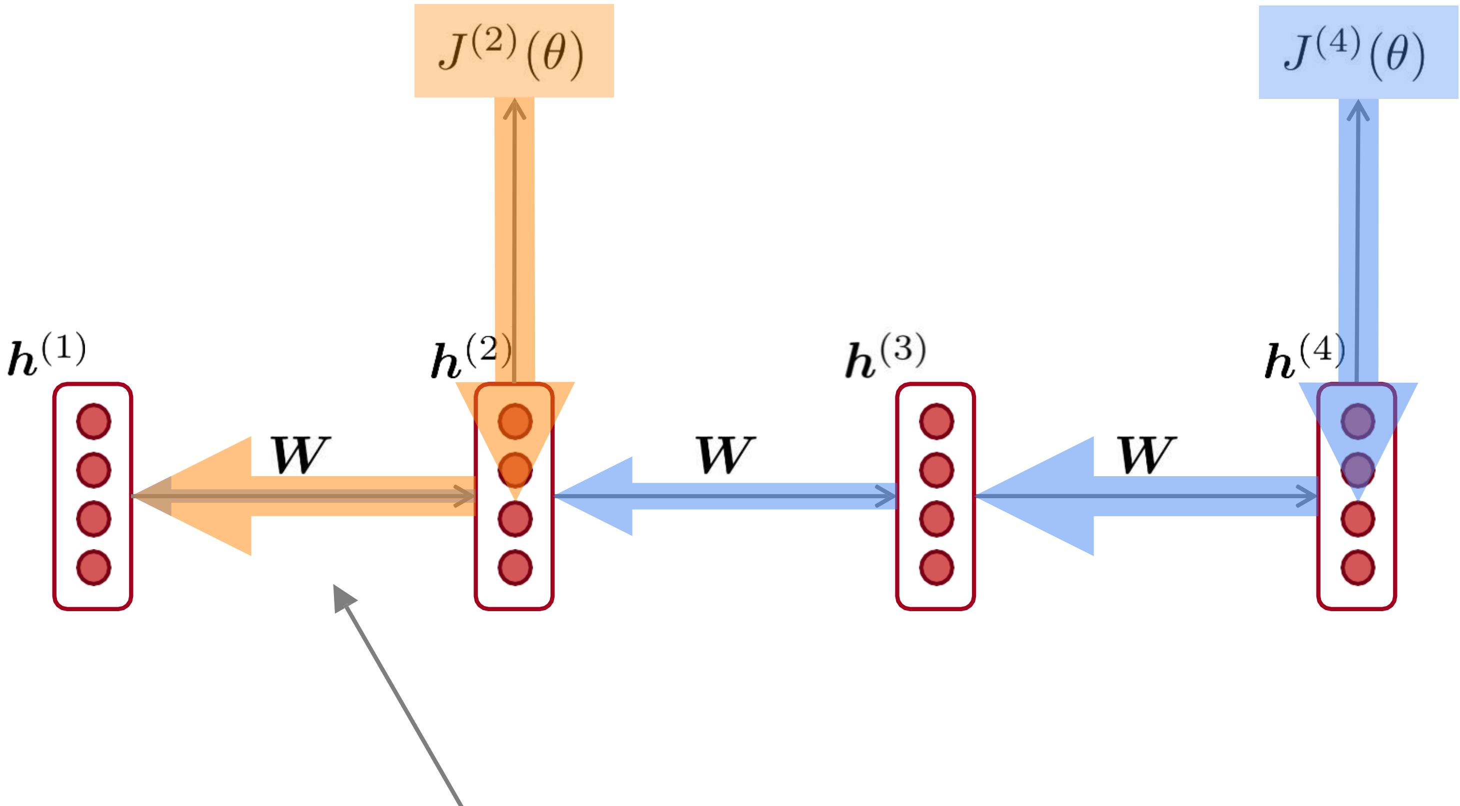
- Pascanu et al showed that that if the largest eigenvalue of W_h is less than 1, then the gradient $\left\|\frac{\partial J^{(i)}(\theta)}{\partial \boldsymbol{h}^{(j)}}\right\|$ will shrink exponentially

- There's a similar proof relating a largest eigenvalue >1 to exploding gradients

Source: "On the difficulty of training recurrent neural networks", Pascanu et al, 2013. http://proceedings.mlr.press/v28/pascanu13.pdf

Adapted from Abigail See

Why is vanishing gradient a problem?



Gradient signal from faraway is lost because it's much smaller than gradient signal from close-by.

So model weights are only updated only with respect to near effects, not long-term effects.

Effect of vanishing gradient on RNN-LM

- **LM task:** *When she tried to print her ______, she found that the printer was out of toner. She went to the stationery store to buy more toner. It was very overpriced. After installing the toner into the printer, she finally printed her tickets.*

- To learn from this training example, the RNN-LM needs to model the dependency between *"tickets"* on the 7^{th} step and the target word *"tickets"* at the end.

- But if gradient is small, the model can't learn this dependency
  - So the model is unable to predict similar long-distance dependencies at test time

Adapted from Abigail See

Effect of vanishing gradient on RNN-LM

- **LM task:** *The writer of the books* ____ → *is* / *are*

- **Correct answer**: *The writer of the books is planning a sequel*

- **Syntactic recency:** *The writer of the books is* (correct)

- **Sequential recency:** *The writer of the books are* (incorrect)

- Due to vanishing gradient, RNN-LMs are better at learning from sequential recency than syntactic recency, so they make this type of error more often than we'd like [Linzen et al 2016]

"Assessing the Ability of LSTMs to Learn Syntax-Sensitive Dependencies", Linzen et al, 2016. https://arxiv.org/pdf/1611.01368.pdf

Why is exploding gradient a problem?

- If the gradient becomes too big, then the SGD update step becomes too big:

$$\theta^{new} = \theta^{old} - \overbrace{\alpha}^{\text{learning rate}} \underbrace{\nabla_{\theta} J(\theta)}_{\text{gradient}}$$

- This can cause bad updates: we take too large a step and reach a bad parameter configuration (with large loss)

- In the worst case, this will result in Inf or NaN in your network (then you have to restart training from an earlier checkpoint)

Gradient clipping: solution for exploding gradient

- Gradient clipping: if the norm of the gradient is greater than some threshold, scale it down before applying SGD update

Algorithm 1 Pseudo-code for norm clipping

$\hat{\mathbf{g}} \leftarrow \frac{\partial \mathcal{E}}{\partial \theta}$
if $\|\hat{\mathbf{g}}\| \geq threshold$ **then**
  $\hat{\mathbf{g}} \leftarrow \frac{threshold}{\|\hat{\mathbf{g}}\|} \hat{\mathbf{g}}$
end if

- Intuition: take a step in the same direction, but a smaller step

Source: "On the difficulty of training recurrent neural networks", Pascanu et al, 2013. http://proceedings.mlr.press/v28/pascanu13.pdf

RNNs with Gates

How to fix vanishing gradient problem?

- The main problem is that *it's too difficult for the RNN to learn to preserve information over many timesteps.*

- In a vanilla RNN, the hidden state is constantly being rewritten

$$\boldsymbol{h}^{(t)} = \sigma\left(\boldsymbol{W}_h \boldsymbol{h}^{(t-1)} + \boldsymbol{W}_x \boldsymbol{x}^{(t)} \qquad \right)$$

- How about a RNN with separate memory?

Gated Recurrent Units (GRUs)

- More complex hidden unit computation in recurrence!
- Introduced by Cho et al. 2014
- Main ideas:
  - keep around memories to capture long distance dependencies
  - allow error messages to flow at different strengths depending on the inputs

Gated Recurrent Units (GRUs)

- Standard RNN computes hidden layer at next time step directly: $h_t = f\left(W^{(hh)}h_{t-1} + W^{(hx)}x_t\right)$
- GRU first computes an update **gate** (another layer) based on current input word vector and hidden state

$$z_t = \sigma\left(W^{(z)}x_t + U^{(z)}h_{t-1}\right)$$

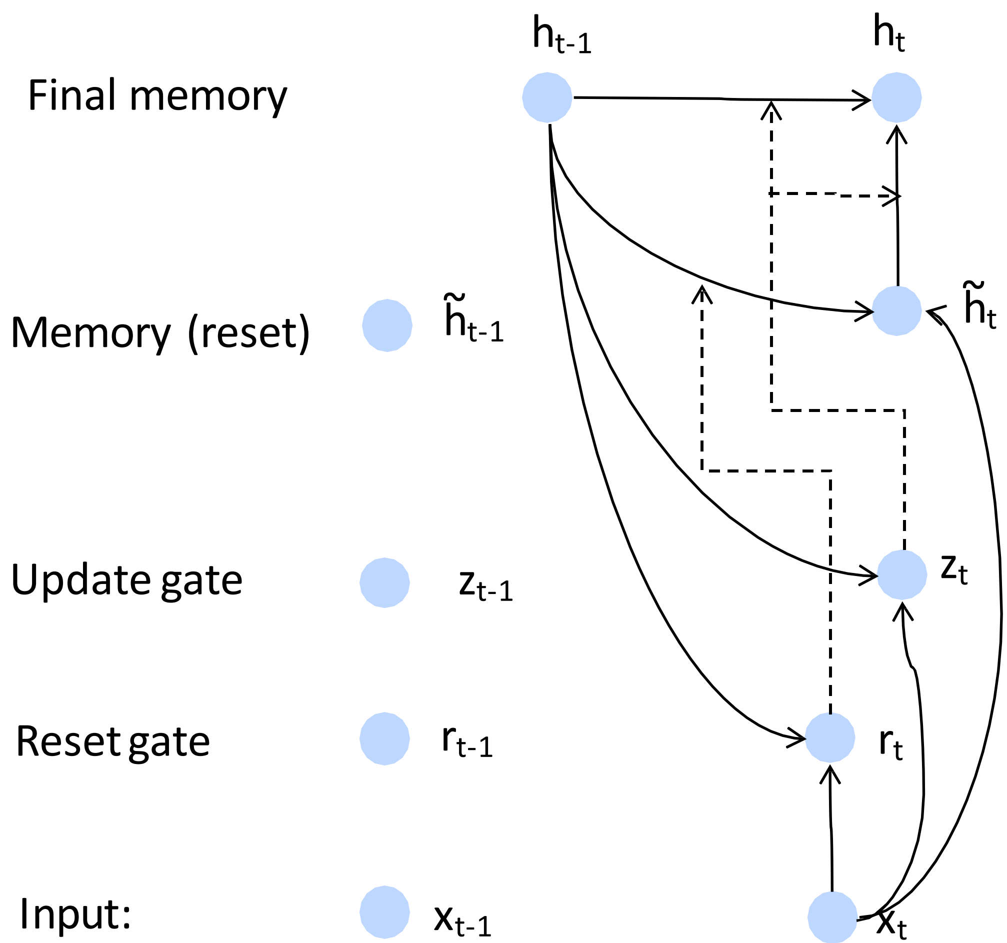
- Compute reset gate similarly but with different weights

$$r_t = \sigma\left(W^{(r)}x_t + U^{(r)}h_{t-1}\right)$$

Gated Recurrent Units (GRUs)

- Update gate $$z_t = \sigma\left(W^{(z)}x_t + U^{(z)}h_{t-1}\right)$$
- Reset gate $$r_t = \sigma\left(W^{(r)}x_t + U^{(r)}h_{t-1}\right)$$
- New memory content: $\tilde{h}_t = \tanh\left(Wx_t + r_t \circ Uh_{t-1}\right)$
  If reset gate unit is ~0, then this ignores previous memory and only stores the new word information
- Final memory at time step combines current and previous time steps: $h_t = z_t \circ h_{t-1} + (1 - z_t) \circ \tilde{h}_t$

Gated Recurrent Units (GRUs)



$$z_t = \sigma\left(W^{(z)}x_t + U^{(z)}h_{t-1}\right)$$

$$r_t = \sigma\left(W^{(r)}x_t + U^{(r)}h_{t-1}\right)$$

$$\tilde{h}_t = \tanh\left(Wx_t + r_t \circ Uh_{t-1}\right)$$

$$h_t = z_t \circ h_{t-1} + (1 - z_t) \circ \tilde{h}_t$$

Richard Socher

Gated Recurrent Units (GRUs)

- If reset ***r*** is close to 0, ignore previous hidden state: Allows model to drop information that is irrelevant in the future

$$z_t = \sigma\left(W^{(z)}x_t + U^{(z)}h_{t-1}\right)$$
$$r_t = \sigma\left(W^{(r)}x_t + U^{(r)}h_{t-1}\right)$$
$$\tilde{h}_t = \tanh\left(Wx_t + r_t \circ Uh_{t-1}\right)$$
$$h_t = z_t \circ h_{t-1} + (1 - z_t) \circ \tilde{h}_t$$

- If update ***z*** is close to 1, can copy information through many time steps, i.e. copy-paste state: Less vanishing gradient!

- Units with short-term dependencies often have reset gates (r) very active; ones with long-term dependencies have active update gates (z)

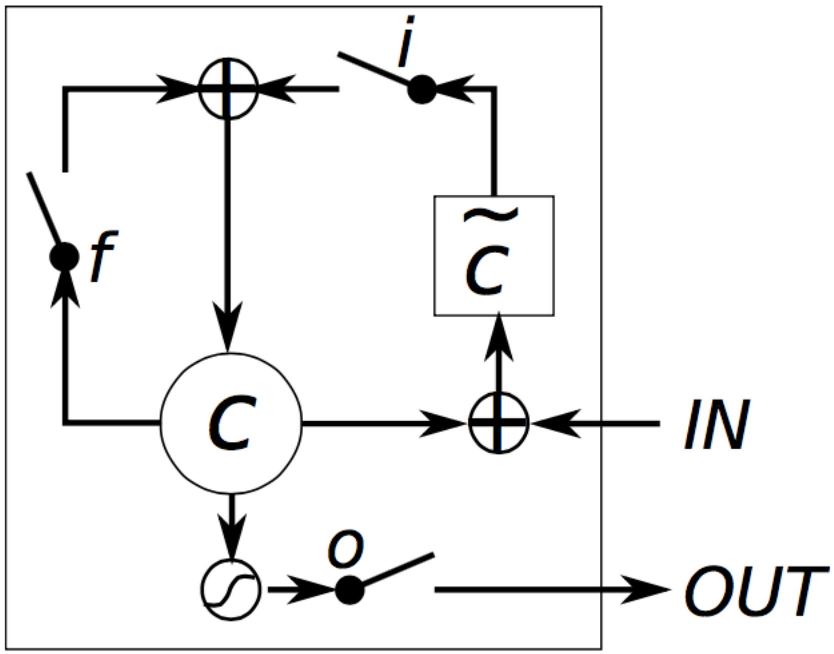
Adapted from Richard Socher

Long-short-term-memories (LSTMs)

- Proposed by Hochreiter and Schmidhuber in 1997
- We can make the units even more complex
- Allow each time step to modify
  - Input gate (current cell matters) $i_t = \sigma\left(W^{(i)}x_t + U^{(i)}h_{t-1}\right)$
  - Forget (gate 0, forget past) $f_t = \sigma\left(W^{(f)}x_t + U^{(f)}h_{t-1}\right)$
  - Output (how much cell is exposed) $o_t = \sigma\left(W^{(o)}x_t + U^{(o)}h_{t-1}\right)$
  - New memory cell $\tilde{c}_t = \tanh\left(W^{(c)}x_t + U^{(c)}h_{t-1}\right)$
- Final memory cell: $c_t = f_t \circ c_{t-1} + i_t \circ \tilde{c}_t$
- Final hidden state: $h_t = o_t \circ \tanh(c_t)$

Adapted from Richard Socher

Long-short-term-memories (LSTMs)



$$i_t = \sigma\left(W^{(i)}x_t + U^{(i)}h_{t-1}\right)$$

$$f_t = \sigma\left(W^{(f)}x_t + U^{(f)}h_{t-1}\right)$$

$$o_t = \sigma\left(W^{(o)}x_t + U^{(o)}h_{t-1}\right)$$

$$\tilde{c}_t = \tanh\left(W^{(c)}x_t + U^{(c)}h_{t-1}\right)$$

$$c_t = f_t \circ c_{t-1} + i_t \circ \tilde{c}_t$$

$$h_t = o_t \circ \tanh(c_t)$$

Intuition: memory cells can keep information intact, unless inputs makes them forget it or overwrite it with new input

Cell can decide to output this information or just store it

Review on your own: Gated Recurrent Units (GRU)

- Proposed by Cho et al. in 2014 as a simpler alternative to the LSTM.
- On each timestep *t* we have input $\boldsymbol{x}^{(t)}$ and hidden state $\boldsymbol{h}^{(t)}$ (no cell state).

Update gate: controls what parts of hidden state are updated vs preserved

Reset gate: controls what parts of previous hidden state are used to compute new content

$$\boldsymbol{u}^{(t)} = \sigma\left(\boldsymbol{W}_u \boldsymbol{h}^{(t-1)} + \boldsymbol{U}_u \boldsymbol{x}^{(t)} + \boldsymbol{b}_u\right)$$

$$\boldsymbol{r}^{(t)} = \sigma\left(\boldsymbol{W}_r \boldsymbol{h}^{(t-1)} + \boldsymbol{U}_r \boldsymbol{x}^{(t)} + \boldsymbol{b}_r\right)$$

New hidden state content: reset gate selects useful parts of prev hidden state. Use this and current input to compute new hidden content.

Hidden state: update gate simultaneously controls what is kept from previous hidden state, and what is updated to new hidden state content

$$\tilde{\boldsymbol{h}}^{(t)} = \tanh\left(\boldsymbol{W}_h(\boldsymbol{r}^{(t)} \circ \boldsymbol{h}^{(t-1)}) + \boldsymbol{U}_h \boldsymbol{x}^{(t)} + \boldsymbol{b}_h\right)$$

$$\boldsymbol{h}^{(t)} = (1 - \boldsymbol{u}^{(t)}) \circ \boldsymbol{h}^{(t-1)} + \boldsymbol{u}^{(t)} \circ \tilde{\boldsymbol{h}}^{(t)}$$

How does this solve vanishing gradient?
GRU makes it easier to retain info long-term (e.g. by setting update gate to 0)

"Learning Phrase Representations using RNN Encoder–Decoder for Statistical Machine Translation", Cho et al. 2014, https://arxiv.org/pdf/1406.1078v3.pdf

Review on your own: Long Short-Term Memory (LSTM)

We have a sequence of inputs $\boldsymbol{x}^{(t)}$, and we will compute a sequence of hidden states $\boldsymbol{h}^{(t)}$ and cell states $\boldsymbol{c}^{(t)}$. On timestep *t*:

Sigmoid function: all gate values are between 0 and 1

Forget gate: controls what is kept vs forgotten, from previous cell state

Input gate: controls what parts of the new cell content are written to cell

Output gate: controls what parts of cell are output to hidden state

$$\boldsymbol{f}^{(t)} = \boxed{\sigma}\left(\boldsymbol{W}_f \boldsymbol{h}^{(t-1)} + \boldsymbol{U}_f \boldsymbol{x}^{(t)} + \boldsymbol{b}_f\right)$$

$$\boldsymbol{i}^{(t)} = \boxed{\sigma}\left(\boldsymbol{W}_i \boldsymbol{h}^{(t-1)} + \boldsymbol{U}_i \boldsymbol{x}^{(t)} + \boldsymbol{b}_i\right)$$

$$\boldsymbol{o}^{(t)} = \boxed{\sigma}\left(\boldsymbol{W}_o \boldsymbol{h}^{(t-1)} + \boldsymbol{U}_o \boldsymbol{x}^{(t)} + \boldsymbol{b}_o\right)$$

New cell content: this is the new content to be written to the cell

Cell state: erase ("forget") some content from last cell state, and write ("input") some new cell content

Hidden state: read ("output") some content from the cell

$$\tilde{\boldsymbol{c}}^{(t)} = \tanh\left(\boldsymbol{W}_c \boldsymbol{h}^{(t-1)} + \boldsymbol{U}_c \boldsymbol{x}^{(t)} + \boldsymbol{b}_c\right)$$

$$\boldsymbol{c}^{(t)} = \boldsymbol{f}^{(t)} \circ \boldsymbol{c}^{(t-1)} + \boldsymbol{i}^{(t)} \circ \tilde{\boldsymbol{c}}^{(t)}$$

$$\boldsymbol{h}^{(t)} = \boldsymbol{o}^{(t)} \circ \tanh \boldsymbol{c}^{(t)}$$

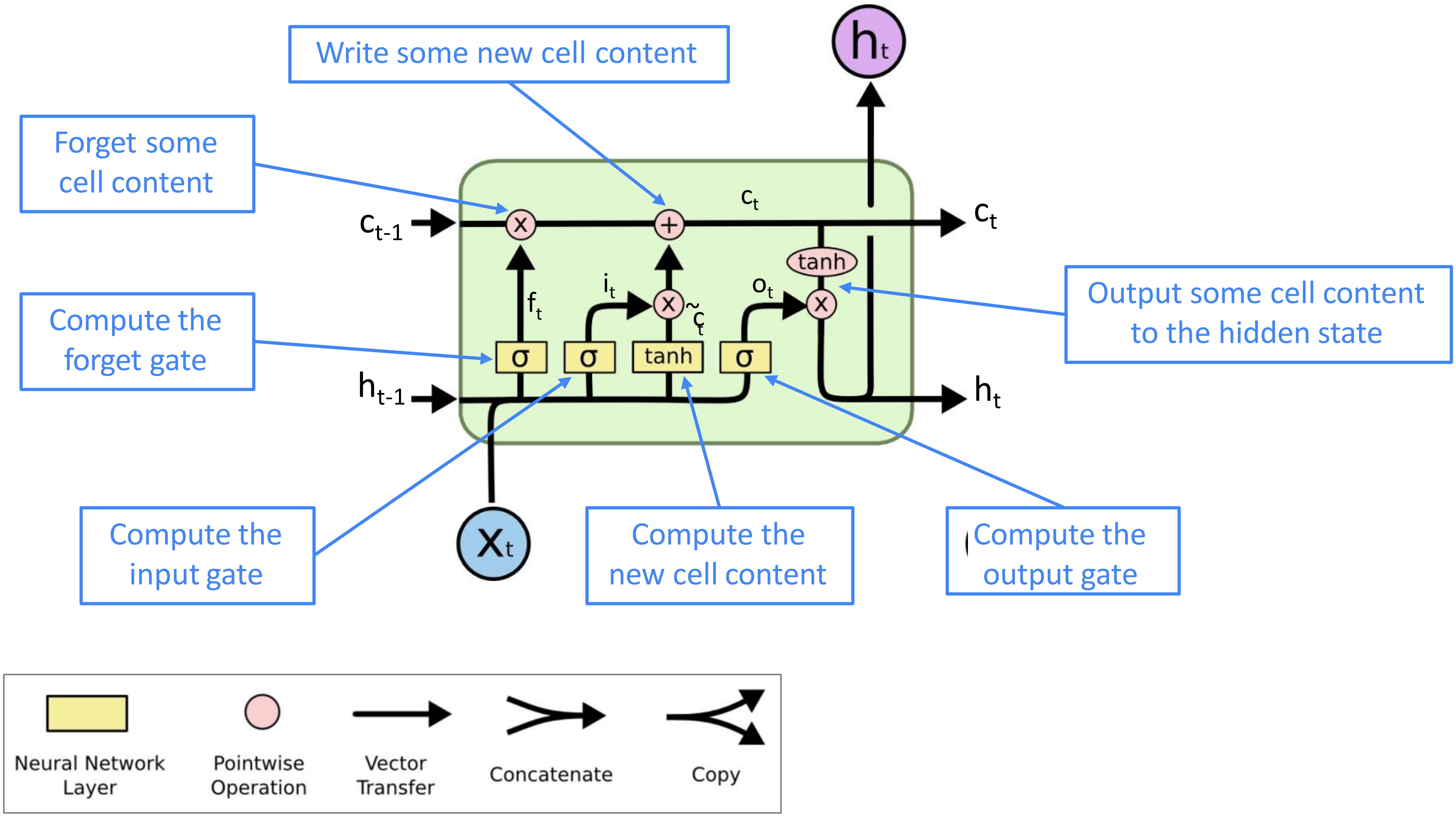
All these are vectors of same length *n*

Gates are applied using element-wise product

Abigail See

Review on your own: Long Short-Term Memory (LSTM)

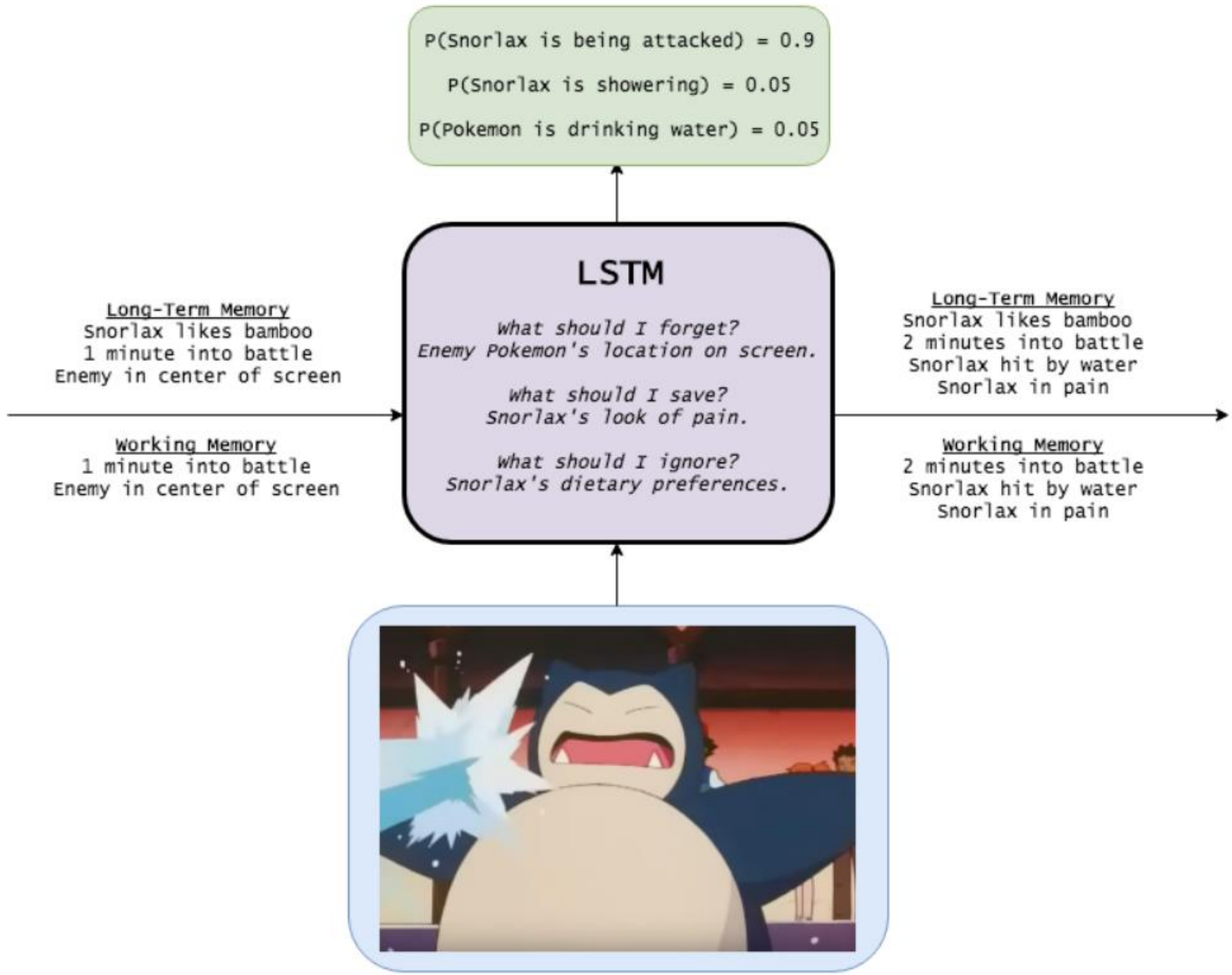
You can think of the LSTM equations visually like this:



Source: http://colah.github.io/posts/2015-08-Understanding-LSTMs/

Abigail See

Cell State vs Hidden State



http://blog.echen.me/2017/05/30/exploring-lstms/

Activity

http://blog.echen.me/2017/05/30/exploring-lstms/

LSTM vs GRU

- Researchers have proposed many gated RNN variants, but LSTM and GRU are the most widely-used
- The biggest difference is that GRU is quicker to compute and has fewer parameters
- There is no conclusive evidence that one consistently performs better than the other
- LSTM is a good default choice (especially if your data has particularly long dependencies, or you have lots of training data)
- Rule of thumb: start with LSTM, but switch to GRU if you want something more efficient

LSTMs: real-world success

- In 2013-2015, LSTMs started achieving state-of-the-art results for sequence modeling
  - Successful tasks include: handwriting recognition, speech recognition, machine translation, parsing, image captioning
  - LSTM became the dominant approach

- Starting in 2019, other approaches (e.g. Transformers) became more dominant for certain NLP tasks (will discuss next lecture)
  - For example in **WMT** (machine translation competition):
  - In WMT 2016, the summary report contains ”RNN” 44 times
  - In WMT 2018, the report contains “RNN” 9 times and “Transformer” 63 times

Source: "Findings of the 2016 Conference on Machine Translation (WMT16)", Bojar et al. 2016, http://www.statmt.org/wmt16/pdf/W16-2301.pdf
Source: "Findings of the 2018 Conference on Machine Translation (WMT18)", Bojar et al. 2018, http://www.statmt.org/wmt18/pdf/WMT028.pdf

Adapted from Abigail See

Is vanishing/exploding gradient just a RNN problem?

- No! It can be a problem for all neural architectures (including feed-forward and convolutional), especially deep ones.
  - Due to chain rule / choice of nonlinearity function, gradient can become vanishingly small as it backpropagates
  - Thus lower layers are learnt very slowly (hard to train)
  - Solution: lots of new deep feedforward/convolutional architectures that add more direct connections (thus allowing the gradient to flow)

For example:

- Residual connections aka "ResNet"
- Also known as skip-connections
- The identity connection preserves information by default
- This makes deep networks much easier to train

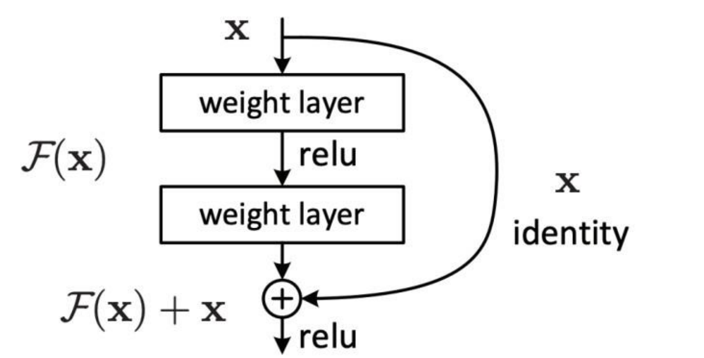


Figure 2. Residual learning: a building block.

"Deep Residual Learning for Image Recognition", He et al, 2015. https://arxiv.org/pdf/1512.03385.pdf

Is vanishing/exploding gradient just a RNN problem?

- No! It can be a problem for all neural architectures (including feed-forward and convolutional), especially deep ones.
  - Due to chain rule / choice of nonlinearity function, gradient can become vanishingly small as it backpropagates
  - Thus lower layers are learnt very slowly (hard to train)
  - Solution: lots of new deep feedforward/convolutional architectures that add more direct connections (thus allowing the gradient to flow)

<u>For example:</u>

- Dense connections aka "DenseNet"
- Directly connect everything to everything!

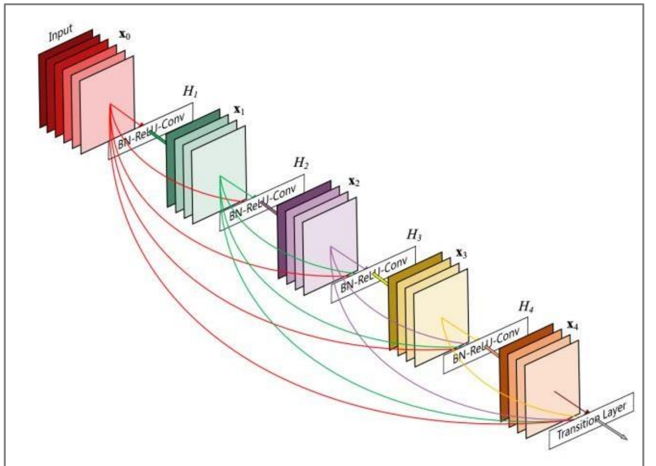
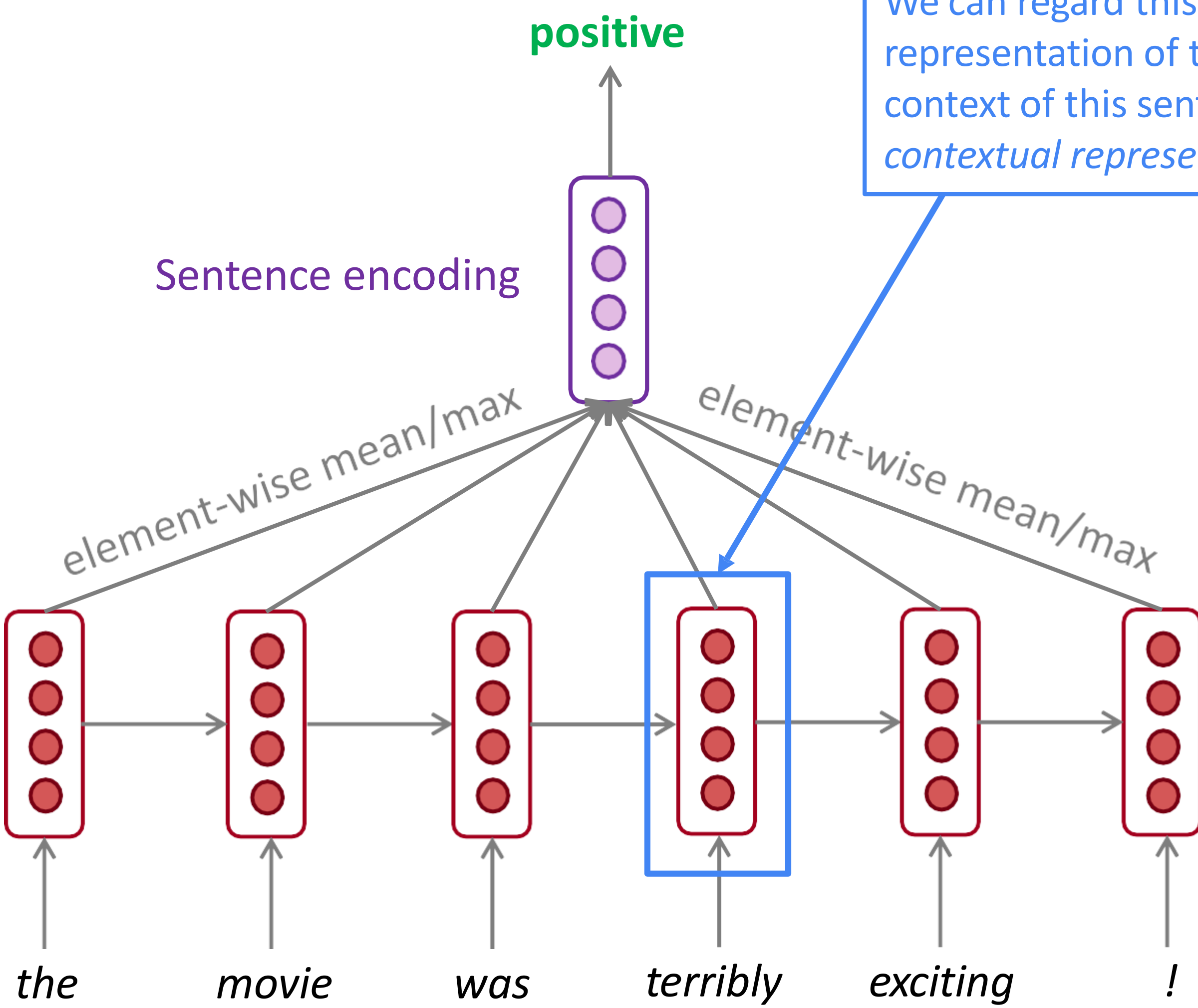


Figure 1: A 5-layer dense block with a growth rate of $k = 4$. Each layer takes all preceding feature-maps as input.

"Densely Connected Convolutional Networks", Huang et al, 2017. https://arxiv.org/pdf/1608.06993.pdf

Bidirectional RNNs: motivation

<u>Task: Sentiment Classification</u>



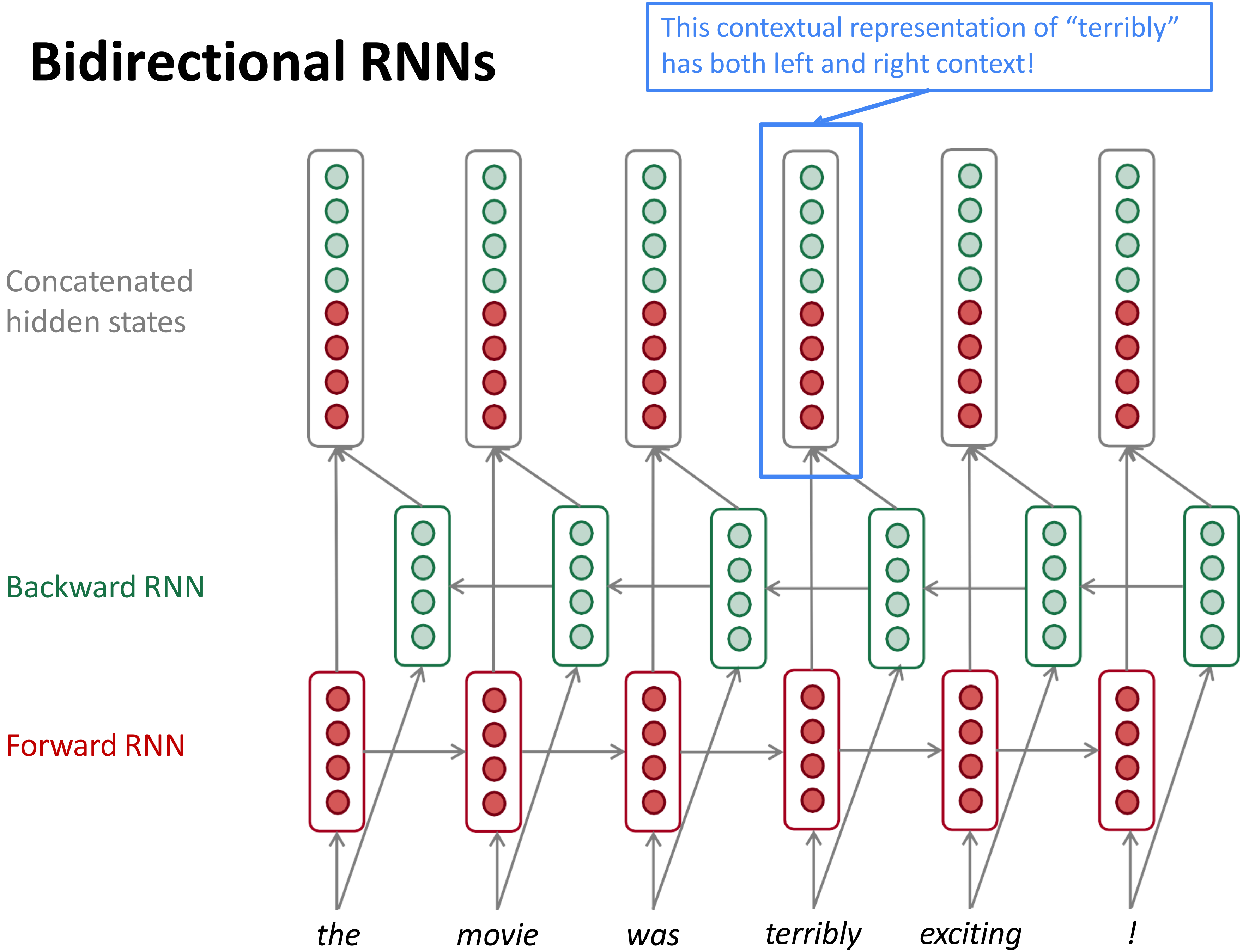
We can regard this hidden state as a representation of the word *"terribly"* in the context of this sentence. We call this a *contextual representation.*

These contextual representations only contain information about the *left* context (e.g. *"the movie was"*).

What about *right* context?

In this example, *"exciting"* is in the right context and this modifies the meaning of *"terribly"* (from negative to positive)

Bidirectional RNNs



Abigail See

Bidirectional RNNs

On timestep *t*:

This is a general notation to mean "compute one forward step of the RNN" – it could be a vanilla, LSTM or GRU computation.

Forward RNN $\overrightarrow{\boldsymbol{h}}^{(t)} = \boxed{\mathrm{RNN}_{\mathrm{FW}}}(\overrightarrow{\boldsymbol{h}}^{(t-1)}, \boldsymbol{x}^{(t)})$

Backward RNN $\overleftarrow{\boldsymbol{h}}^{(t)} = \mathrm{RNN}_{\mathrm{BW}}(\overleftarrow{\boldsymbol{h}}^{(t+1)}, \boldsymbol{x}^{(t)})$

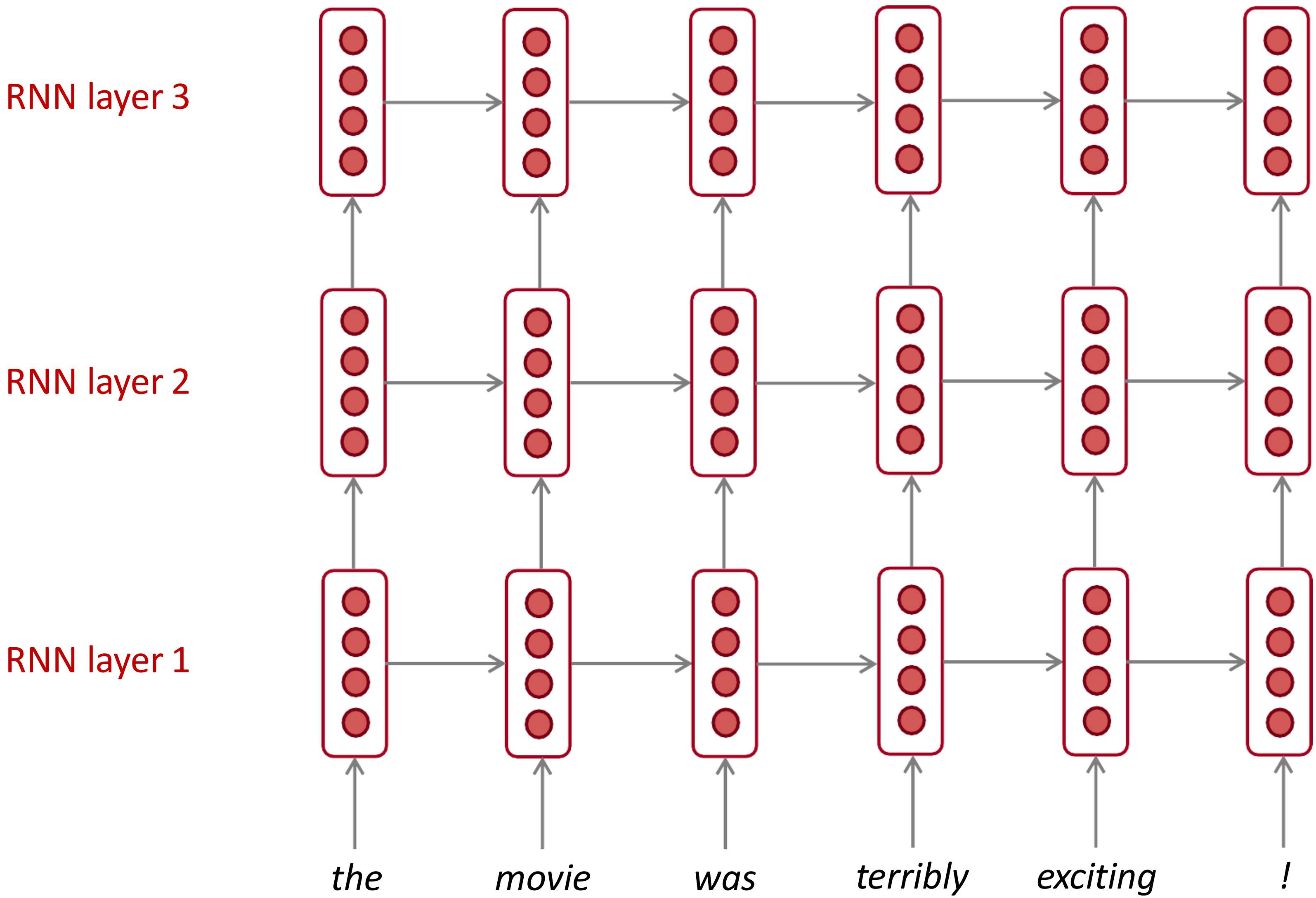
Generally, these two RNNs have separate weights

Concatenated hidden states $\boxed{\boldsymbol{h}^{(t)}} = [\overrightarrow{\boldsymbol{h}}^{(t)}; \overleftarrow{\boldsymbol{h}}^{(t)}]$

We regard this as "the hidden state" of a bidirectional RNN. This is what we pass on to the next parts of the network.

Multi-layer RNNs

The hidden states from RNN layer *i* are the inputs to RNN layer *i+1*



Evaluating Language Models

- The standard evaluation metric for Language Models is perplexity.

$$\text{perplexity} = \underbrace{\prod_{t=1}^{T} \left(\frac{1}{P_{\text{LM}}(\boldsymbol{x}^{(t+1)} | \, \boldsymbol{x}^{(t)}, \ldots, \boldsymbol{x}^{(1)})} \right)}_{\text{Inverse probability of corpus, according to Language Model}}^{1/T}$$

Normalized by number of words

- This is equal to the exponential of the cross-entropy loss $J(\theta)$:

$$= \prod_{t=1}^{T} \left(\frac{1}{\hat{\boldsymbol{y}}_{\boldsymbol{x}_{t+1}}^{(t)}} \right)^{1/T} = \exp\left(\frac{1}{T} \sum_{t=1}^{T} -\log \hat{\boldsymbol{y}}_{\boldsymbol{x}_{t+1}}^{(t)} \right) = \exp(J(\theta))$$

Lower perplexity is better!

Recap thus far

- **Language Model**: A system that predicts the next word
- **Recurrent Neural Network**: A family of neural networks that:
  - Take sequential input of any length
  - Apply the same weights on each step
  - Can optionally produce output on each step
- Vanishing gradient problem: what it is, why it happens, and why it's bad for RNNs
- LSTMs and GRUs: more complicated RNNs that use gates to control information flow; more resilient to vanishing gradients

Plan for this lecture

- Recurrent neural networks
  - Basics
  - Training (backprop through time, vanishing gradient)
  - Recurrent networks with gates (GRU, LSTM)
- Applications in NLP and vision
  - Neural machine translation (beam search, attention)
  - Image/video captioning

Applications

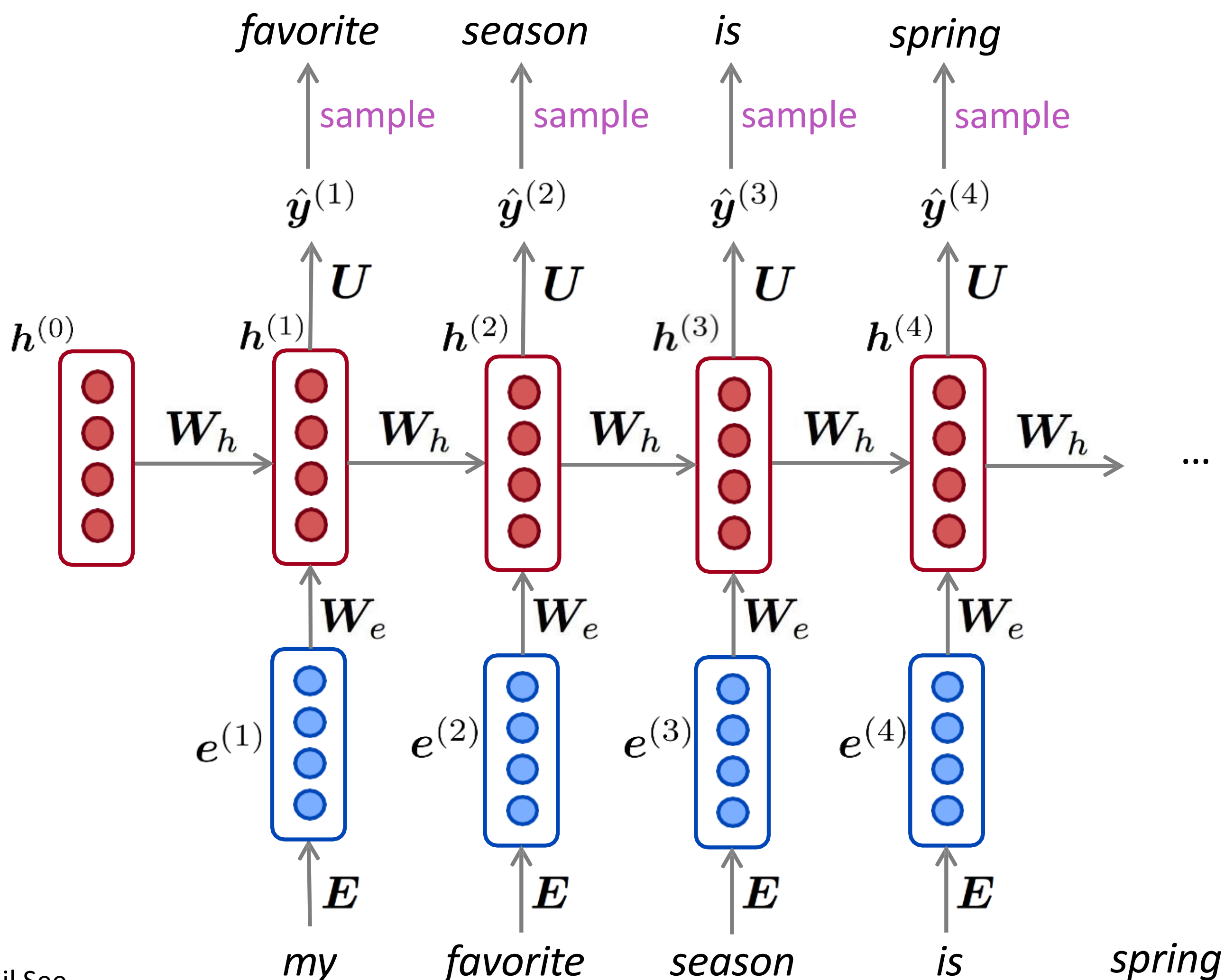
Why should we care about Language Modeling?

- Language Modeling is a benchmark task that helps us measure our progress on understanding language

- Language Modeling is a subcomponent of many NLP tasks, especially those involving generating text or estimating the probability of text:
  - Predictive typing
  - Speech recognition
  - Handwriting recognition
  - Spelling/grammar correction
  - Authorship identification
  - Machine translation
  - Summarization
  - Dialogue
  - etc.

Generating text with a RNN Language Model

You can use a RNN Language Model to generate text by repeated sampling. Sampled output is next step's input.



Abigail See

Generating text with a RNN Language Model

- Let's have some fun!
- You can train a RNN-LM on any kind of text, then generate text in that style.
- RNN-LM trained on Obama speeches:

The United States will step up to the cost of a new challenges of the American people that will share the fact that we created the problem. They were attacked and so that they have to say that all the task of the final days of war that I will not be able to get this done.

Source: https://medium.com/@samim/obama-rnn-machine-generated-political-speeches-c8abd18a2ea0

Generating text with a RNN Language Model

- Let's have some fun!
- You can train a RNN-LM on any kind of text, then generate text in that style.
- RNN-LM trained on *Harry Potter*:

"Sorry," Harry shouted, panicking—"I'll leave those brooms in London, are they?"

"No idea," said Nearly Headless Nick, casting low close by Cedric, carrying the last bit of treacle Charms, from Harry's shoulder, and to answer him the common room perched upon it, four arms held a shining knob from when the spider hadn't felt it seemed. He reached the teams too.

Source: https://medium.com/deep-writing/harry-potter-written-by-artificial-intelligence-8a9431803da6

Generating text with a RNN Language Model

- Let’s have some fun!
- You can train a RNN-LM on any kind of text, then generate text in that style.
- RNN-LM trained on paint color names:

Ghasty Pink 231 137 165	Sand Dan 201 172 143
Power Gray 151 124 112	Grade Bat 48 94 83
Navel Tan 199 173 140	Light Of Blast 175 150 147
Bock Coe White 221 215 236	Grass Bat 176 99 108
Horble Gray 178 181 196	Sindis Poop 204 205 194
Homestar Brown 133 104 85	Dope 219 209 179
Snader Brown 144 106 74	Testing 156 101 106
Golder Craam 237 217 177	Stoner Blue 152 165 159
Hurky White 232 223 215	Burble Simp 226 181 132
Burf Pink 223 173 179	Stanky Bean 197 162 171
Rose Hork 230 215 198	Turdly 190 164 116

This is an example of a character-level RNN-LM (predicts what character comes next)

Source: http://aiweirdness.com/post/160776374467/new-paint-colors-invented-by-neural-network

Generating poetry with RNNs

Sonnet 116 – Let me not ...

by William Shakespeare

Let me not to the marriage of true minds
Admit impediments. Love is not love
Which alters when it alteration finds,
Or bends with the remover to remove:
O no! it is an ever-fixed mark
That looks on tempests and is never shaken;
It is the star to every wandering bark,
Whose worth's unknown, although his height be taken.
Love's not Time's fool, though rosy lips and cheeks
Within his bending sickle's compass come:
Love alters not with his brief hours and weeks,
But bears it out even to the edge of doom.
If this be error and upon me proved,
I never writ, nor no man ever loved.

Generating poetry with RNNs

at first:

```
tyntd-iafhatawiaoihrdemot  lytdws  e ,tfti, astai f ogoh eoase rrranbyne 'nhthnee e
plia tklrgd t o idoe ns,smtt   h ne etie h,hregtrs nigtike,aoaenns lng
```

train more

```
"Tmont thithey" fomesscerliund
Keushey. Thom here
sheulke, anmerenith ol sivh I lalterthend Bleipile shuwy fil on aseterlome
coaniogennc Phe lism thond hon at. MeiDimorotion in ther thize."
```

train more

```
Aftair fall unsuch that the hall for Prince Velzonski's that me of
her hearly, and behs to so arwage fiving were to it beloge, pavu say falling misfort
how, and Gogition is so overelical and ofter.
```

train more

```
"Why do what that day," replied Natasha, and wishing to himself the fact the
princess, Princess Mary was easier, fed in had oftened him.
Pierre aking his soul came to the packs and drove up his father-in-law women.
```

More info: http://karpathy.github.io/2015/05/21/rnn-effectiveness/

Generating poetry with RNNs

```
PANDARUS:
Alas, I think he shall be come approached and the day
When little srain would be attain'd into being never fed,
And who is but a chain and subjects of his death,
I should not sleep.

Second Senator:
They are away this miseries, produced upon my soul,
Breaking and strongly should be buried, when I perish
The earth and thoughts of many states.

DUKE VINCENTIO:
Well, your wit is in the care of side and that.

Second Lord:
They would be ruled after this chamber, and
my fair nues begun out of the fact, to be conveyed,
Whose noble souls I'll have the heart of the wars.

Clown:
Come, sir, I will make did behold your worship.

VIOLA:
I'll drink it.
```

```
VIOLA:
Why, Salisbury must find his flesh and thought
That which I am not aps, not a man and in fire,
To show the reining of the raven and the wars
To grace my hand reproach within, and not a fair are hand,
That Caesar and my goodly father's world;
When I was heaven of presence and our fleets,
We spare with hours, but cut thy council I am great,
Murdered and by thy master's ready there
My power to give thee but so much as hell:
Some service in the noble bondman here,
Would show him to her wine.

KING LEAR:
O, if you were a feeble sight, the courtesy of your law,
Your sight and several breath, will wear the gods
With his heads, and my hands are wonder'd at the deeds,
So drop upon your lordship's head, and your opinion
Shall be against your honour.
```

Andrej Karpathy

Generating textbooks with RNNs

For $\bigoplus_{n=1,\ldots,m}$ where $\mathcal{L}_{m_\bullet} = 0$, hence we can find a closed subset $\mathcal{H}$ in $\mathcal{H}$ and any sets $\mathcal{F}$ on X, U is a closed immersion of S, then $U \to T$ is a separated algebraic space.

Proof. Proof of (1). It also start we get

$$S = \mathrm{Spec}(R) = U \times_X U \times_X U$$

and the comparicoly in the fibre product covering we have to prove the lemma generated by $\coprod Z \times_U U \to V$. Consider the maps M along the set of points Sch_{fppf} and $U \to U$ is the fibre category of S in U in Section, ?? and the fact that any U affine, see Morphisms, Lemma ??. Hence we obtain a scheme S and any open subset $W \subset U$ in $Sh(G)$ such that $\mathrm{Spec}(R') \to S$ is smooth or an

$$U = \bigcup U_i \times_{S_i} U_i$$

which has a nonzero morphism we may assume that f_i is of finite presentation over S. We claim that $\mathcal{O}_{X,x}$ is a scheme where $x, x', s'' \in S'$ such that $\mathcal{O}_{X,x'} \to \mathcal{O}'_{X',x'}$ is separated. By Algebra, Lemma ?? we can define a map of complexes $\mathrm{GL}_{S'}(x'/S'')$ and we win. □

To prove study we see that $\mathcal{F}|_U$ is a covering of $\mathcal{X}'$, and $\mathcal{T}_i$ is an object of $\mathcal{F}_{X/S}$ for $i > 0$ and $\mathcal{F}_p$ exists and let $\mathcal{F}_i$ be a presheaf of $\mathcal{O}_X$-modules on $\mathcal{C}$ as a $\mathcal{F}$-module. In particular $\mathcal{F} = U/\mathcal{F}$ we have to show that

$$\widetilde{M}^\bullet = \mathcal{I}^\bullet \otimes_{\mathrm{Spec}(k)} \mathcal{O}_{S,s} - i_X^{-1}\mathcal{F})$$

is a unique morphism of algebraic stacks. Note that

$$\mathrm{Arrows} = (Sch/S)^{opp}_{fppf}, (Sch/S)_{fppf}$$

and

$$V = \Gamma(S, \mathcal{O}) \longmapsto (U, \mathrm{Spec}(A))$$

is an open subset of X. Thus U is affine. This is a continuous map of X is the inverse, the groupoid scheme S.

Proof. See discussion of sheaves of sets. □

The result for prove any open covering follows from the less of Example ??. It may replace S by $X_{spaces,\acute{e}tale}$ which gives an open subspace of X and T equal to S_{Zar}, see Descent, Lemma ??. Namely, by Lemma ?? we see that R is geometrically regular over S.

Lemma 0.1. *Assume (3) and (3) by the construction in the description.*

Suppose $X = \lim |X|$ (by the formal open covering X and a single map $\underline{Proj}_X(\mathcal{A}) = \mathrm{Spec}(B)$ over U compatible with the complex

$$Set(\mathcal{A}) = \Gamma(X, \mathcal{O}_{X,\mathcal{O}_X}).$$

When in this case of to show that $\mathcal{Q} \to \mathcal{C}_{Z/X}$ is stable under the following result in the second conditions of (1), and (3). This finishes the proof. By Definition ?? (without element is when the closed subschemes are catenary. If T is surjective we may assume that T is connected with residue fields of S. Moreover there exists a closed subspace $Z \subset X$ of X where U in X' is proper (some defining as a closed subset of the uniqueness it suffices to check the fact that the following theorem

(1) *f is locally of finite type. Since $S = \mathrm{Spec}(R)$ and $Y = \mathrm{Spec}(R)$.*

Proof. This is form all sheaves of sheaves on X. But given a scheme U and a surjective étale morphism $U \to X$. Let $U \cap U = \coprod_{i=1,\ldots,n} U_i$ be the scheme X over S at the schemes $X_i \to X$ and $U = \lim_i X_i$. □

The following lemma surjective restrocomposes of this implies that $\mathcal{F}_{x_0} = \mathcal{F}_{x_0} = \mathcal{F}_{\mathcal{X},\ldots,0}$.

Lemma 0.2. *Let X be a locally Noetherian scheme over S, $E = \mathcal{F}_{X/S}$. Set $\mathcal{I} = \mathcal{J}_1 \subset \mathcal{I}'_n$. Since $\mathcal{I}^n \subset \mathcal{I}^n$ are nonzero over $i_0 \leq \mathfrak{p}$ is a subset of $\mathcal{J}_{n,0} \circ \overline{A}_2$ works.*

Lemma 0.3. *In Situation ??. Hence we may assume $\mathfrak{q}' = 0$.*

Proof. We will use the property we see that $\mathfrak{p}$ is the mext functor (??). On the other hand, by Lemma ?? we see that

$$D(\mathcal{O}_{X'}) = \mathcal{O}_X(D)$$

where K is an F-algebra where δ_{n+1} is a scheme over S. □

Andrej Karpathy

Generating code with RNNs

```
static void do_command(struct seq_file *m, void *v)
{
  int column = 32 << (cmd[2] & 0x80);
  if (state)
    cmd = (int)(int_state ^ (in_8(&ch->ch_flags) & Cmd) ? 2 : 1);
  else
    seq = 1;
  for (i = 0; i < 16; i++) {
    if (k & (1 << 1))
      pipe = (in_use & UMXTHREAD_UNCCA) +
        ((count & 0x00000000fffffff8) & 0x000000f) << 8;
    if (count == 0)
      sub(pid, ppc_md.kexec_handle, 0x20000000);
    pipe_set_bytes(i, 0);
  }
  /* Free our user pages pointer to place camera if all dash */
  subsystem_info = &of_changes[PAGE_SIZE];
  rek_controls(offset, idx, &soffset);
  /* Now we want to deliberately put it to device */
  control_check_polarity(&context, val, 0);
  for (i = 0; i < COUNTER; i++)
    seq_puts(s, "policy ");
}
```

Generated C code

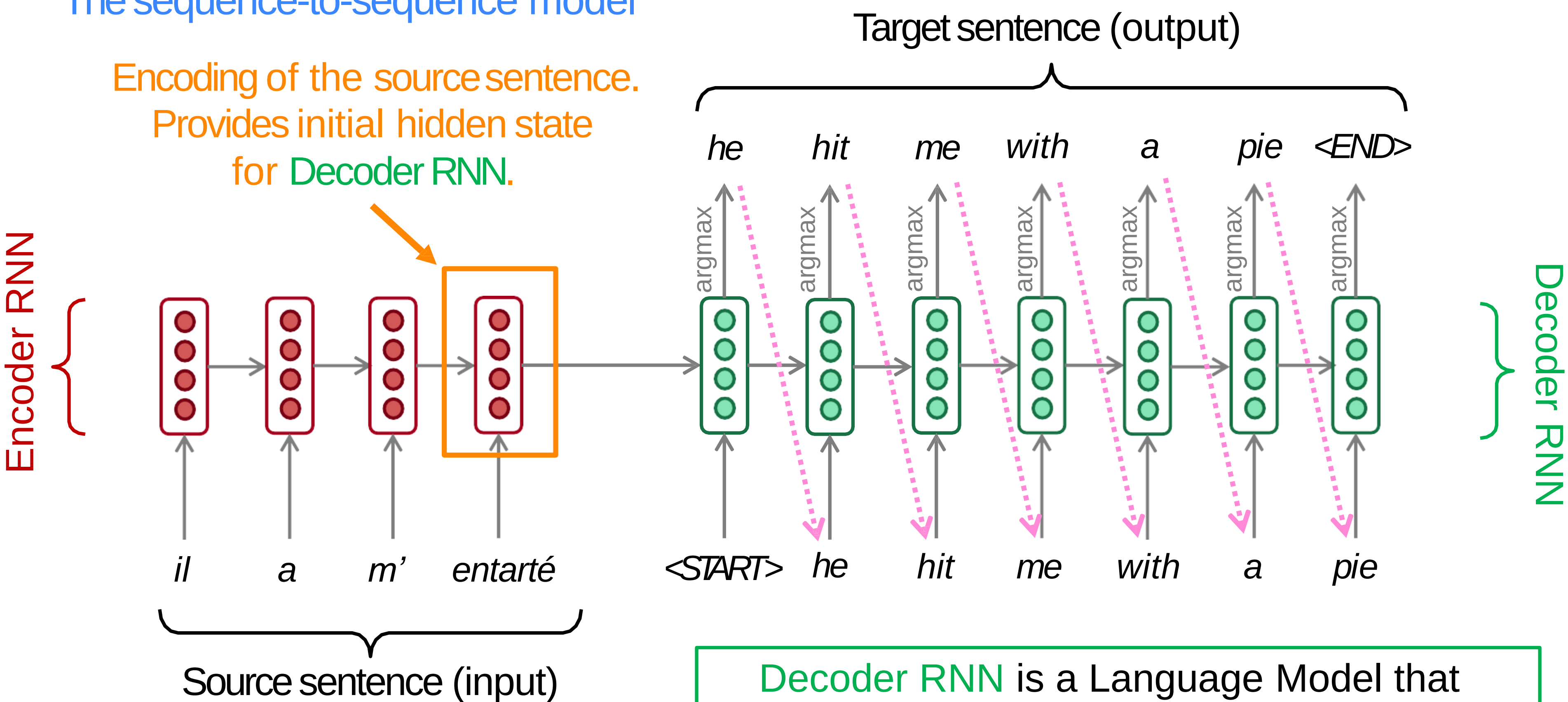
Neural Machine Translation

- Neural Machine Translation (NMT) is a way to do Machine Translation with a *single neural network*

- The neural network architecture is called sequence-to-sequence (aka seq2seq) and it involves *two* RNNs

Neural Machine Translation (NMT)

The sequence-to-sequence model



Encoder RNN produces an *encoding* of the source sentence.

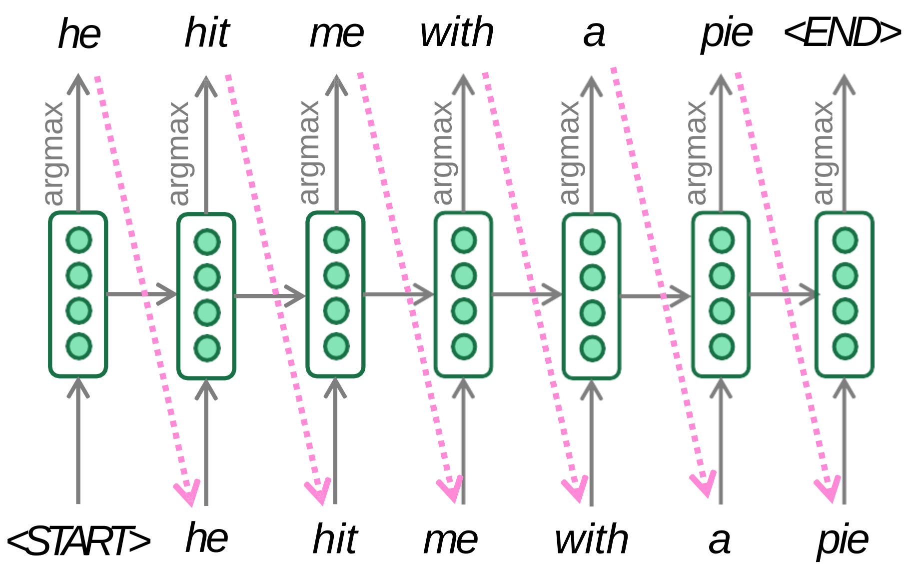
Decoder RNN is a Language Model that generates target sentence, *conditioned on encoding*.

Note: This diagram shows **test time** behavior: decoder output is fed in as next step's input

Abigail See

Greedy decoding

- We saw how to generate (or "decode") the target sentence by taking argmax on each step of the decoder



- This is greedy decoding (take most probable word on eachstep)
- **Problems with this method?**

Problems with greedy decoding

- Greedy decoding has no way to undo decisions!
  - <u>Input</u>: *il a m'entarté* *(he hit me with a pie)*
  - → *he* ___
  - → *he hit* ___
  - → *he hit a* ___ (whoops! no going back now…)
- How to fix this?

Exhaustive search decoding

- Ideally we want to find (length *T*) translation *y* that maximizes

$$P(y|x) = P(y_1|x)\,P(y_2|y_1,x)\,P(y_3|y_1,y_2,x)\ldots,P(y_T|y_1,\ldots,y_{T-1},x)$$
$$= \prod_{t=1}^{T} P(y_t|y_1,\ldots,y_{t-1},x)$$

- We could try computing all possible sequences *y*
  - This means that on each step *t* of the decoder, we're tracking V^T possible partial translations, where *V* is vocabulary size
  - This $O(V^T)$ complexity is far too expensive!

Beam search decoding

- Core idea: On each step of decoder, keep track of the *k* most probable partial translations (*hypotheses*)
  - *k* is the beam size (in practice around 5 to 10)

- A hypothesis $y_1, \ldots, y_t$ has a score which is its log probability:

$$\text{score}(y_1, \ldots, y_t) = \log P_{\text{LM}}(y_1, \ldots, y_t | x) = \sum_{i=1}^{t} \log P_{\text{LM}}(y_i | y_1, \ldots, y_{i-1}, x)$$

  - Scores are all negative, and higher score is better
  - We search for high-scoring hypotheses, tracking top *k* on each step

- Beam search is not guaranteed to find optimal solution
- But much more efficient than exhaustive search!

Beam search decoding: example

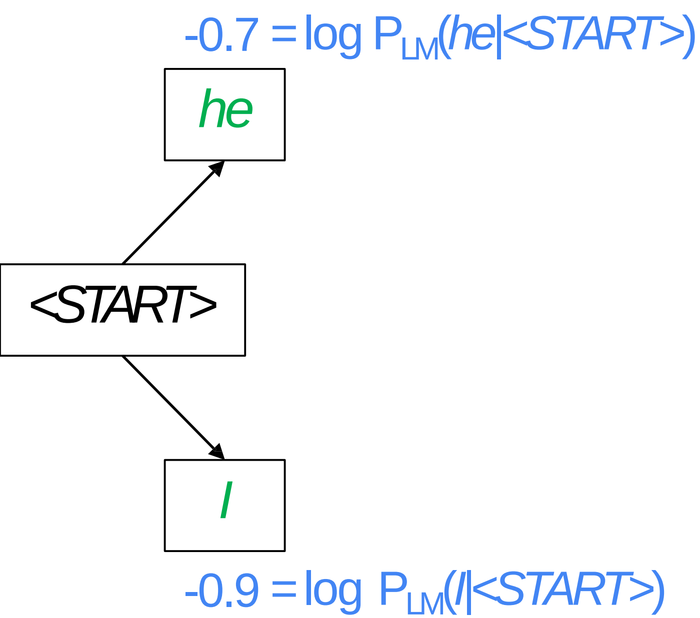
Beam size = k = 2. Blue numbers = $\text{score}(y_1, \ldots, y_t) = \sum_{i=1}^{t} \log P_{\text{LM}}(y_i | y_1, \ldots, y_{i-1}, x)$

<START>

Calculate prob dist of next word

Beam search decoding: example

Beam size = k = 2. Blue numbers = $\text{score}(y_1, \ldots, y_t) = \sum_{i=1}^{t} \log P_{\text{LM}}(y_i | y_1, \ldots, y_{i-1}, x)$



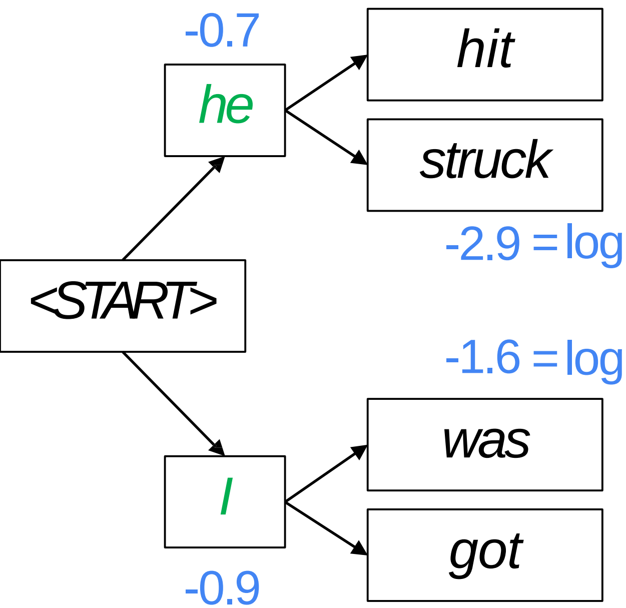
Take top *k* words
and compute scores

Abigail See

Beam search decoding: example

Beam size = k = 2. Blue numbers = $\text{score}(y_1, \ldots, y_t) = \sum_{i=1}^{t} \log P_{\text{LM}}(y_i | y_1, \ldots, y_{i-1}, x)$

-1.7 = log P_{LM}(*hit*|*<START> he*) + -0.7



-2.9 = log P_{LM}(*struck*|*<START> he*) + -0.7

-1.6 = log P_{LM}(*was*|*<START> I*) + -0.9

-1.8 = log P_{LM}(*got*|*<START> I*) + -0.9

For each of the *k* hypotheses, find top *k* next words and calculate scores

Abigail See

Beam search decoding: example

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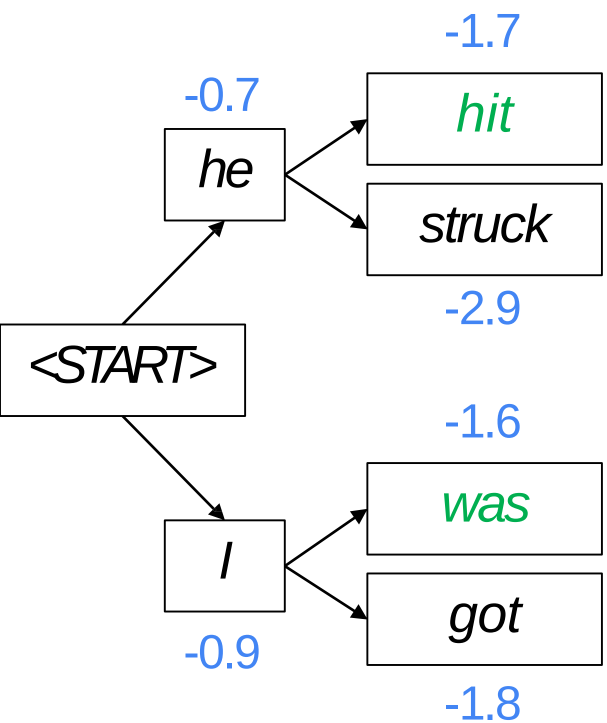

Of these k^2 hypotheses,
just keep k with highest scores

Abigail See

Beam search decoding: example

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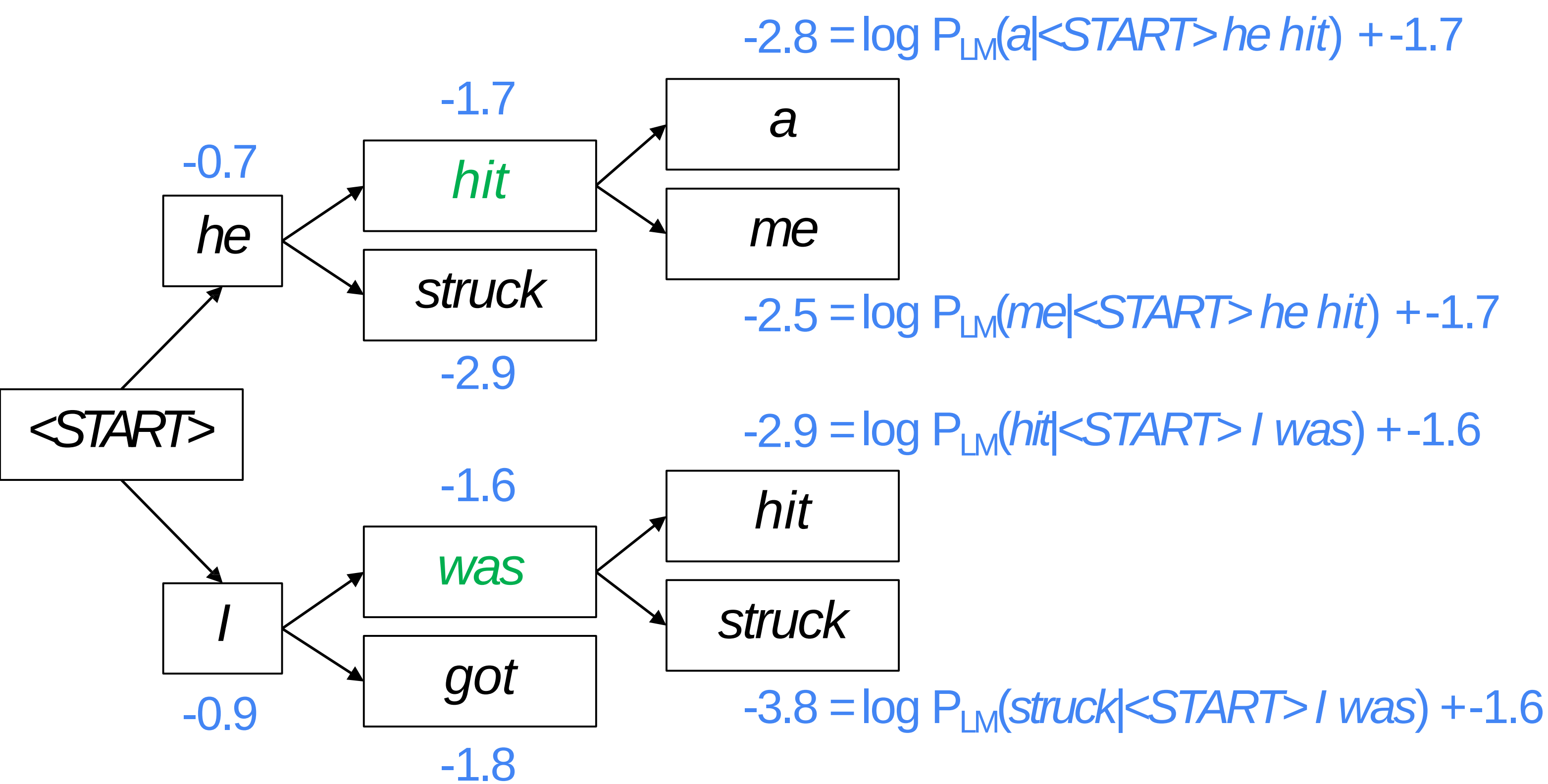

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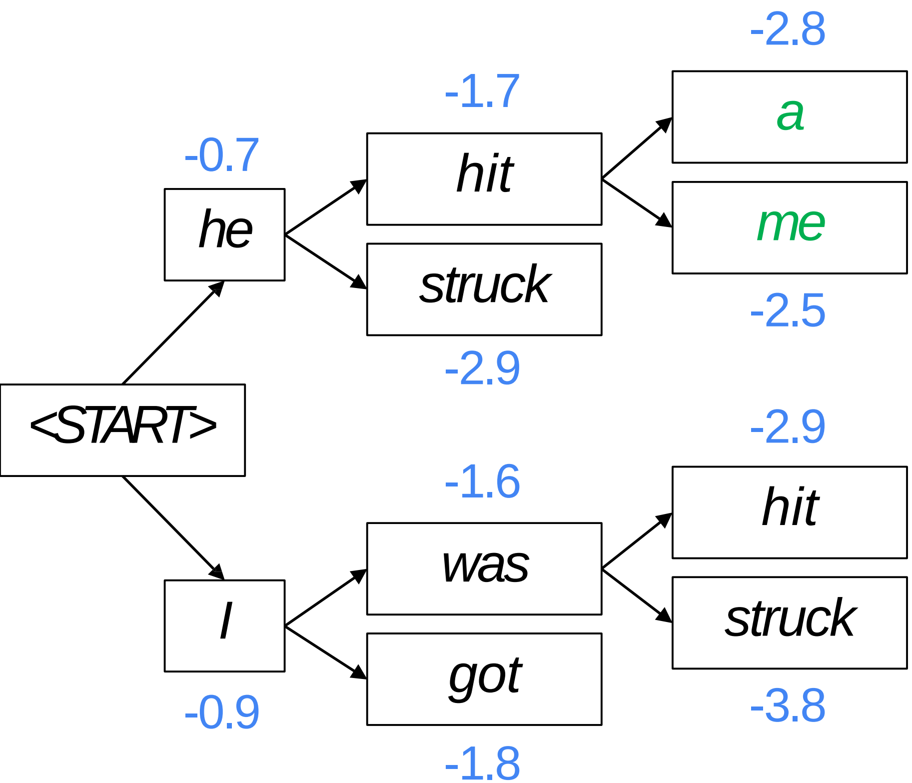

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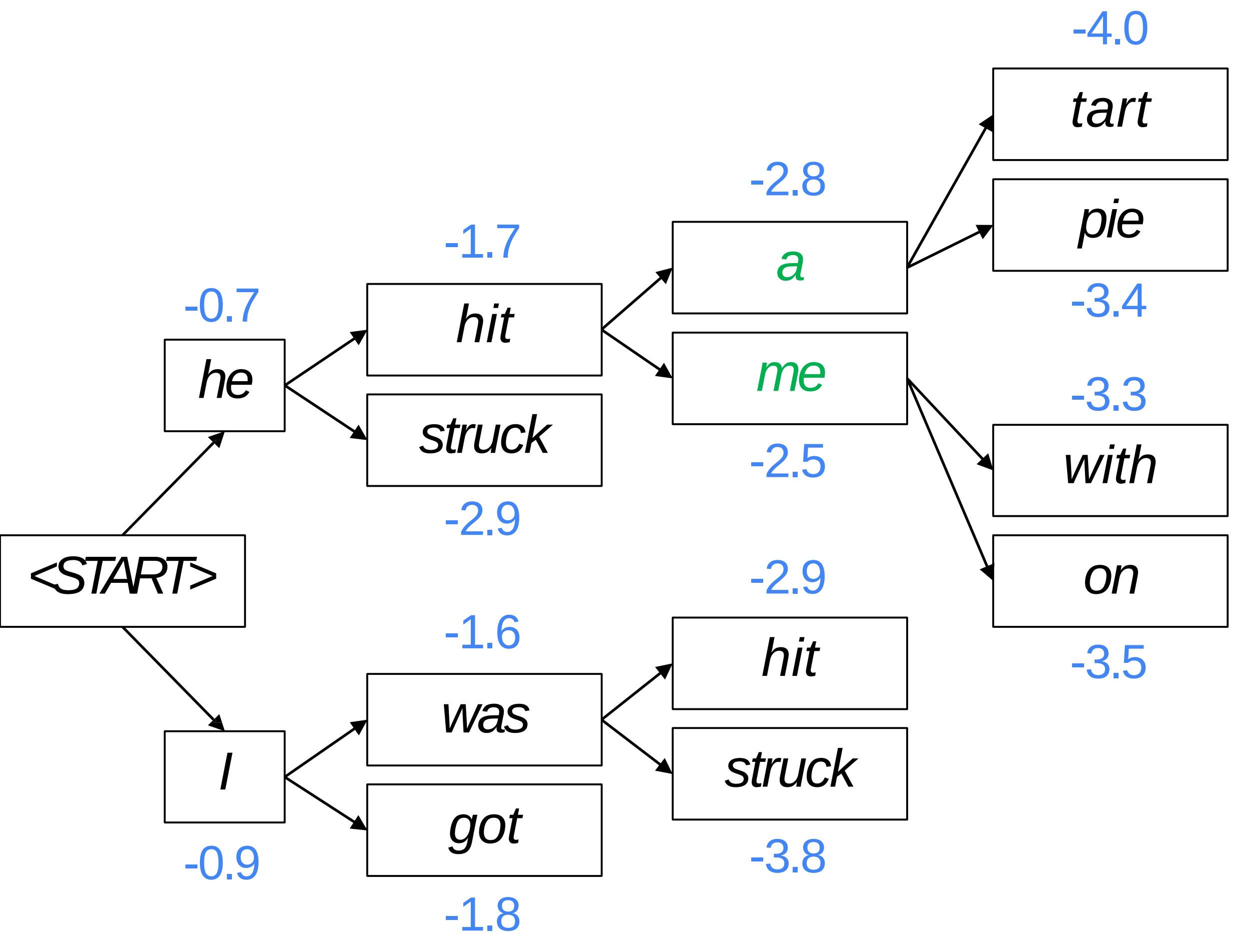

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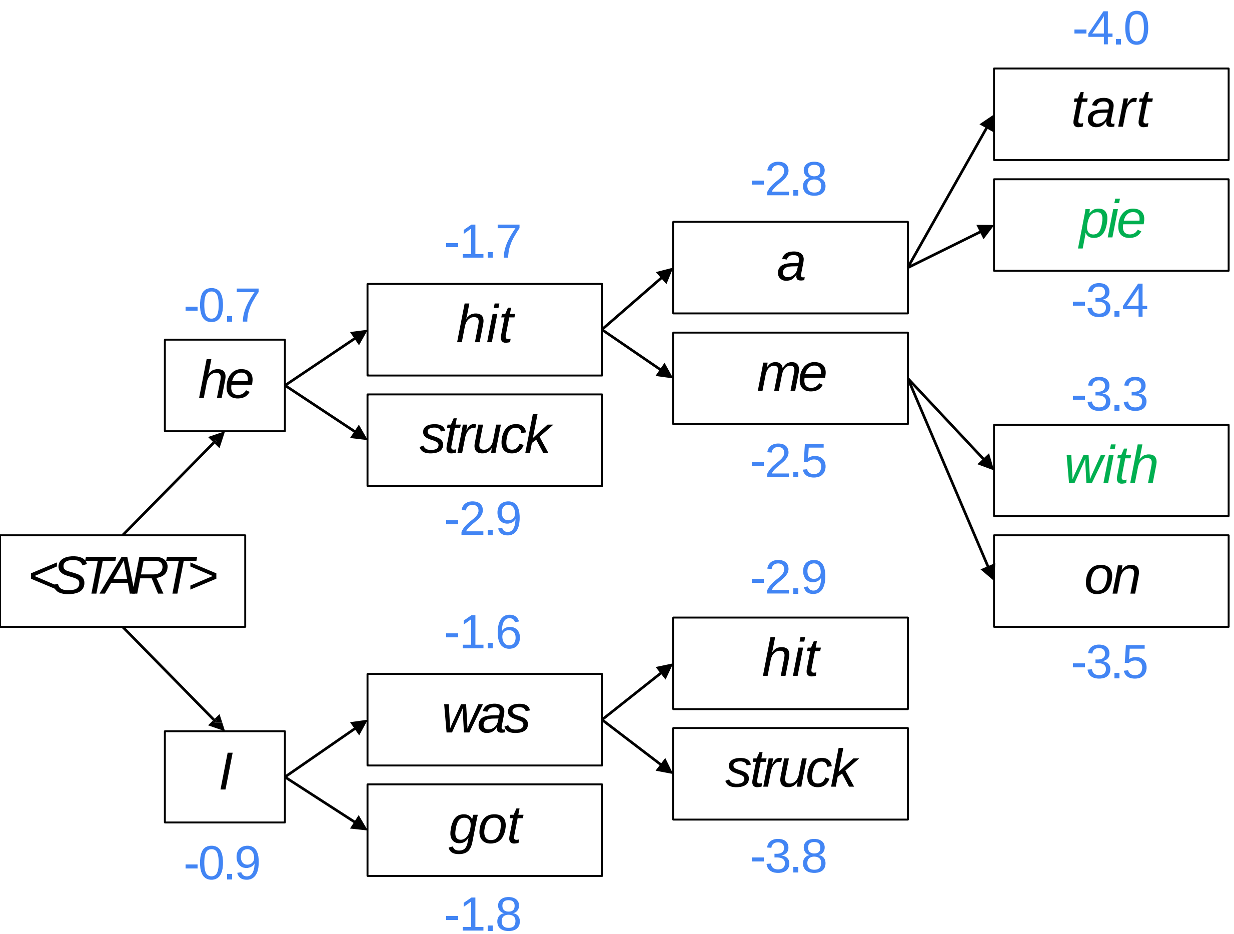

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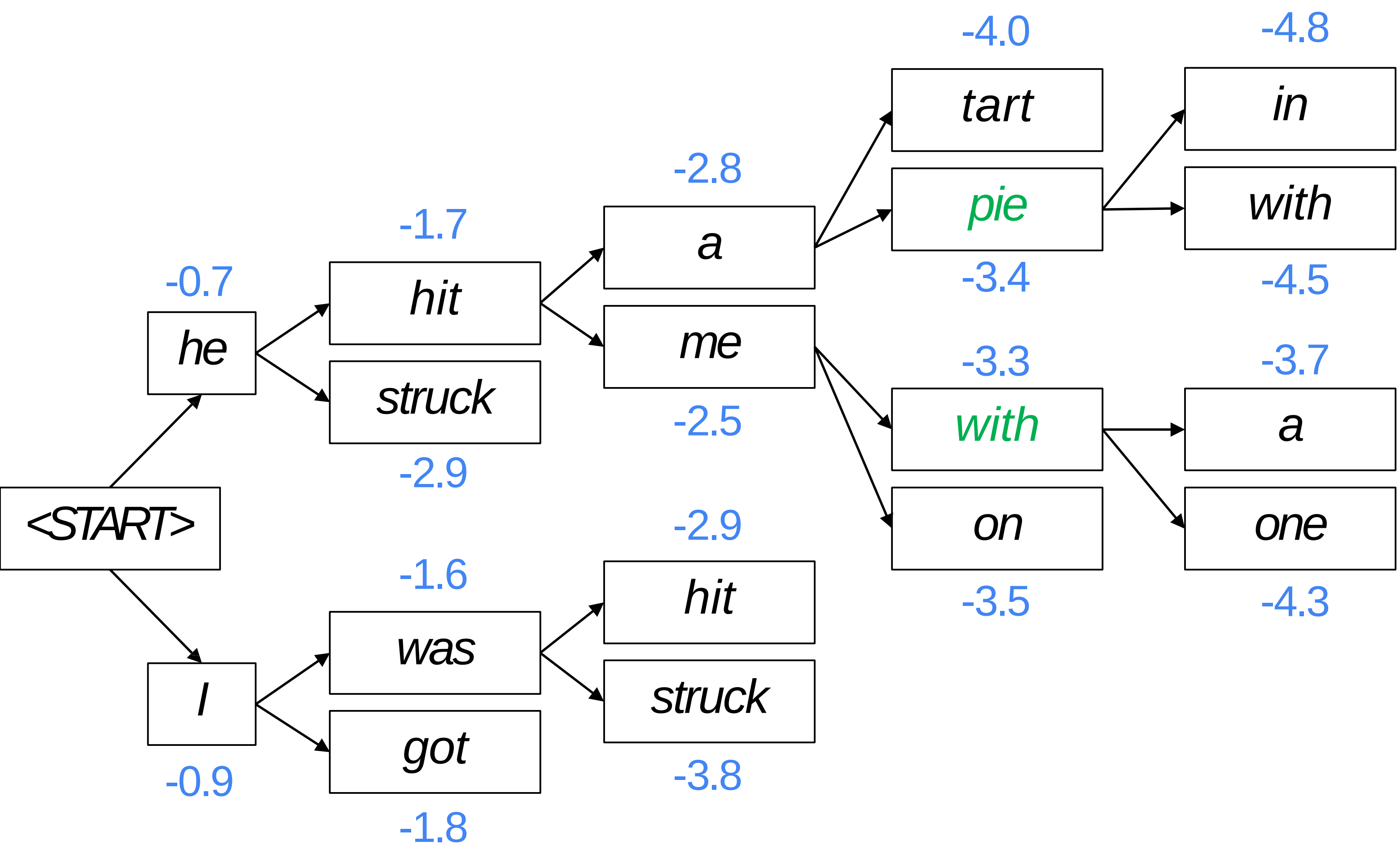

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Abigail See

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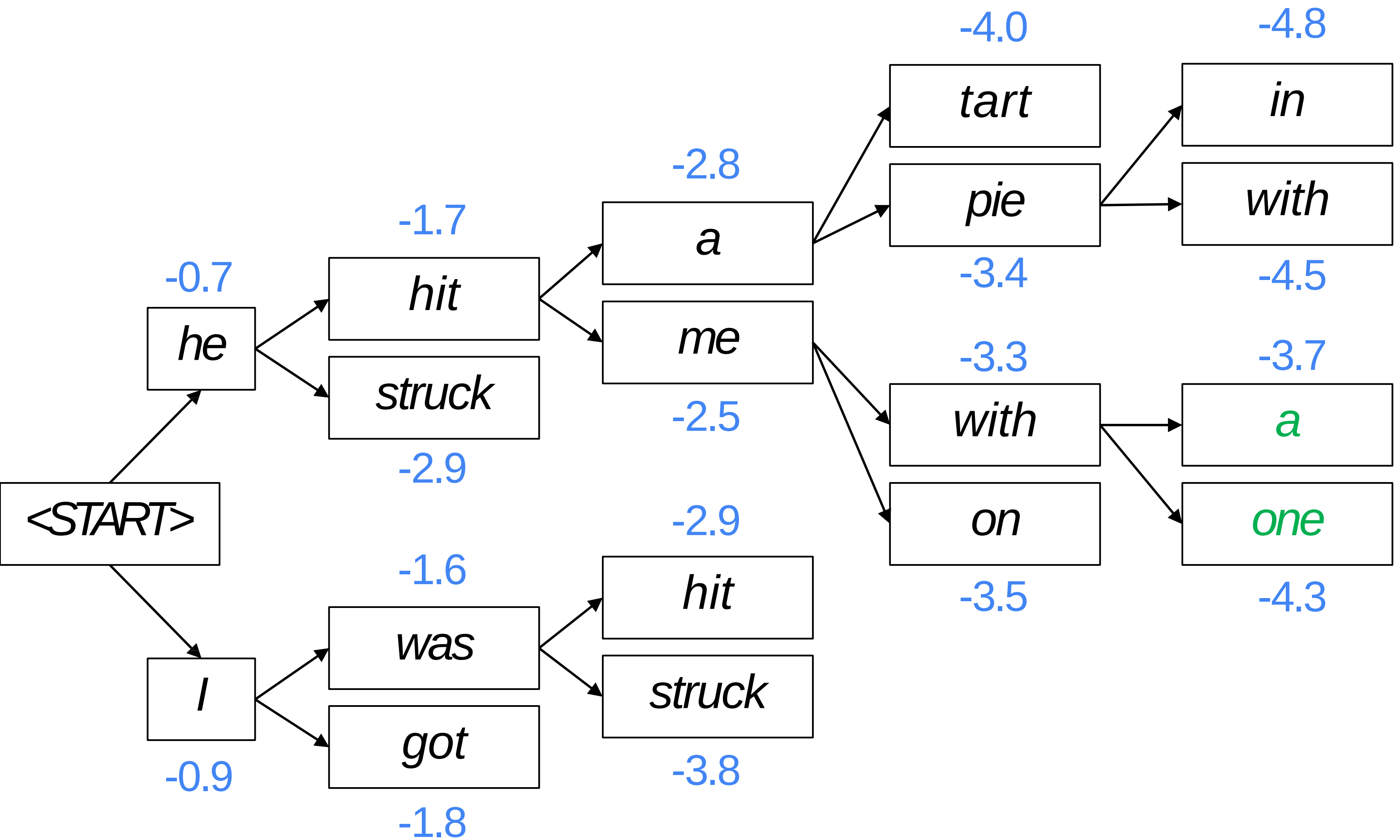

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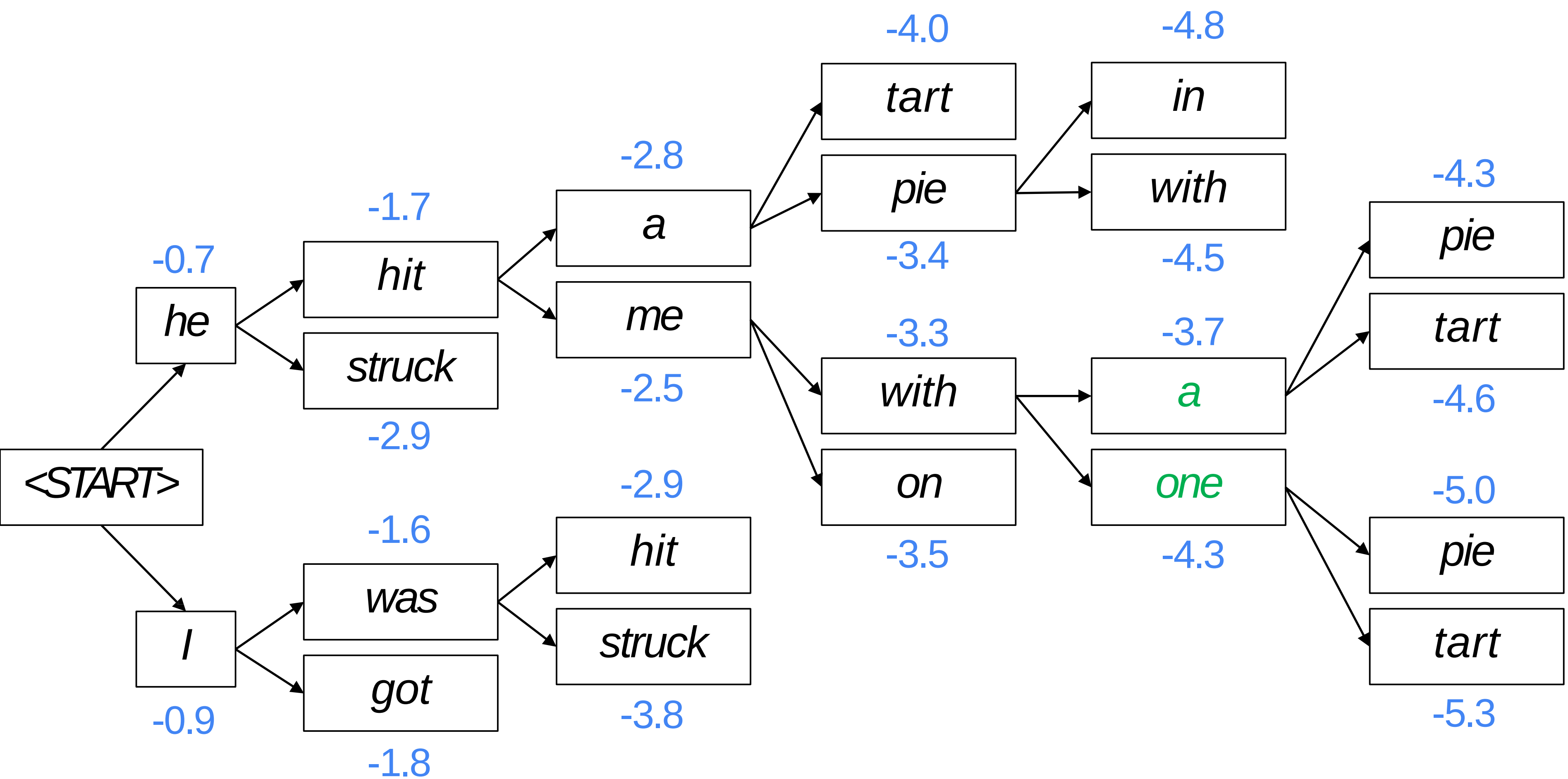

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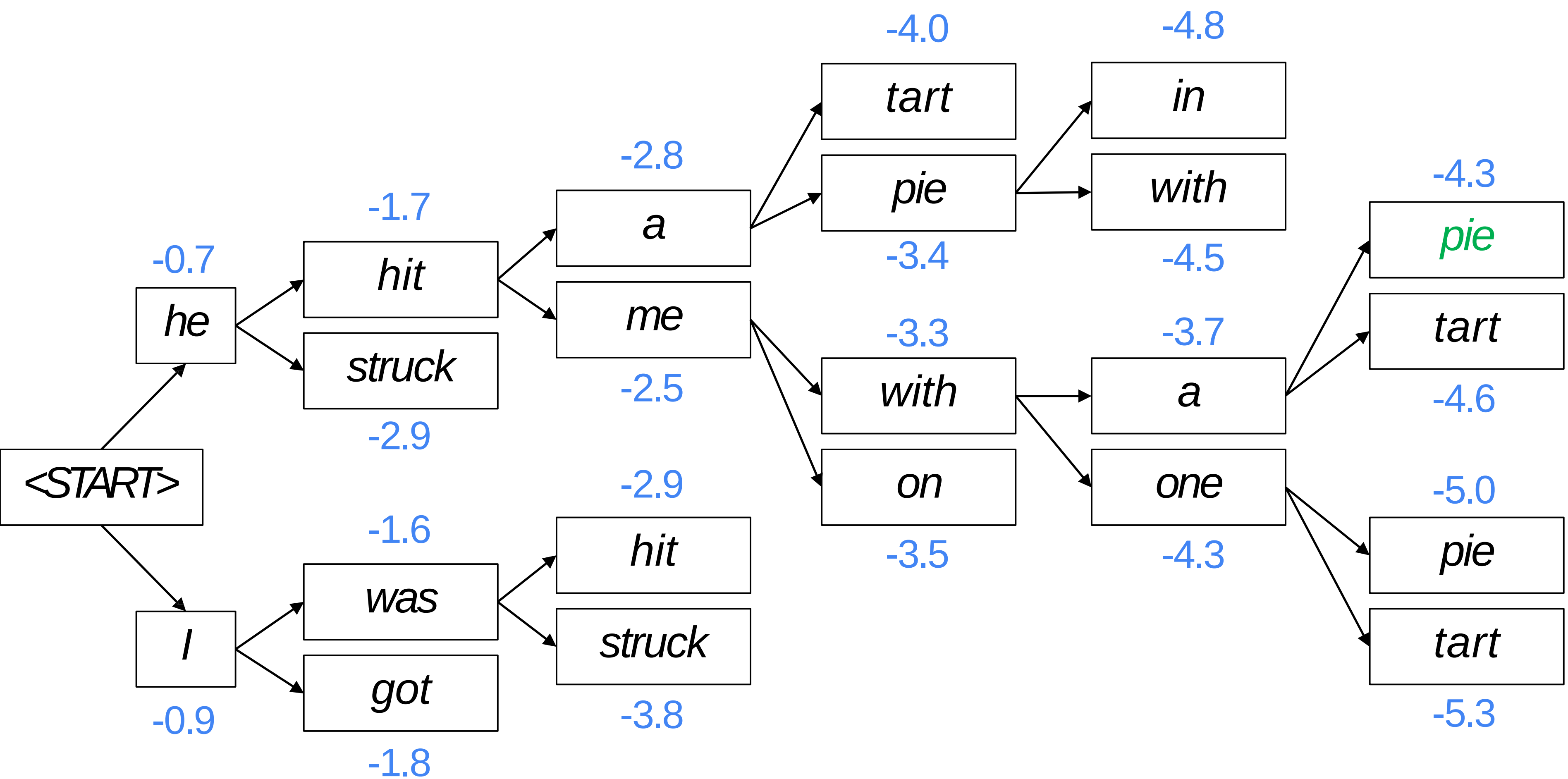

This is the top-scoring hypothesis!

Abigail See

Beam search decoding: example

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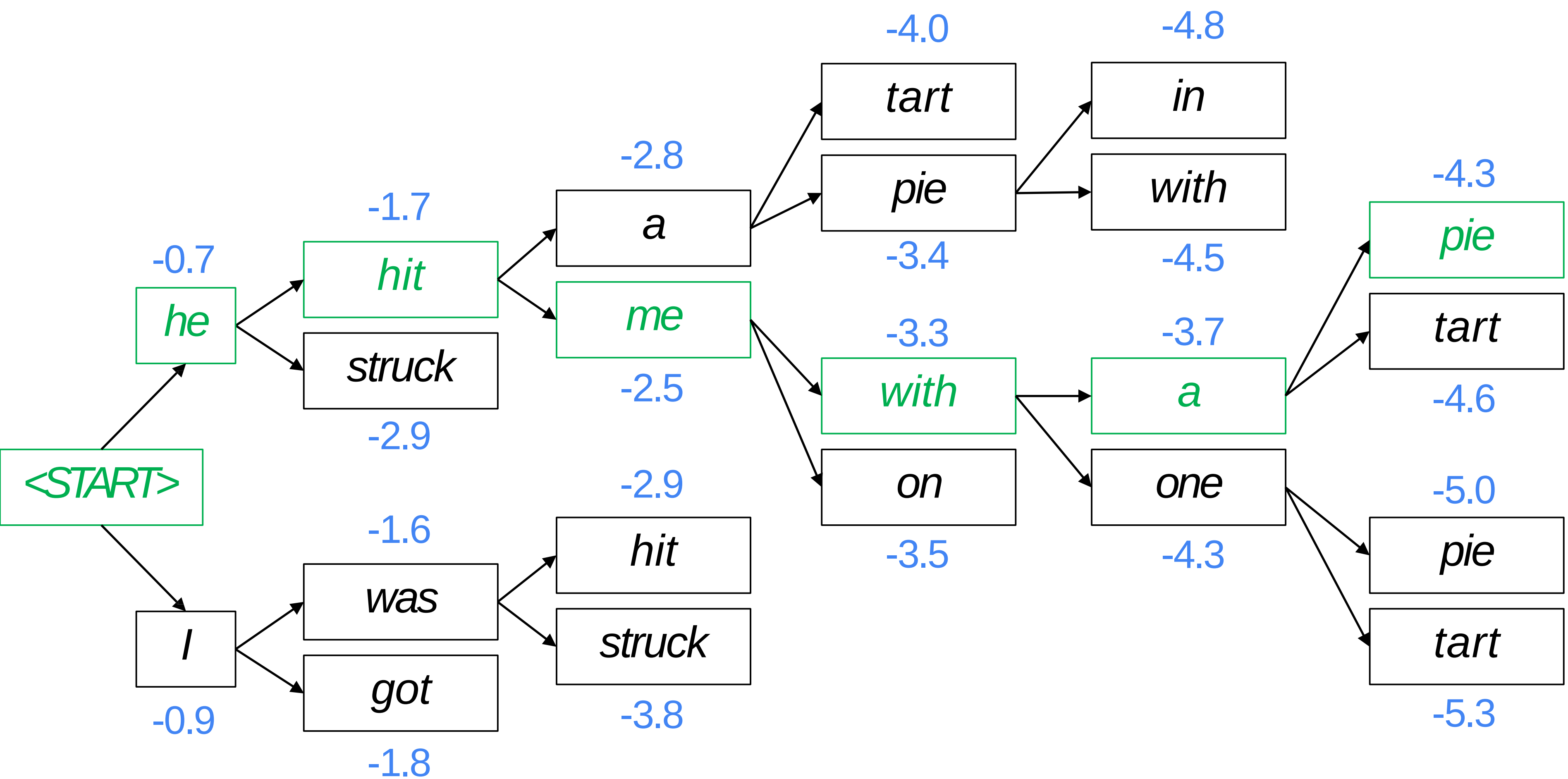


Backtrack to obtain the full hypothesis

Abigail See

Beam search decoding: finishing up

- We have our list of completed hypotheses.
- How to select top one with highest score?

- Each hypothesis $y_1, \dots, y_t$ on our list has a score

$$\text{score}(y_1, \dots, y_t) = \log P_{\text{LM}}(y_1, \dots, y_t | x) = \sum_{i=1}^{t} \log P_{\text{LM}}(y_i | y_1, \dots, y_{i-1}, x)$$

- <u>Problem with this:</u> longer hypotheses have lower scores

- <u>Fix:</u> Normalize by length. Use this to select top one instead:

$$\frac{1}{t} \sum_{i=1}^{t} \log P_{\text{LM}}(y_i | y_1, \dots, y_{i-1}, x)$$

How do we evaluate Machine Translation?

BLEU (**B**ilingual **E**valuation **U**nderstudy)

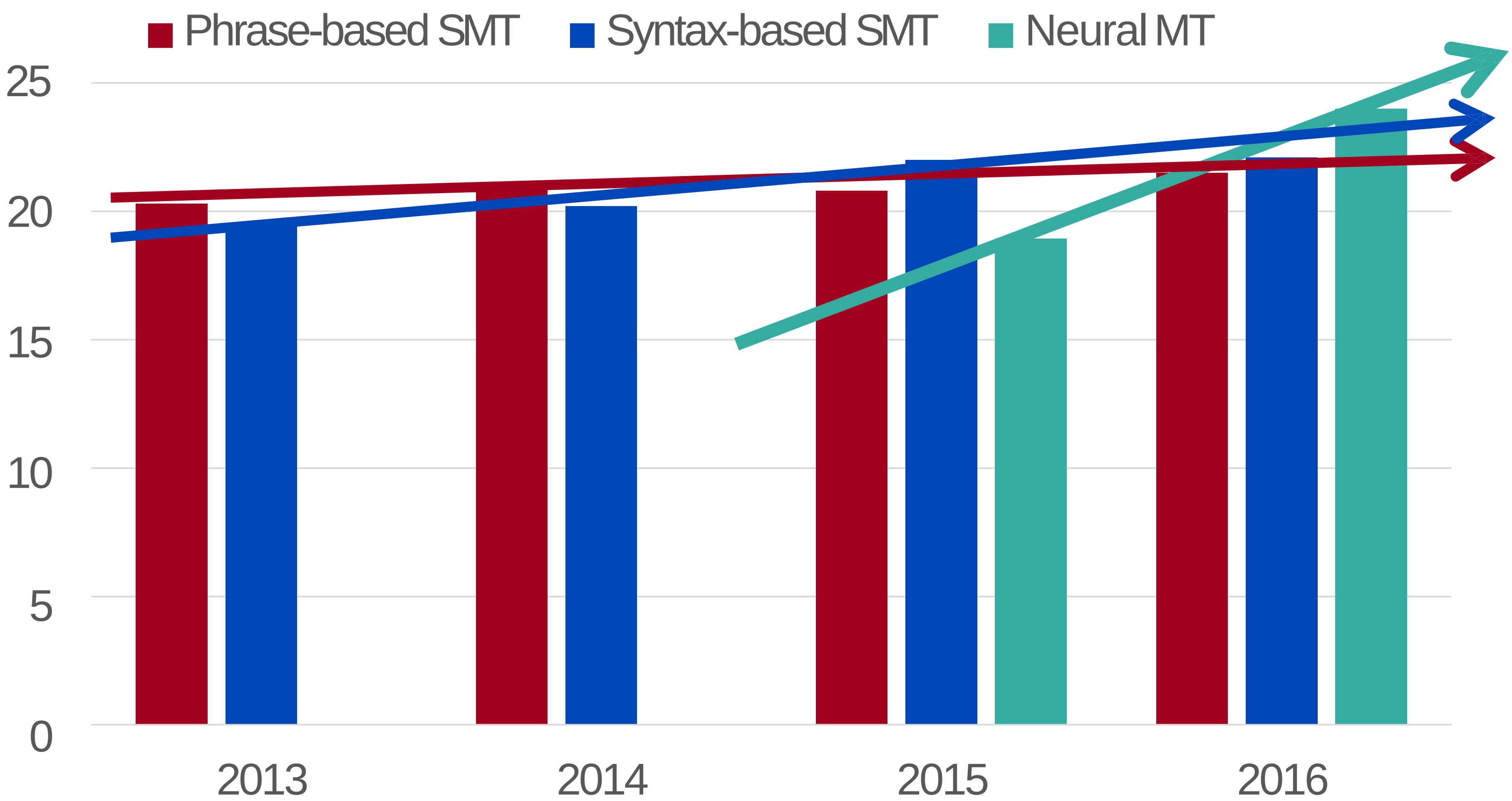
- BLEU compares the machine-written translation to one or several human-written translation(s), and computes a similarity score based on:
  - *n*-gram precision (usually for 1, 2, 3 and 4-grams)
  - Plus a penalty for too-short system translations

- BLEU is useful but imperfect
  - There are many valid ways to translate a sentence
  - So a good translation can get a poor BLEU score because it has low *n*-gram overlap with the human translation ☹

Source: " BLEU: a Method for Automatic Evaluation of Machine Translation", Papineni et al, 2002.

MT progress over time

[Edinburgh En-De WMT newstest2013 Cased BLEU; NMT 2015 from U. Montréal]



Source: http://www.meta-net.eu/events/meta-forum-2016/slides/09_sennrich.pdf

NMT: the biggest success story of NLP Deep Learning

Neural Machine Translation went from a fringe research activity in **2014** to the leading standard method in **2016**

- **2014**: First seq2seq paper published
- **2016**: Google Translate switches from SMT to NMT
- This is amazing!
  - **SMT** systems, built by hundreds of engineers over many years, outperformed by NMT systems trained by a handful of engineers in a few months

So is Machine Translation solved?

- **Nope!**
- Many difficulties remain:
  - Out-of-vocabulary words
  - Domain mismatch between train and test data
  - Maintaining context over longer text
  - Low-resource language pairs

Further reading: *"Has AI surpassed humans at translation? Not even close!"*
https://www.skynettoday.com/editorials/state_of_nmt

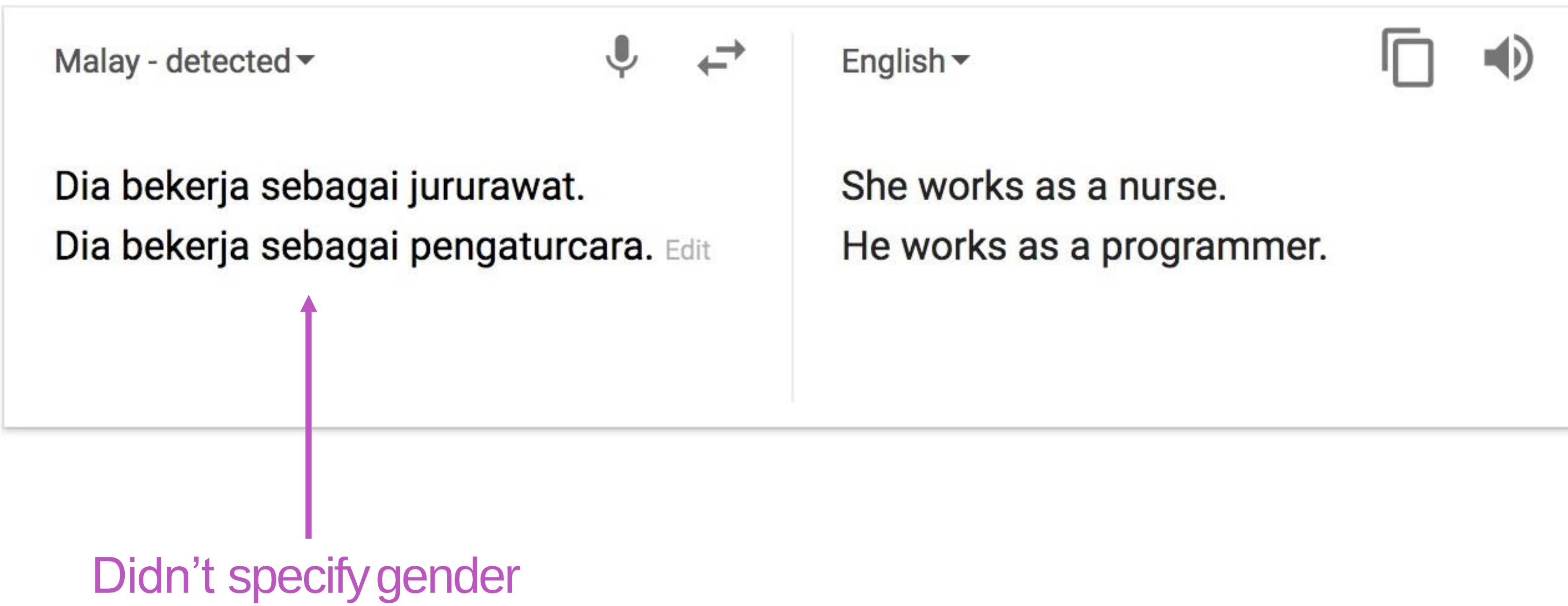
So is Machine Translation solved?

- **Nope!**
- Using common sense is still hard

?

So is Machine Translation solved?

- **Nope!**
- NMT picks up biases in training data



Source: https://hackernoon.com/bias-sexist-or-this-is-the-way-it-should-be-ce1f7c8c683c

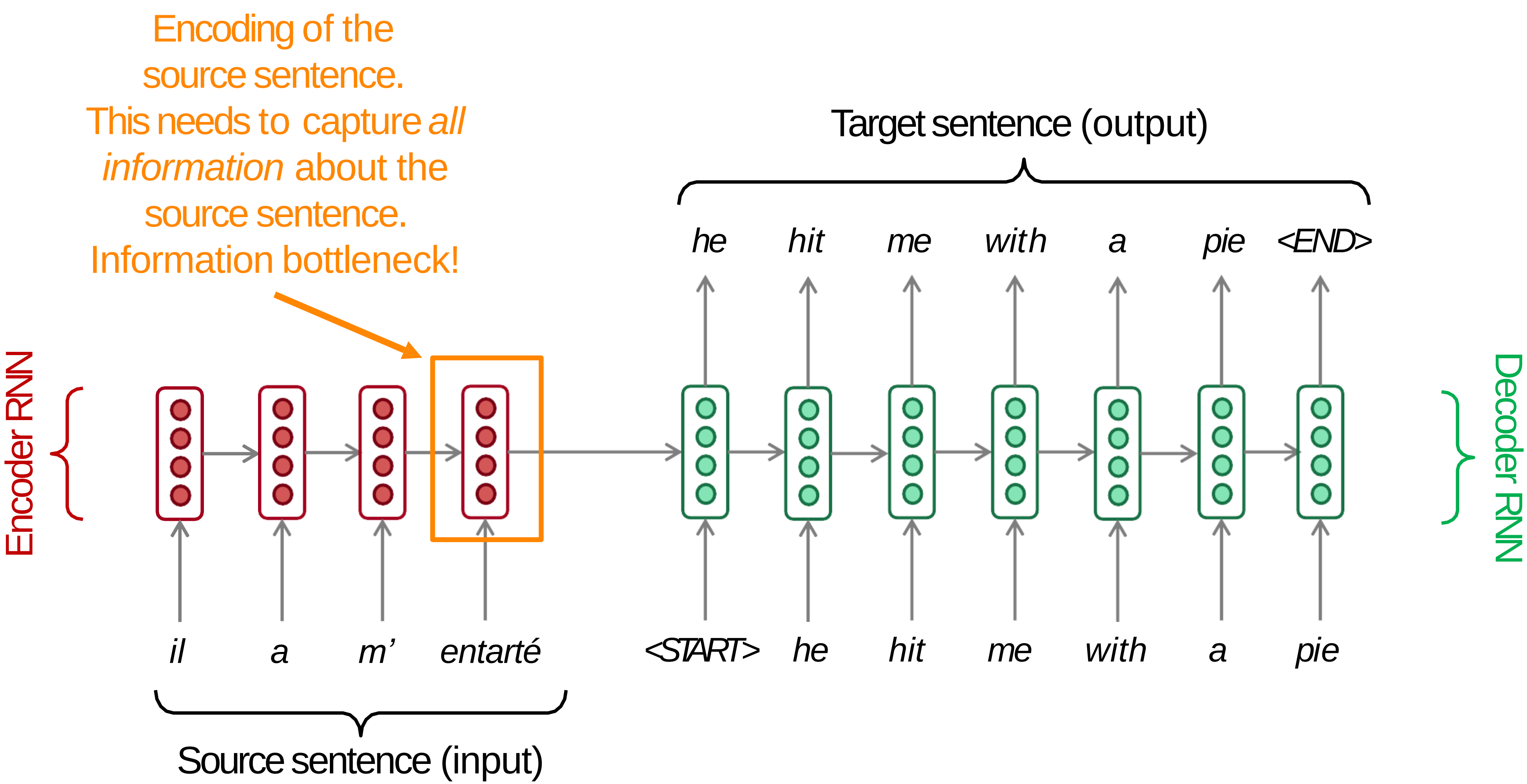
NMT research continues

NMT is the **flagship task** for NLP Deep Learning

- NMT research has pioneered many of the recent innovations of NLP Deep Learning
- In **2019**: NMT research continues to thrive
    - Researchers have found *many, many* improvements to the "vanilla" seq2seq NMT system
    - But one improvement is so integral that it is the new vanilla…

ATTENTION

Sequence-to-sequence: the bottleneck problem



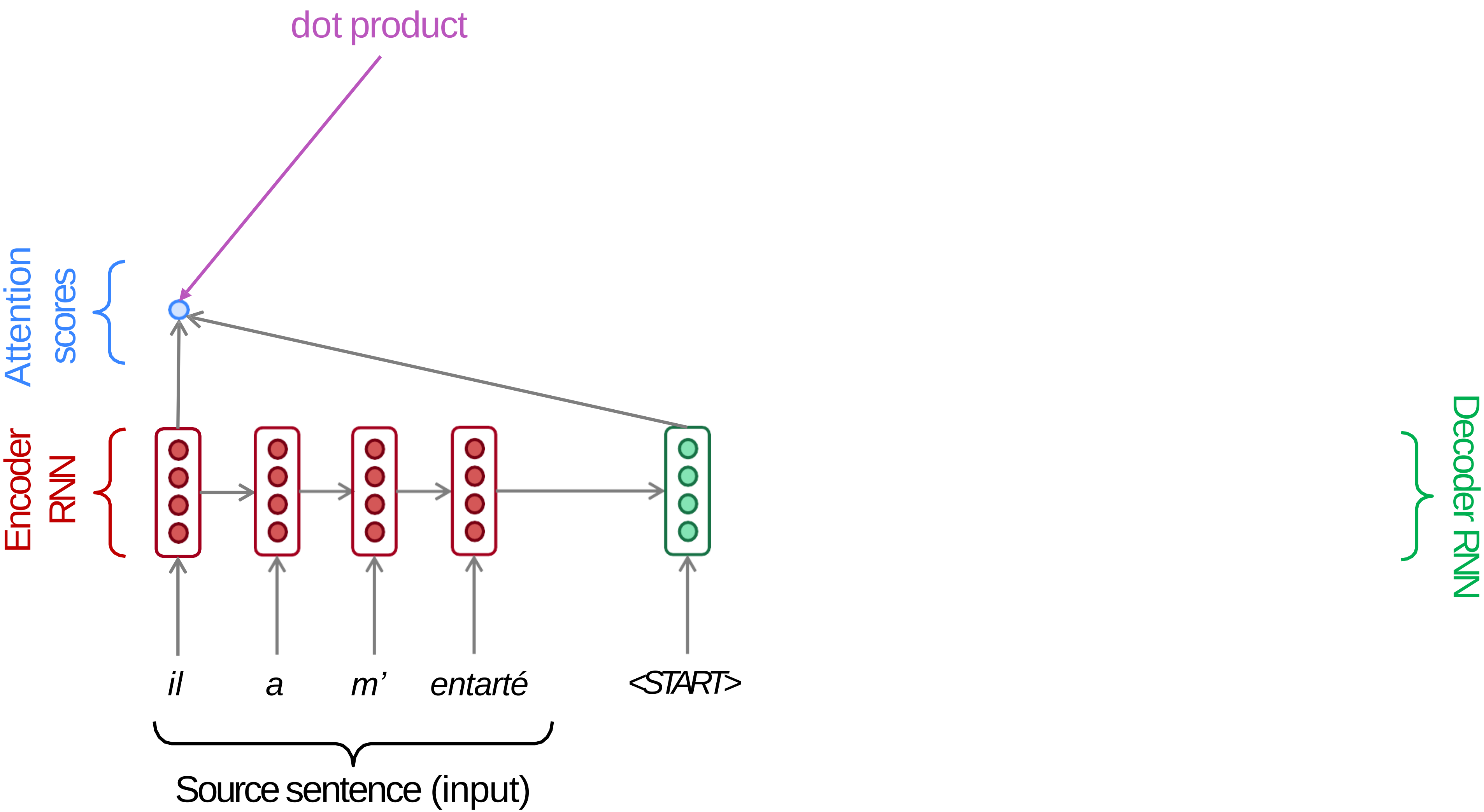
Attention

- **Attention** provides a solution to the bottleneck problem.

- Core idea: on each step of the decoder, use *direct connection to the encoder* to *focus on a particular part* of the source sequence

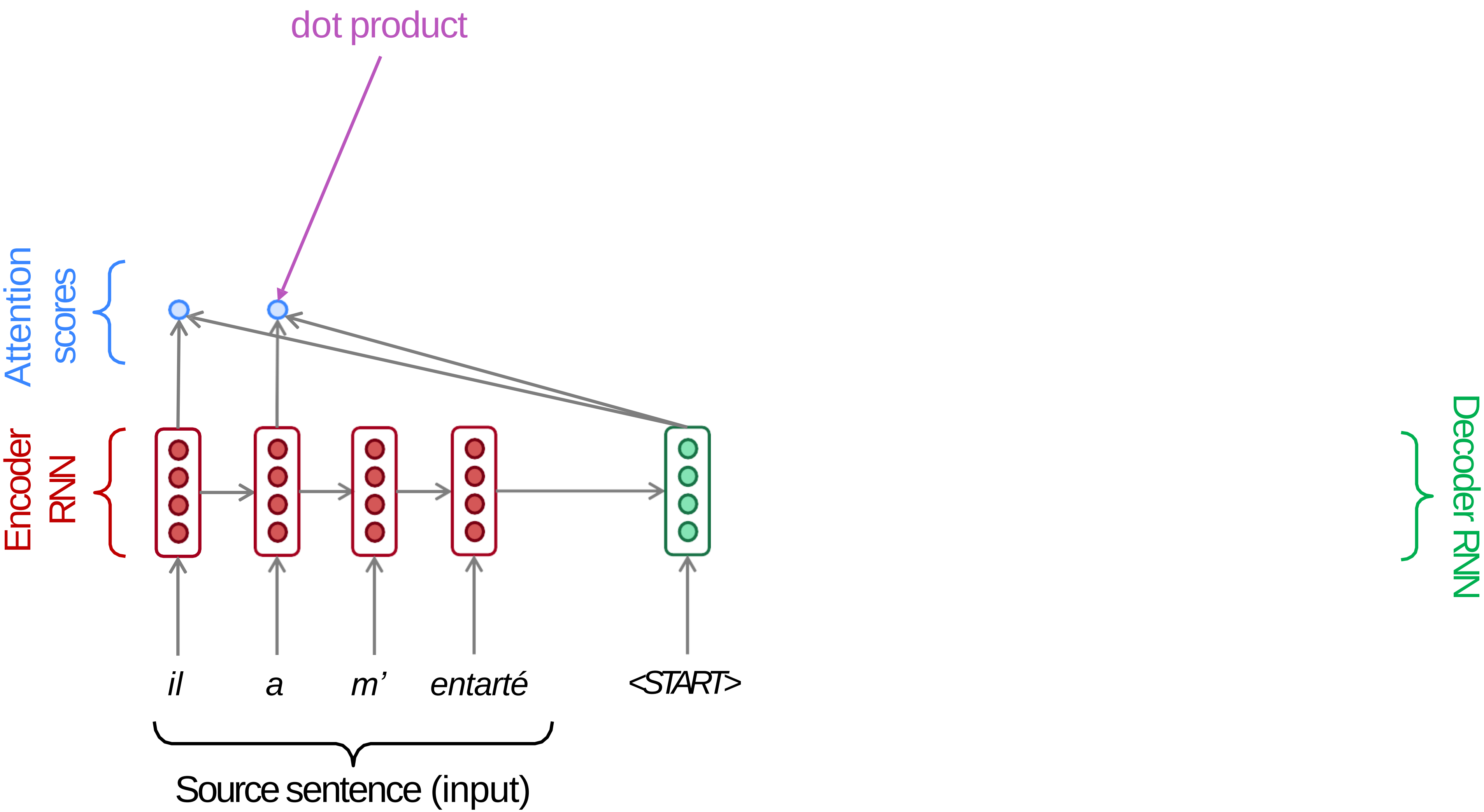
- First we will show via diagram (no equations), then we will show with equations

Sequence-to-sequence with attention



Abigail See

Sequence-to-sequence with attention



Abigail See

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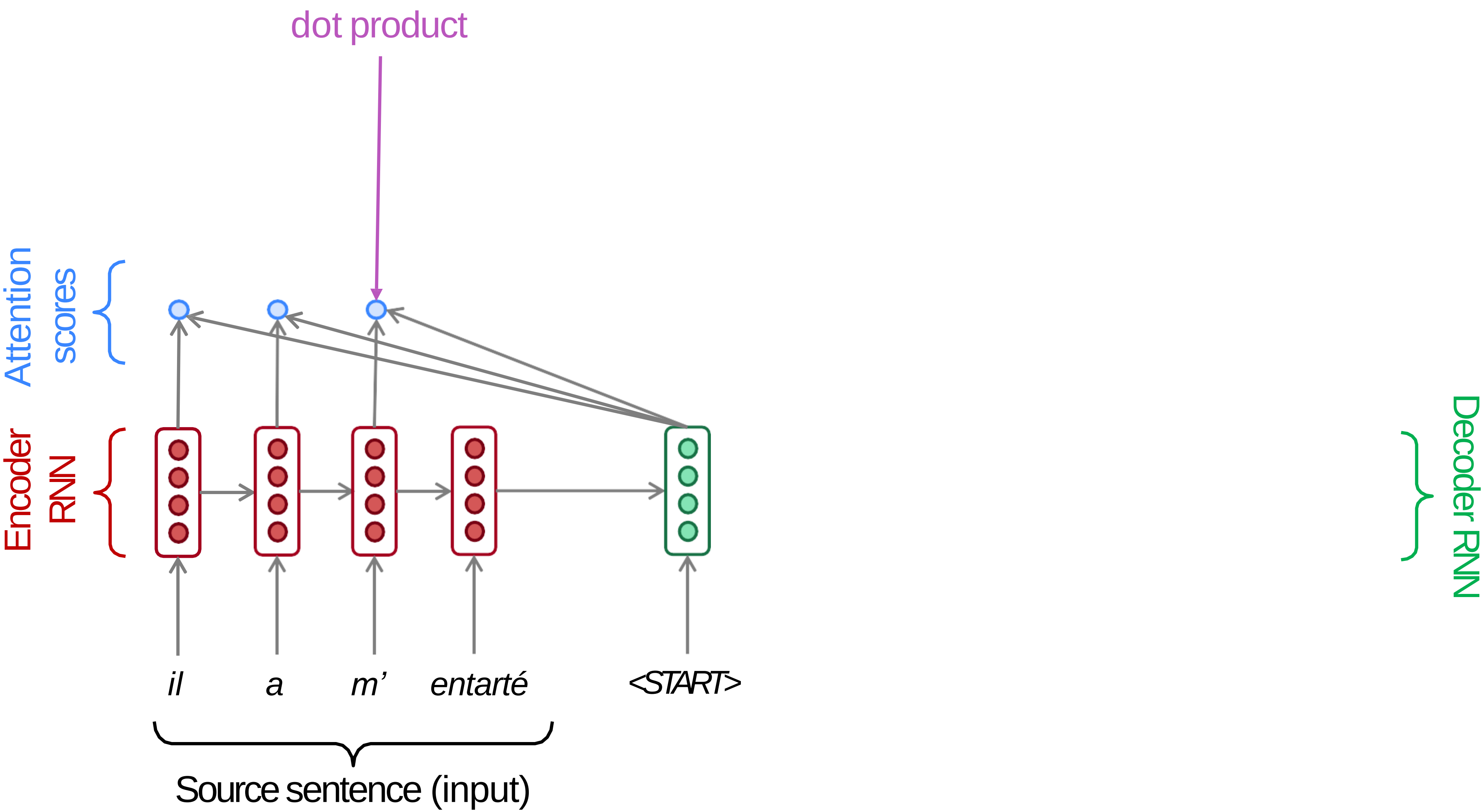

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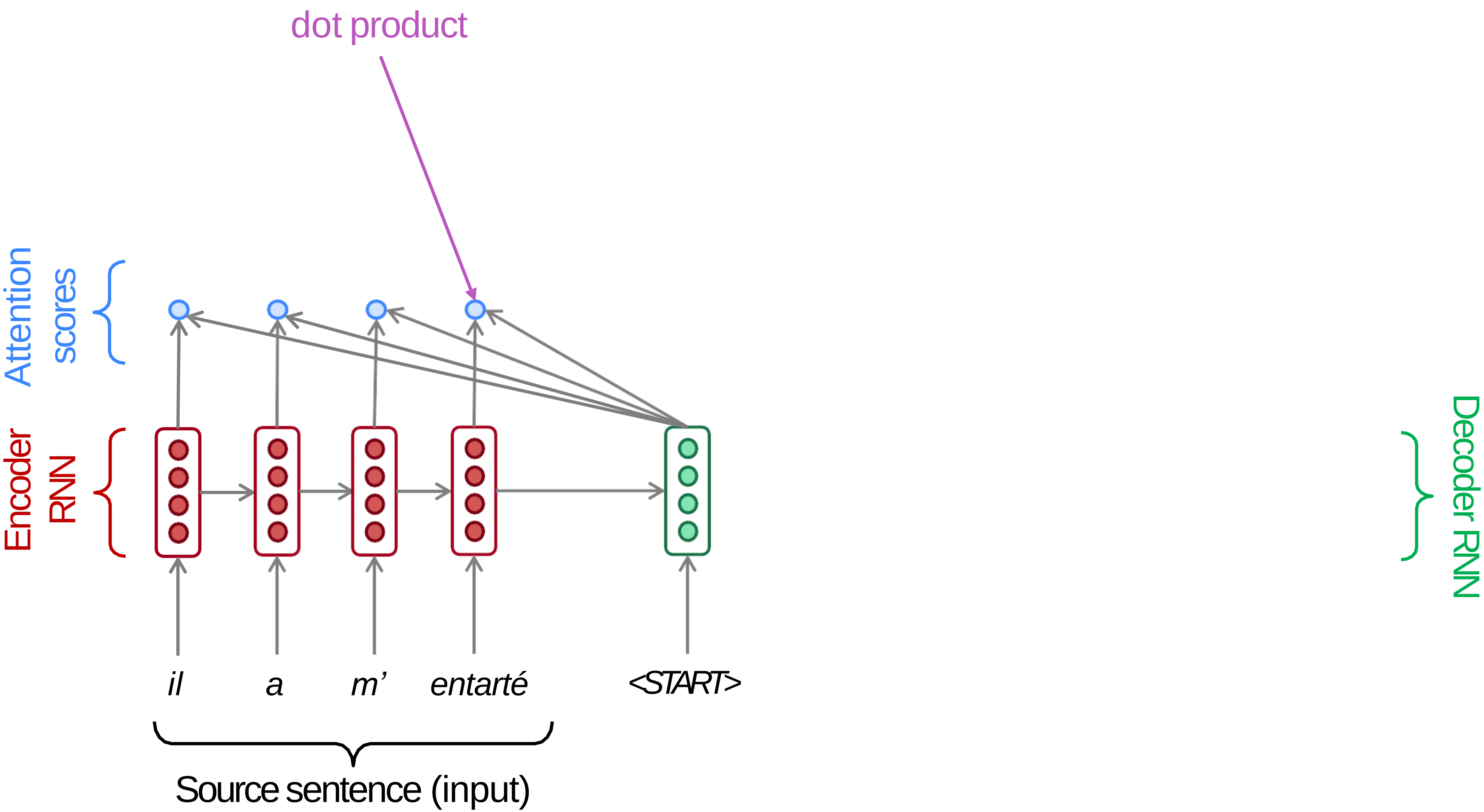

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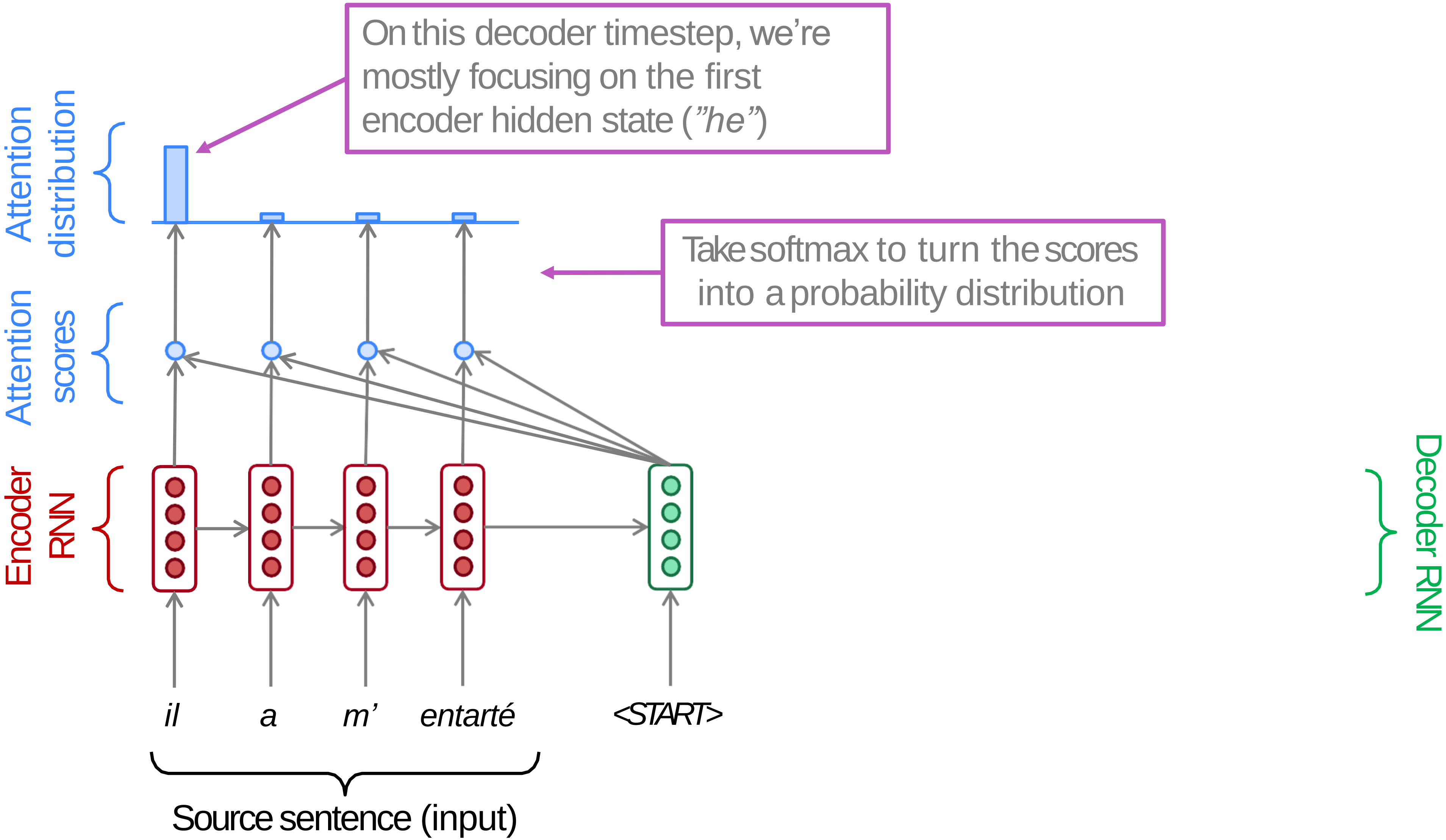

Abigail See

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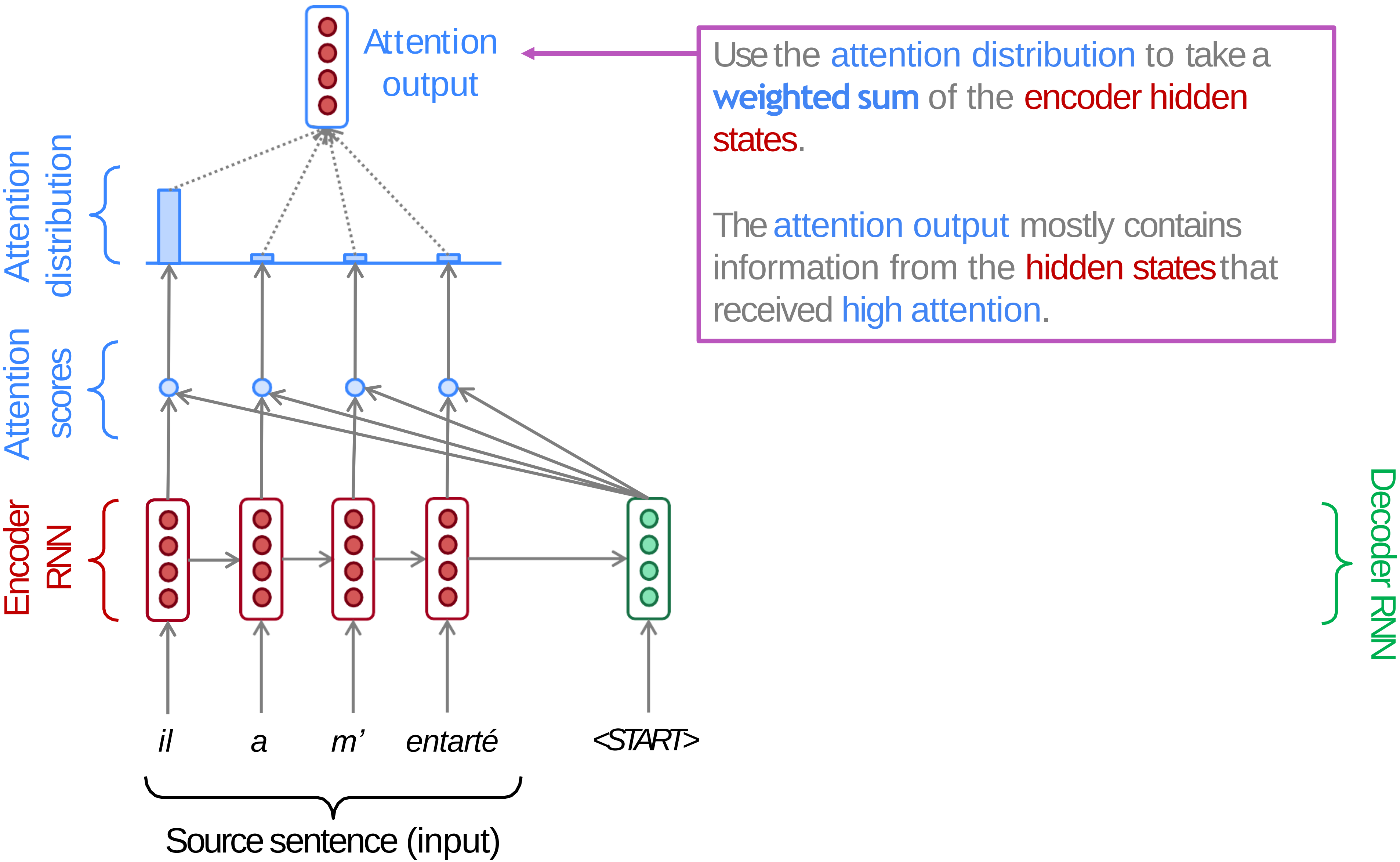
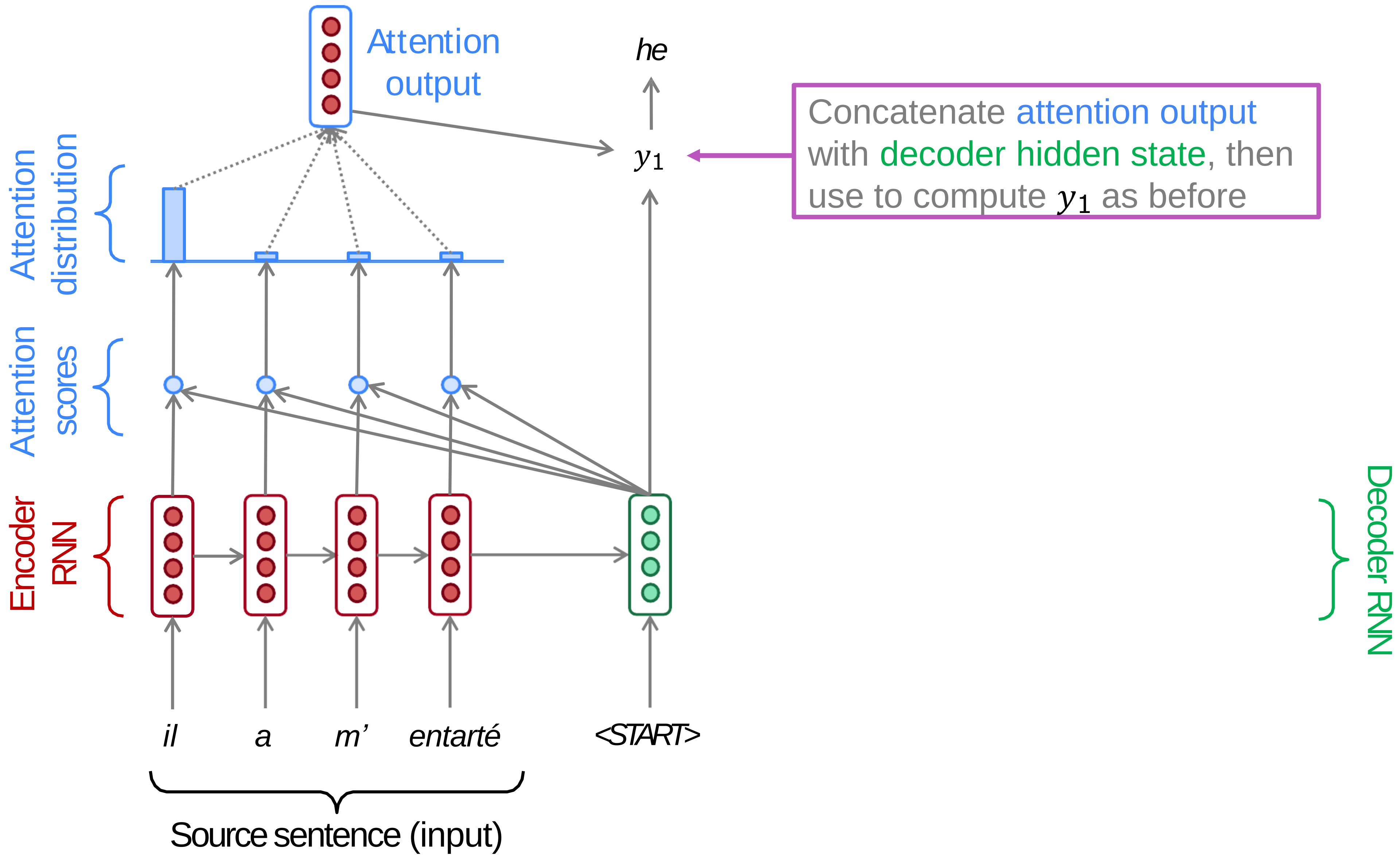


Use the attention distribution to take a **weighted sum** of the encoder hidden states.

The attention output mostly contains information from the hidden states that received high attention.

Abigail See

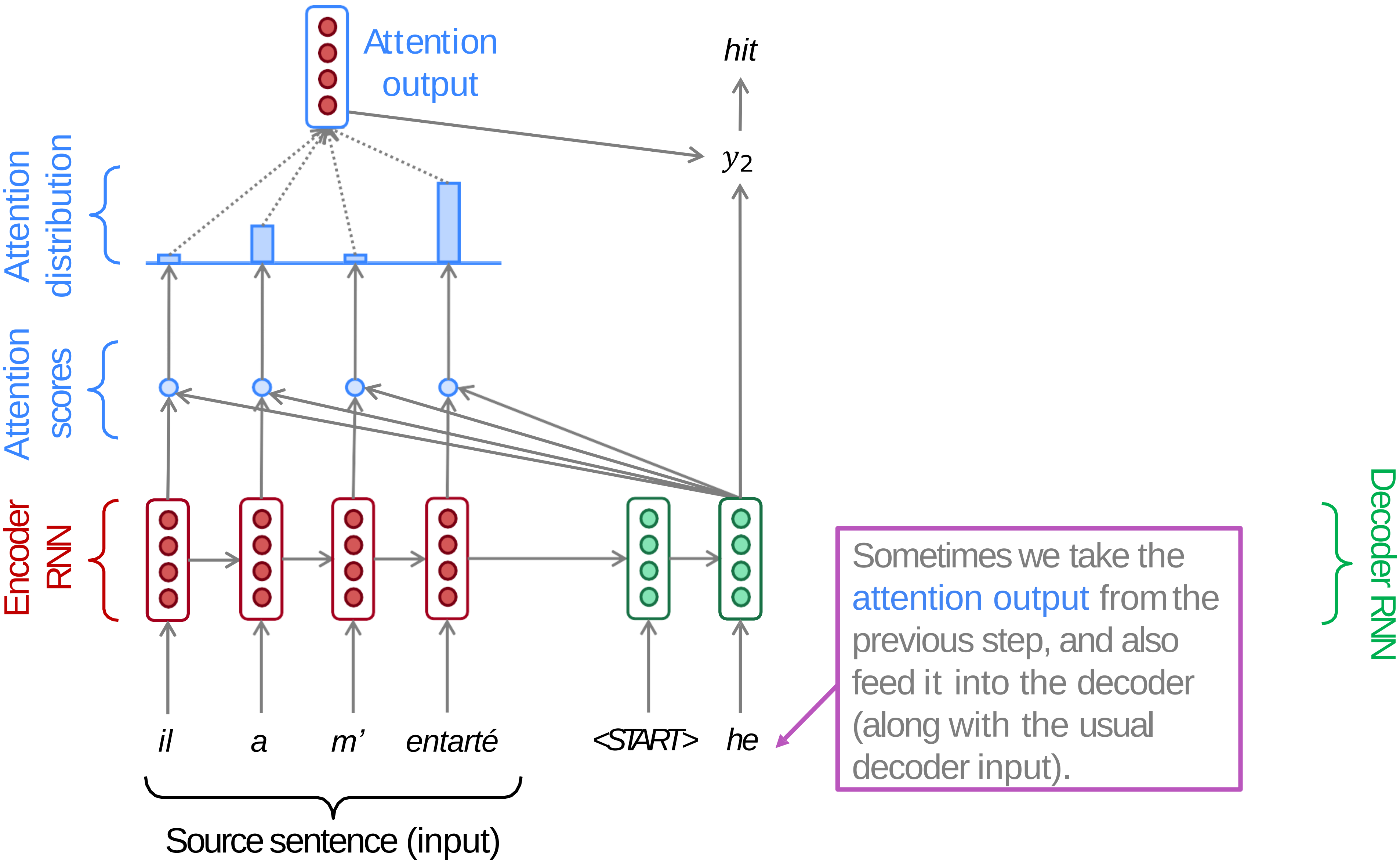
Sequence-to-sequence with attention



Concatenate attention output with decoder hidden state, then use to compute y_1 as before

Abigail See

Sequence-to-sequence with attention



Sometimes we take the attention output from the previous step, and also feed it into the decoder (along with the usual decoder input).

Abigail See

Attention: in equations

- We have encoder hidden states $h_1, \ldots, h_N \in \mathbb{R}^h$
- On timestep *t*, we have decoder hidden state $s_t \in \mathbb{R}^h$
- We get the attention score $\boldsymbol{e}^t$ for this step:

$$\boldsymbol{e}^t = [\boldsymbol{s}_t^T \boldsymbol{h}_1, \ldots, \boldsymbol{s}_t^T \boldsymbol{h}_N] \in \mathbb{R}^N$$

- We take softmax to get the attention distribution α^t for this step (this is a probability distribution and sums to 1)

$$\alpha^t = \mathrm{softmax}(\boldsymbol{e}^t) \in \mathbb{R}^N$$

- We use α^t to take a weighted sum of the encoder hidden states to get the attention output $\boldsymbol{a}_t$

$$\boldsymbol{a}_t = \sum_{i=1}^{N} \alpha_i^t \boldsymbol{h}_i \in \mathbb{R}^h$$

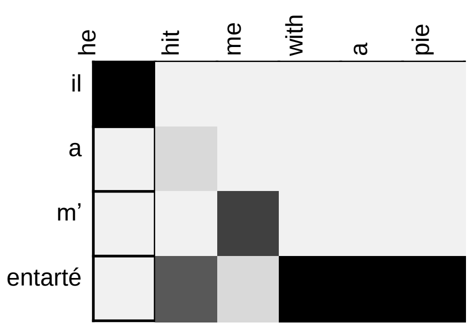
- Finally we concatenate the attention output $\boldsymbol{a}_t$ with the decoder hidden state s_t and proceed as in the non-attention seq2seq model

$$[\boldsymbol{a}_t; \boldsymbol{s}_t] \in \mathbb{R}^{2h}$$

Abigail See

Attention is great

- Attention significantly improves NMT performance
  - It’s very useful to allow decoder to focus on certain parts of the source
- Attention solves the bottleneck problem
  - Attention allows decoder to look directly at source; bypass bottleneck
- Attention helps with vanishing gradient problem
  - Provides shortcut to faraway states
- Attention provides some interpretability
  - By inspecting attention distribution, we can see what the decoder was focusing on
  - We get (soft) alignment for free!
  - This is cool because we never explicitly trained an alignment system
  - The network just learned alignment by itself



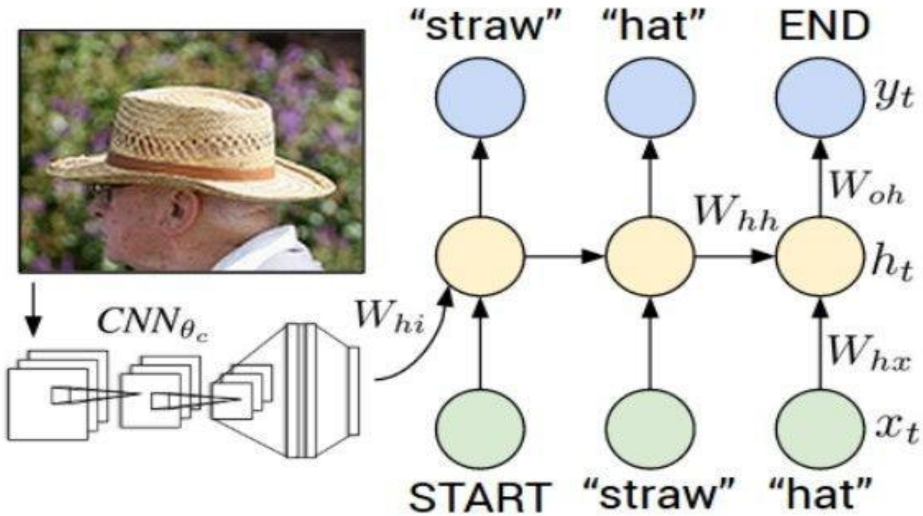
Attention is a *general* Deep Learning technique

- We've seen that attention is a great way to improve the sequence-to-sequence model for Machine Translation.
- However: You can use attention in many architectures (not just seq2seq) and many tasks (not just MT)

- **More general definition of attention**:
  - Given a set of vector *values*, and a vector *query*, **attention** is a technique to compute a weighted sum of the values, dependent on the query.

- We sometimes say that the query *attends to* the values.
- For example, in seq2seq + attention model, each decoder hidden state (query) *attends to* all encoder hidden states (values).

Image Captioning

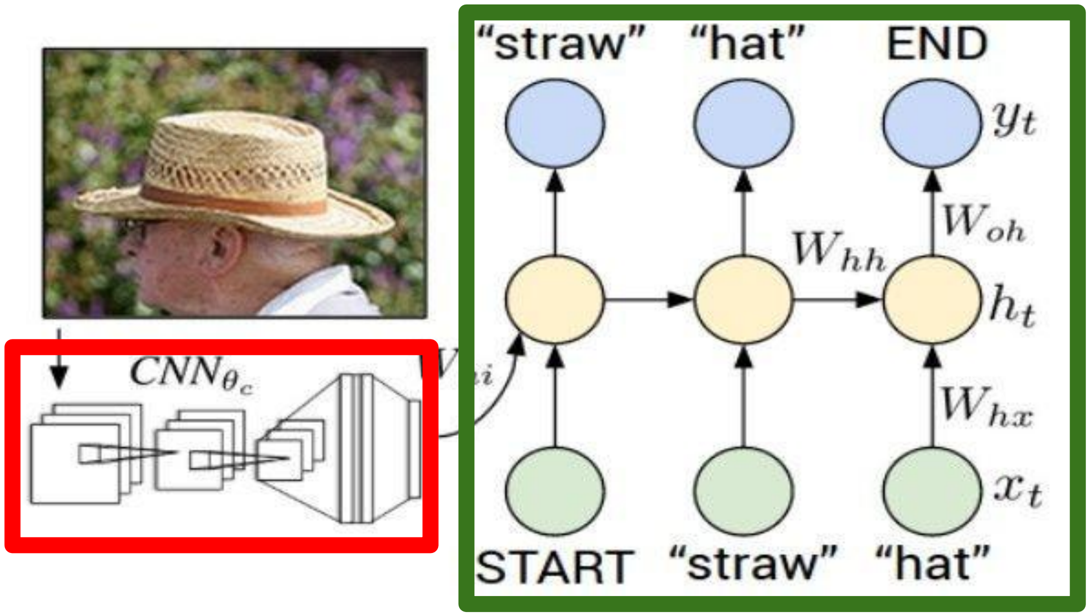


CVPR 2015:
Deep Visual-Semantic Alignments for Generating Image Descriptions, Karpathy and Fei-Fei
Show and Tell: A Neural Image Caption Generator, Vinyals et al.
Long-term Recurrent Convolutional Networks for Visual Recognition and Description, Donahue et al.
Learning a Recurrent Visual Representation for Image Caption Generation, Chen and Zitnick

Adapted from Andrej Karpathy

Image Captioning

Recurrent Neural Network



Convolutional Neural Network

Image Captioning

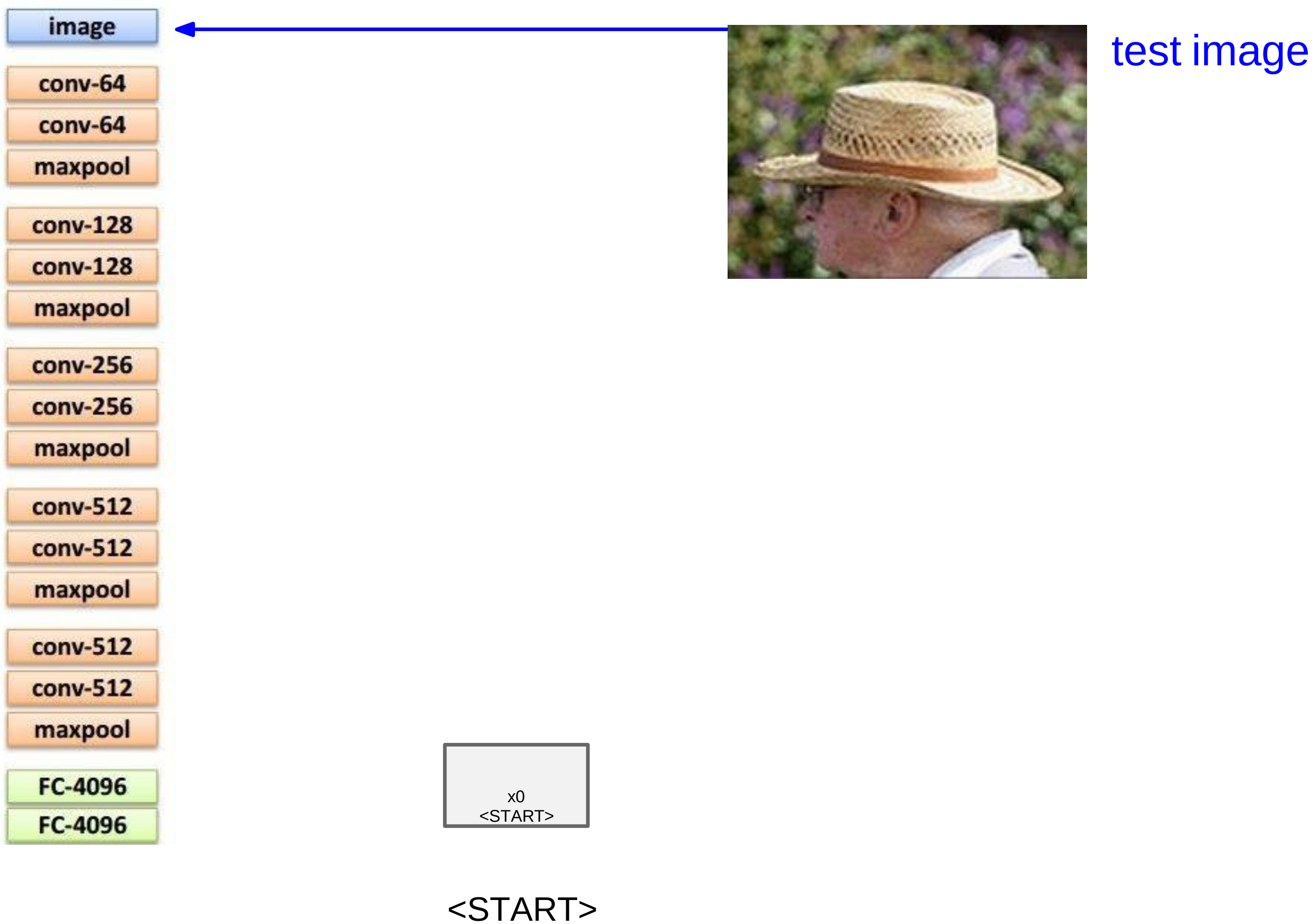
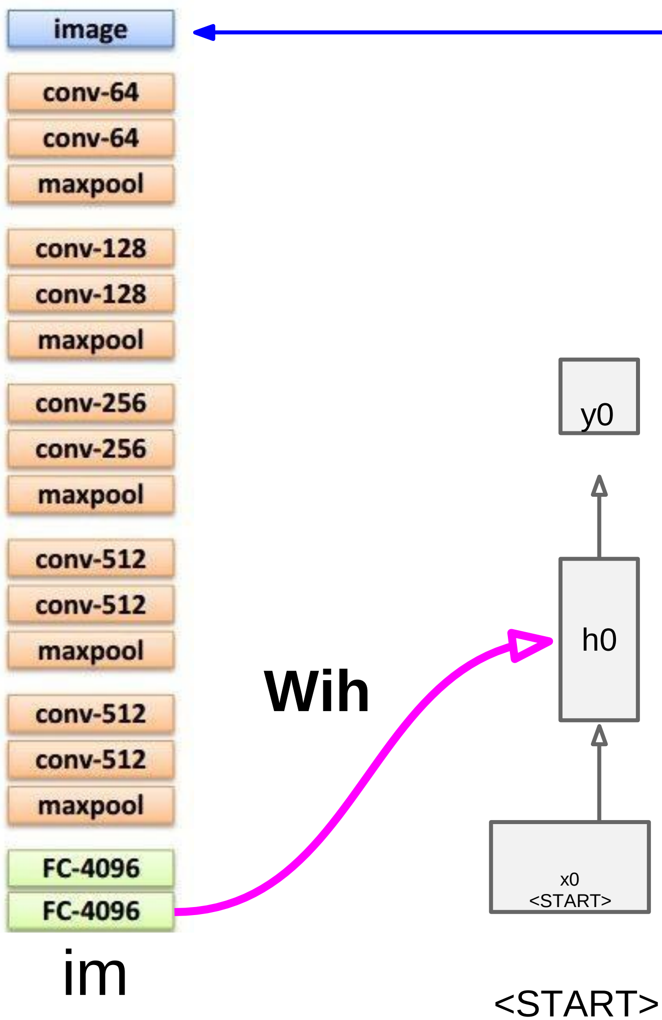


Image Captioning



test image

before:

$$h = \tanh(W_{xh} * x + W_{hh} * h)$$

now:

$$h = \tanh(W_{xh} * x + W_{hh} * h + W_{ih} * im)$$

Andrej Karpathy

Image Captioning

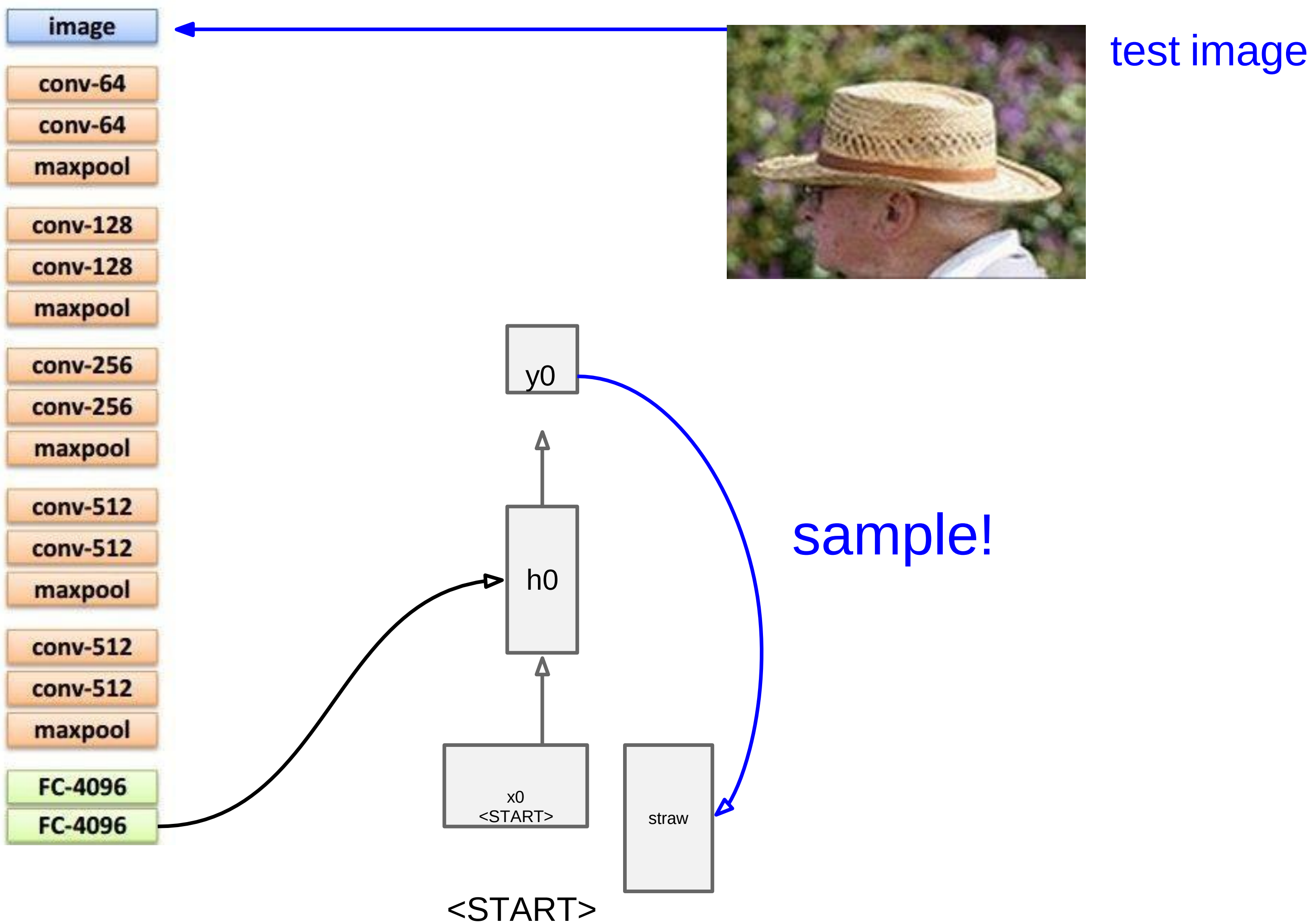


Image Captioning

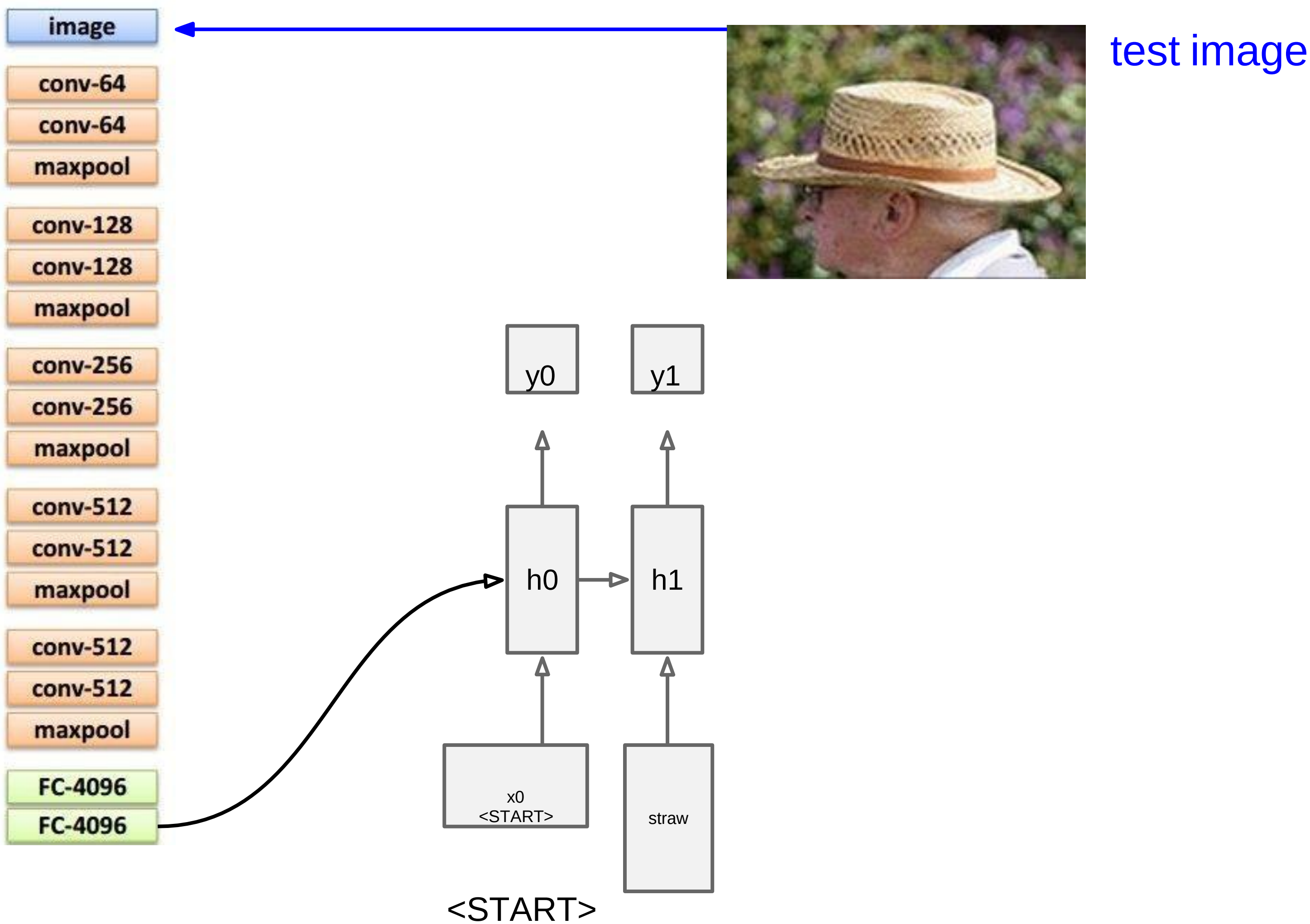
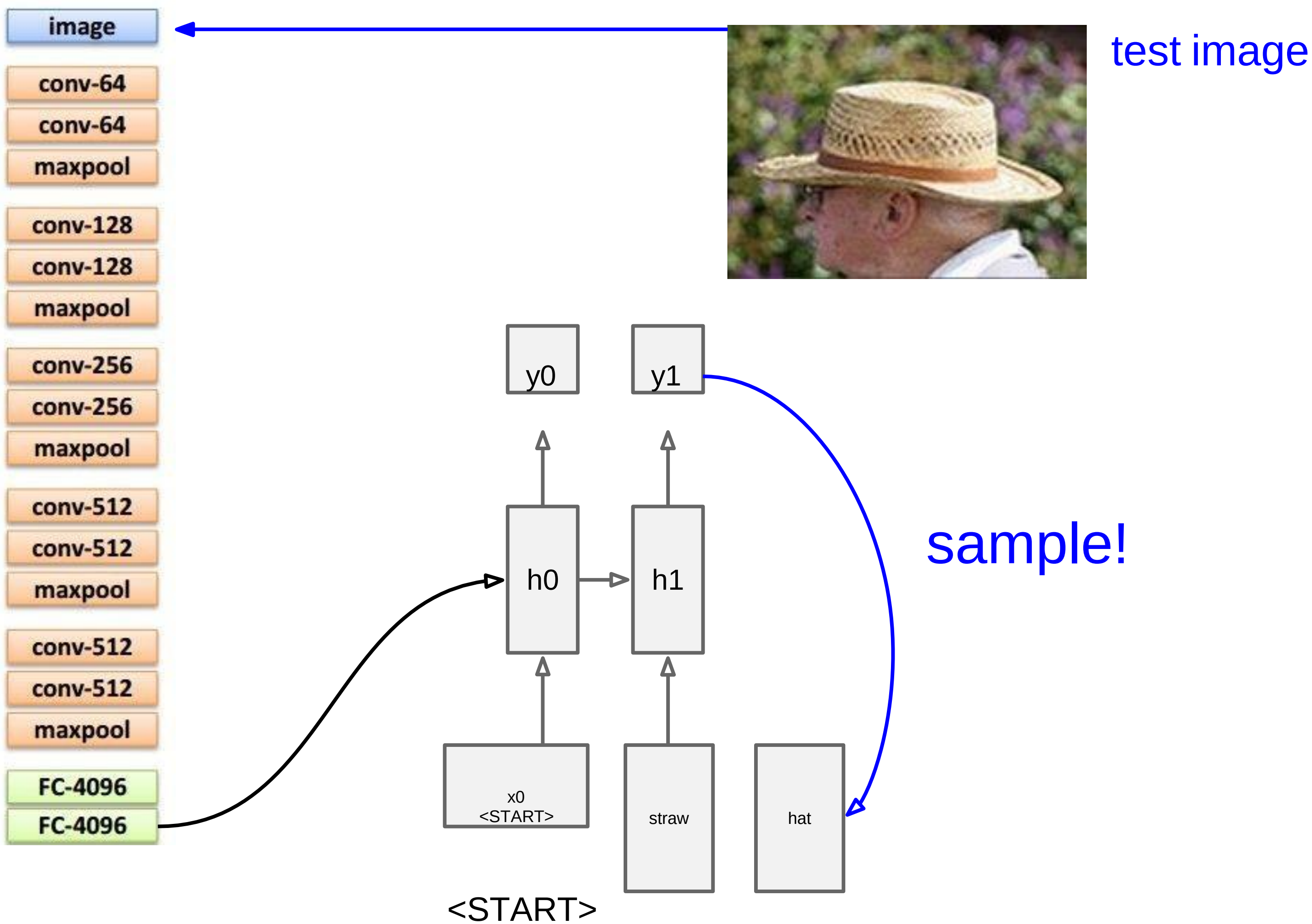
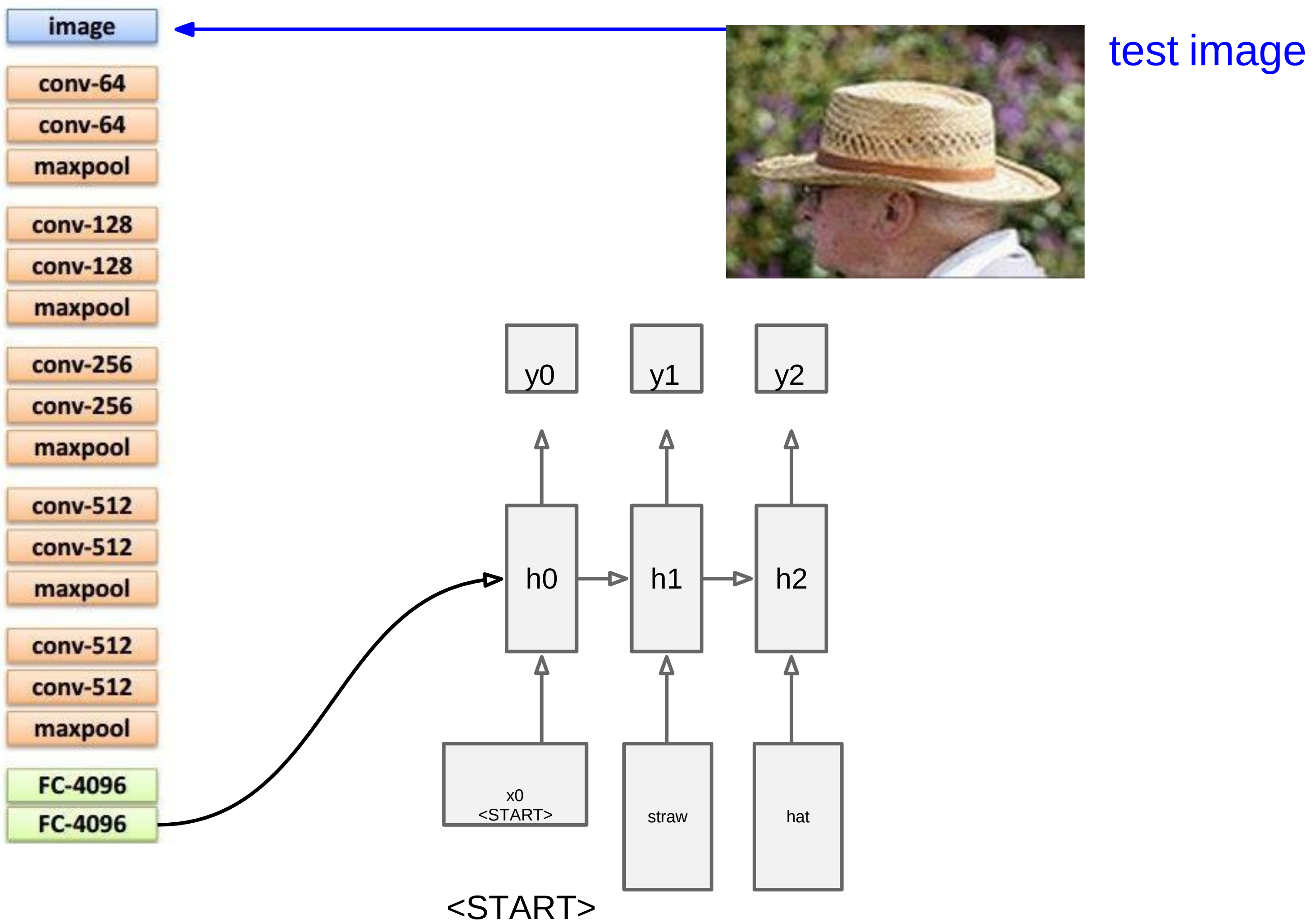


Image Captioning



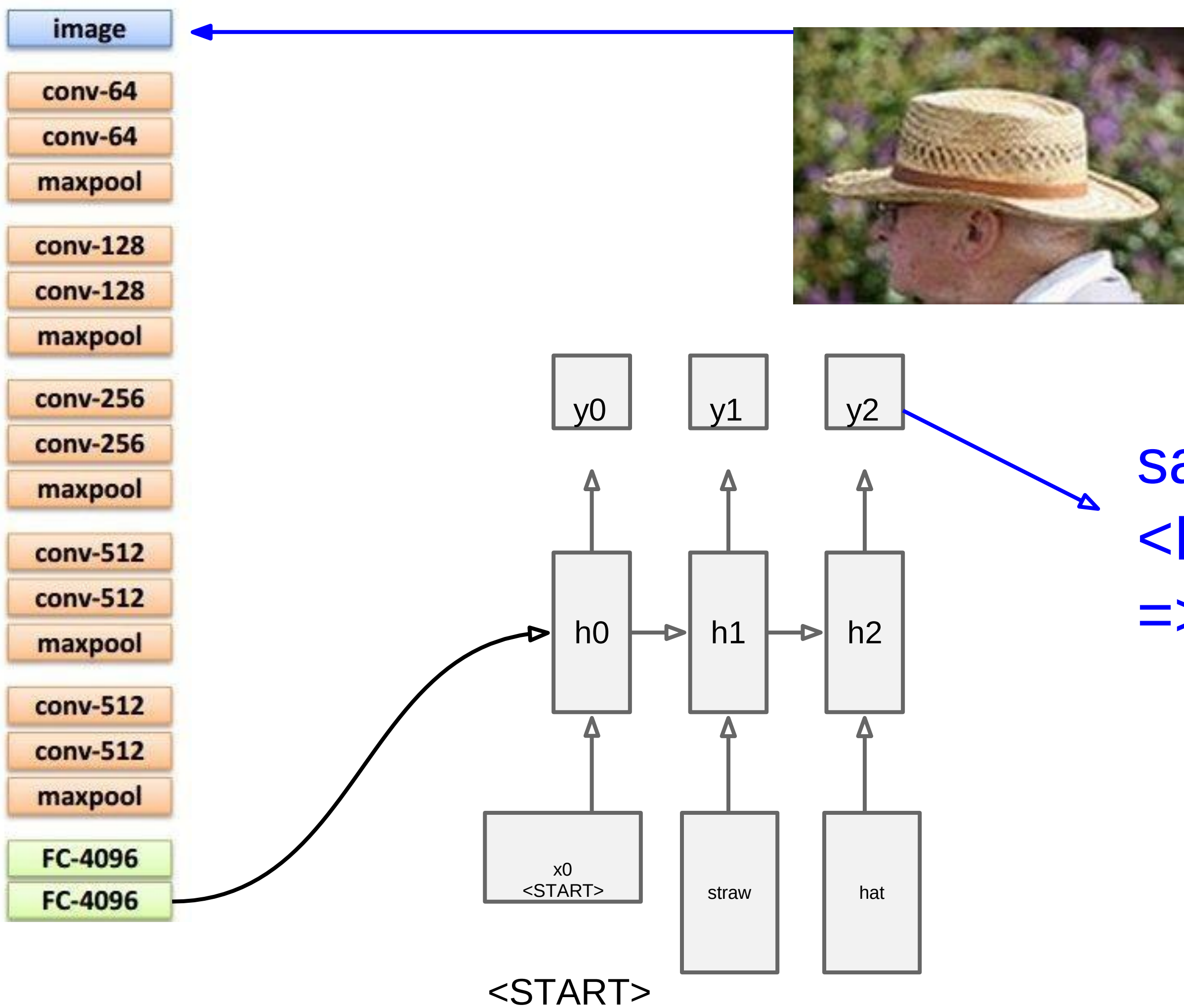
Andrej Karpathy

Image Captioning



Andrej Karpathy

Image Captioning



test image

Caption generated:
“straw hat”

sample
<END> token
=> finish.

Adapted from Andrej Karpathy

Image Captioning

"man in black shirt is playing guitar."

"construction worker in orange safety vest is working on road."

"two young girls are playing with lego toy."

"boy is doing backflip on wakeboard."

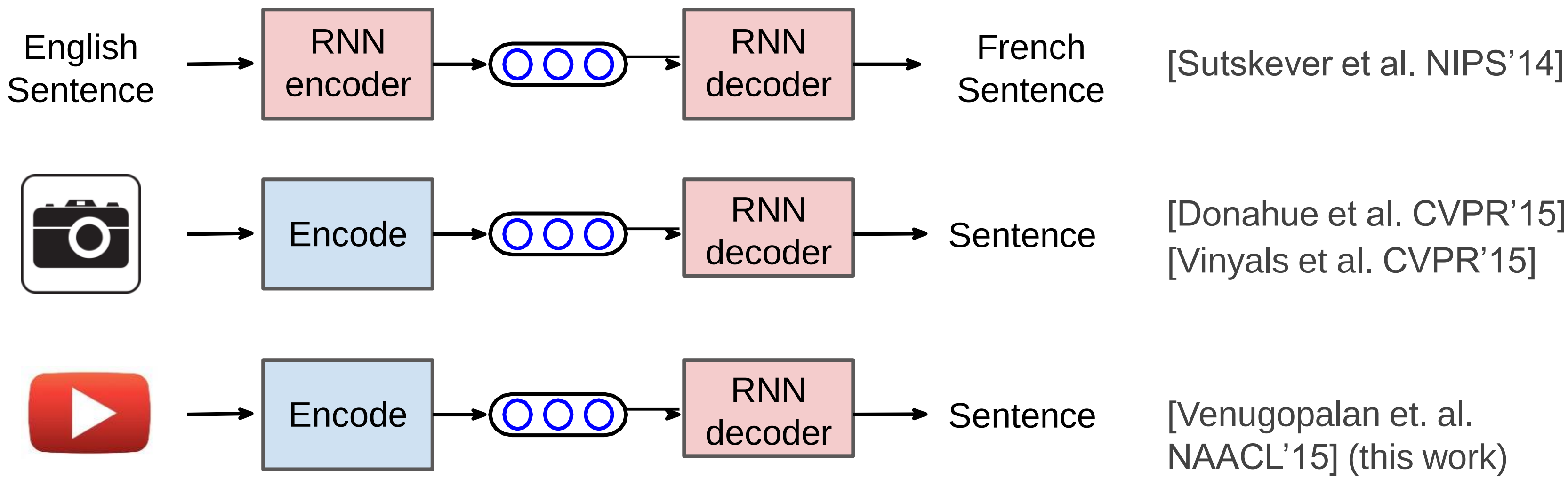
"a young boy is holding a baseball bat."

"a cat is sitting on a couch with a remote control."

"a woman holding a teddy bear in front of a mirror."

"a horse is standing in the middle of a road."

Video Captioning

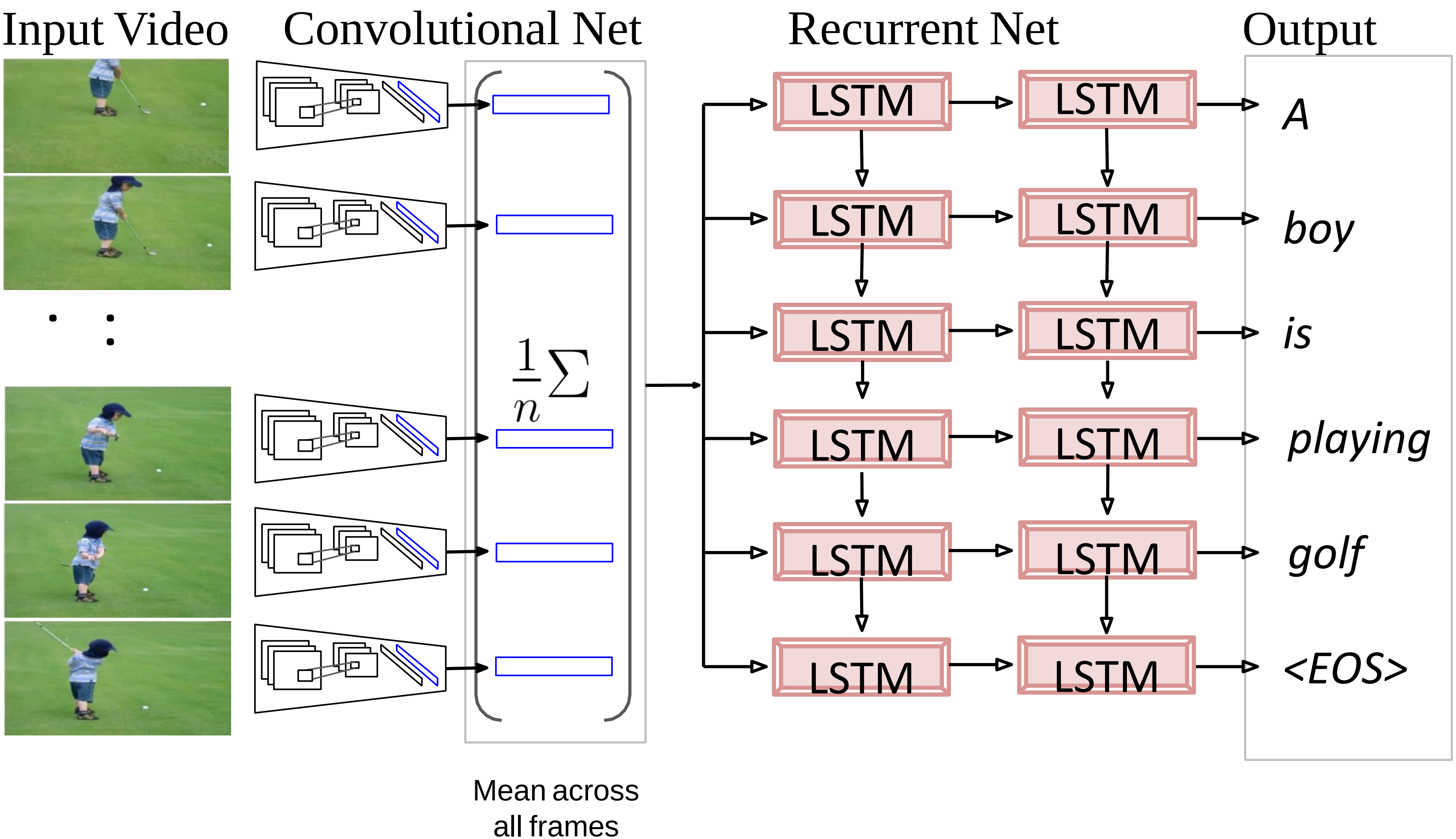


Key Insight:

Generate feature representation of the video and "decode" it to a sentence

Venugopalan et al., "Translating Videos to Natural Language using Deep Recurrent Neural Networks", NAACL-HTL 2015

Video Captioning



Venugopalan et al., "Translating Videos to Natural Language using Deep Recurrent Neural Networks", NAACL-HTL 2015

Video Captioning

FGM: A person is dancing with the person on the stage.
YT: A group of men are riding the forest.
I+V: **A group of people are dancing.**
GT: Many men and women are dancing in the street.

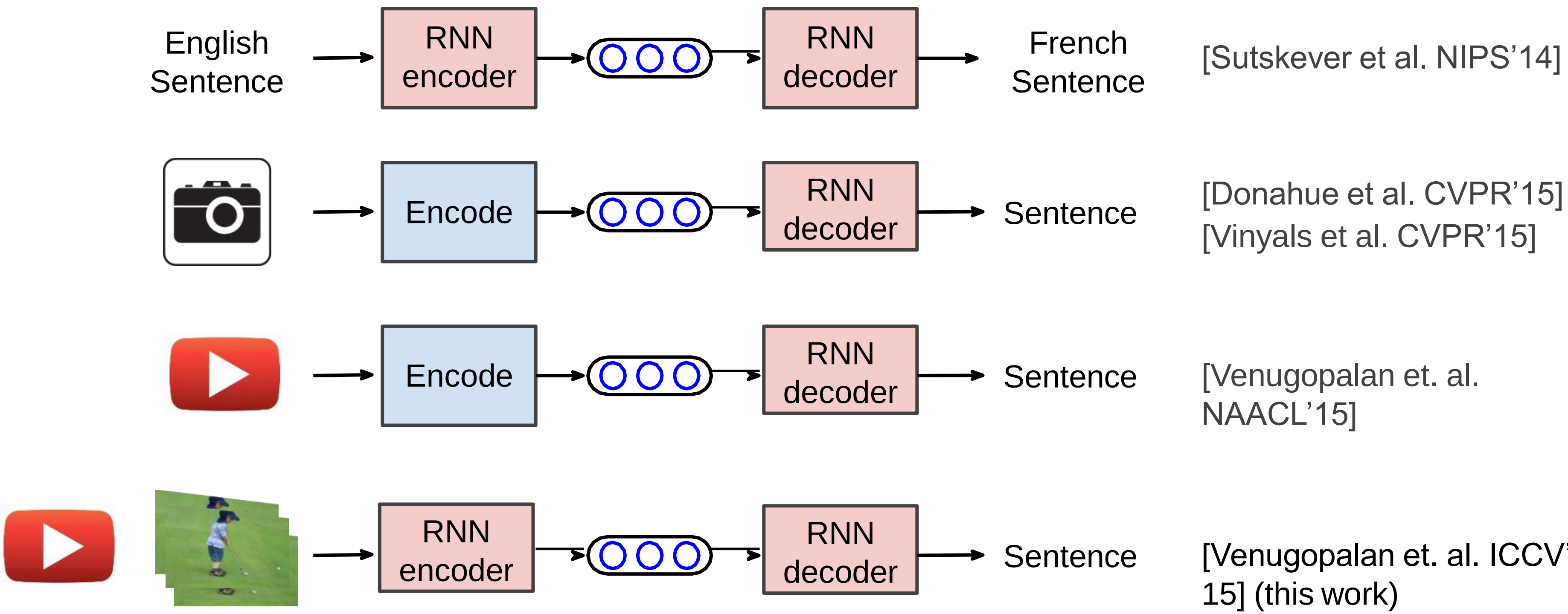
FGM: A person is cutting a potato in the kitchen.
YT: A man is slicing a tomato.
I+V: **A man is slicing a carrot.**
GT: A man is slicing carrots.

FGM: A person is walking with a person in the forest.
YT: A monkey is walking.
I+V: **A bear is eating a tree.**
GT: Two bear cubs are digging into dirt and plant matter at the base of a tree.

FGM: A person is riding a horse on the stage.
YT: A group of playing are playing in the ball.
I+V: **A basketball player is playing.**
GT: Dwayne wade does a fancy layup in an allstar game.

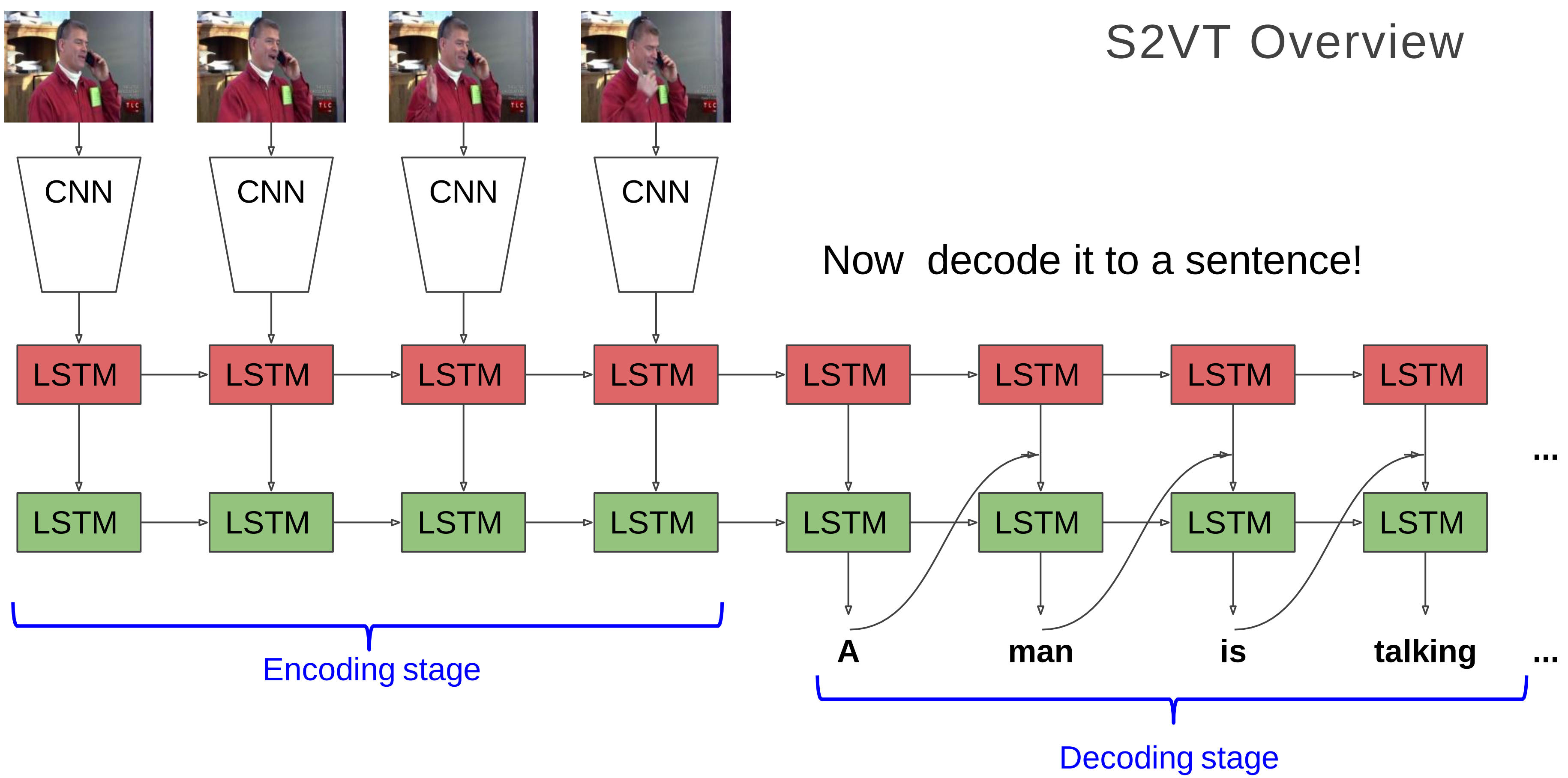
Venugopalan et al., “Translating Videos to Natural Language using Deep Recurrent Neural Networks”, NAACL-HTL 2015

Video Captioning



Venugopalan et al., "Sequence to Sequence - Video to Text", ICCV 2015

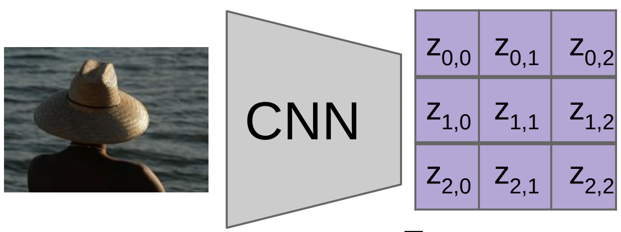
Video Captioning



Venugopalan et al., “Sequence to Sequence - Video to Text”, ICCV 2015

Image Captioning using spatial features

Input: Image **I**
Output: Sequence $\mathbf{y} = y_1, y_2, \ldots, y_T$



Extract spatial features from a pretrained CNN

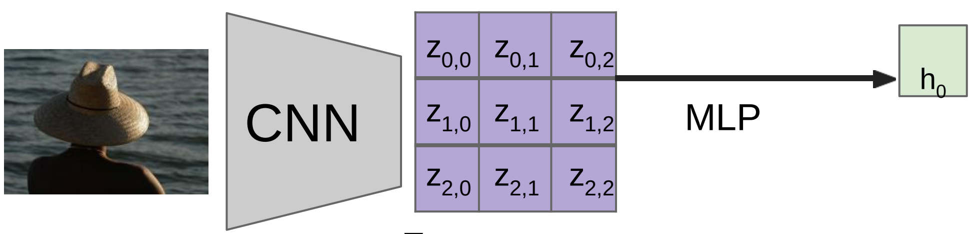
Features: H x W x D

Xu et al, "Show, Attend and Tell: Neural Image Caption Generation with Visual Attention", ICML 2015

Image Captioning using spatial features

Input: Image **I**
Output: Sequence $\mathbf{y} = y_1, y_2, \ldots, y_T$

Encoder: $h_0 = f_{\mathbf{W}}(\mathbf{z})$
where $\mathbf{z}$ is spatial CNN features
$f_{\mathbf{W}}(\mathbf{.})$ is an MLP



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where context vector c is often $c = h_0$

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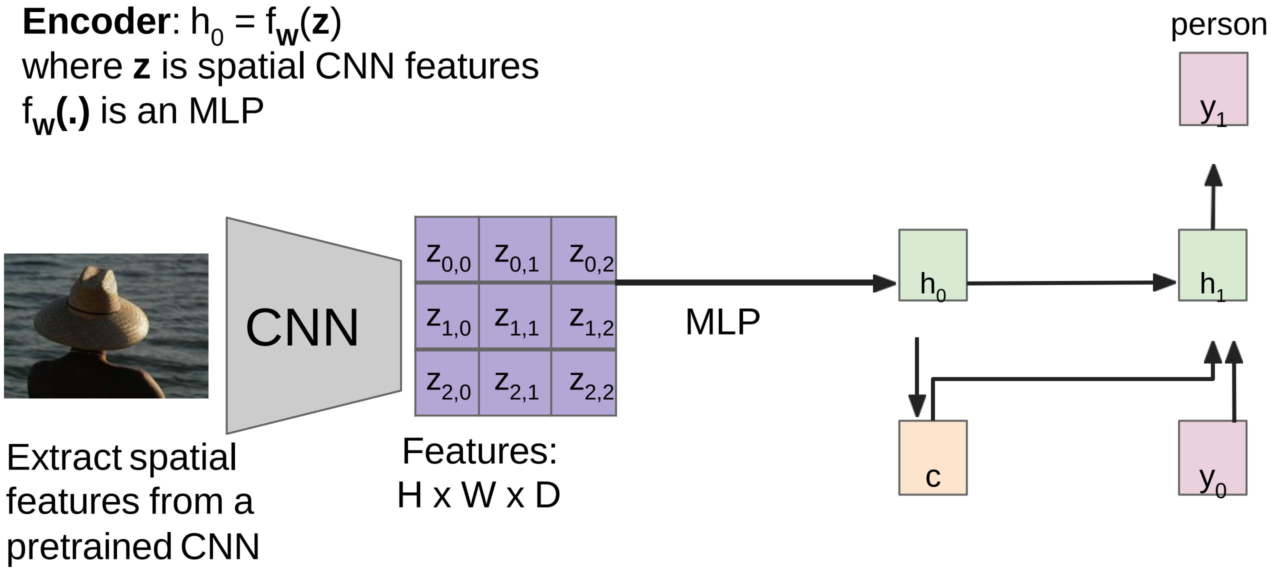
$f_W(.)$ is an MLP



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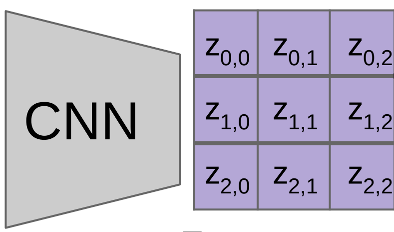

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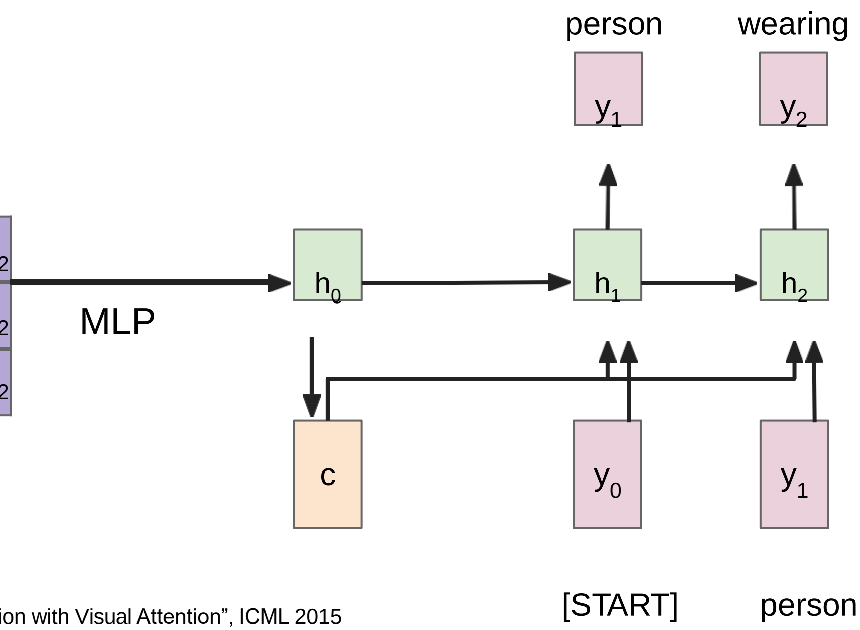

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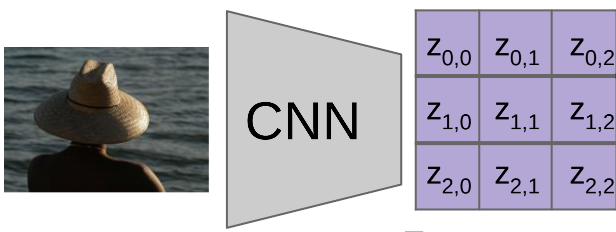

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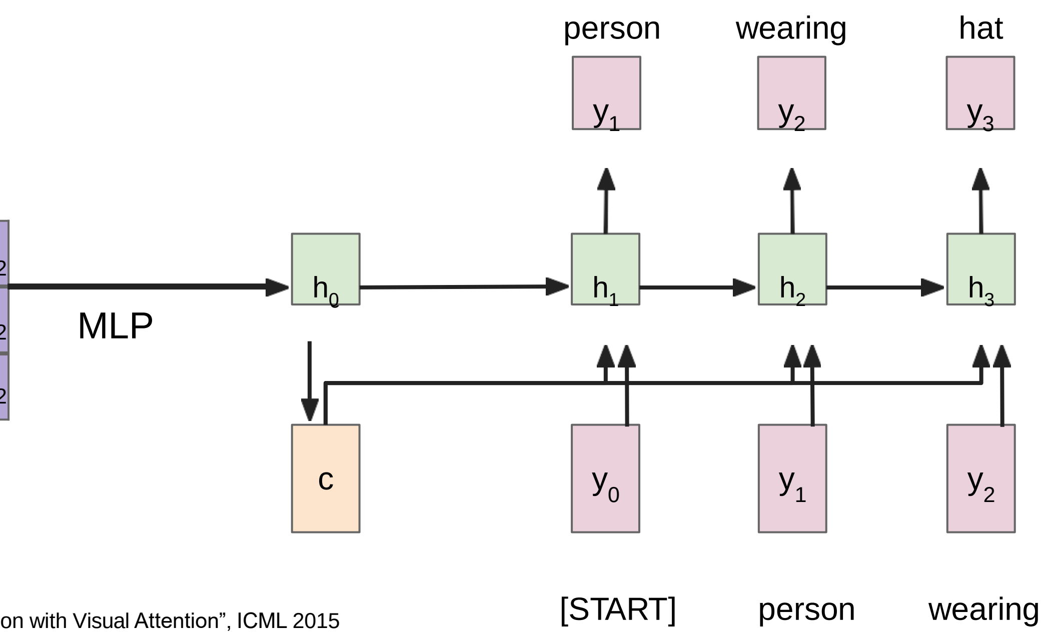

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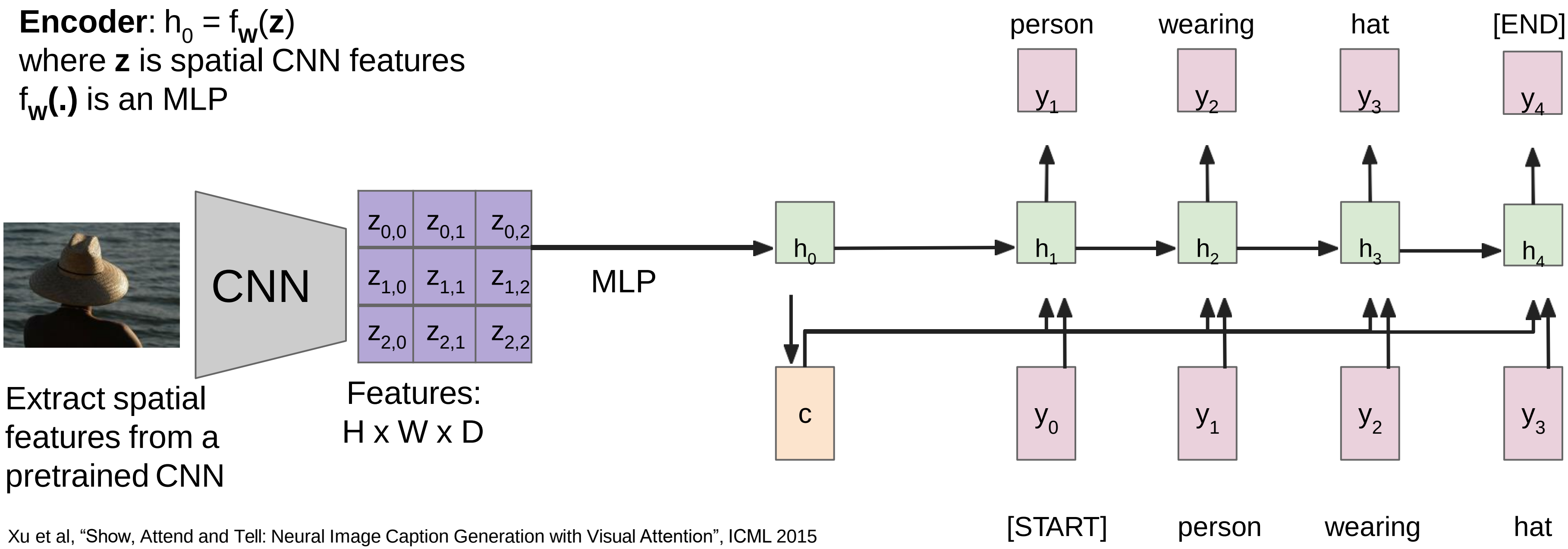


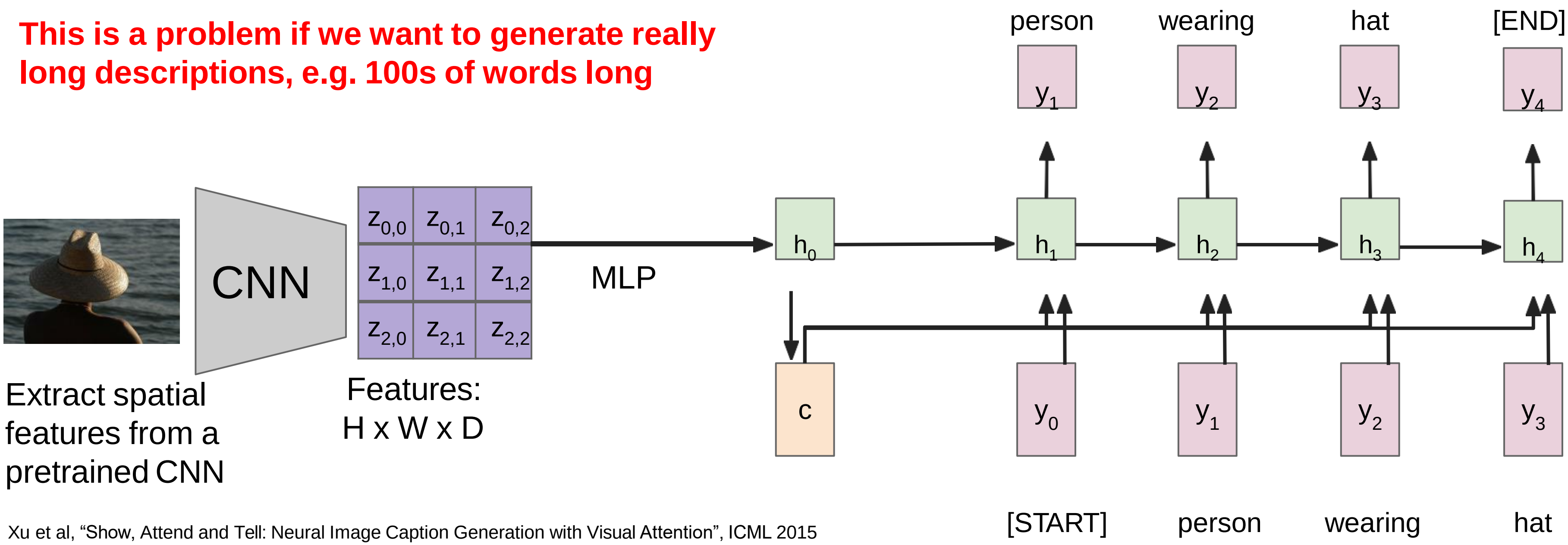
Xu et al, “Show, Attend and Tell: Neural Image Caption Generation with Visual Attention”, ICML 2015

Image Captioning using spatial features

Problem: Input is "bottlenecked" through c

- Model needs to encode everything it wants to say within c

This is a problem if we want to generate really long descriptions, e.g. 100s of words long



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Features: H x W x D

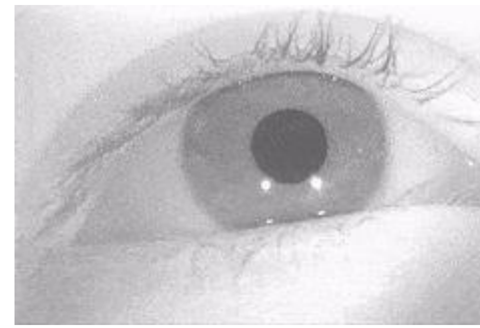
Xu et al, "Show, Attend and Tell: Neural Image Caption Generation with Visual Attention", ICML 2015

Image Captioning with RNNs and Attention

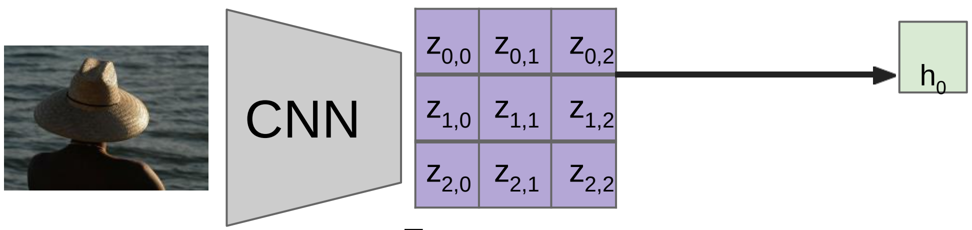
gif source

Attention idea: New context vector at every time step.

Each context vector will attend to different image regions



Attention Saccades in humans



Extract spatial features from a pretrained CNN

Features: H x W x D

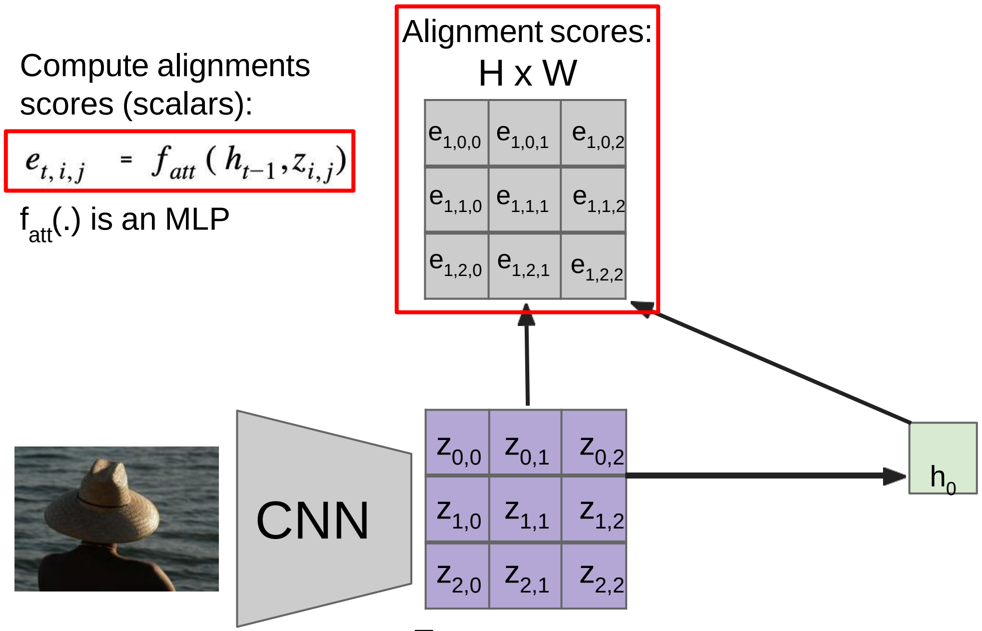
Xu et al, "Show, Attend and Tell: Neural Image Caption Generation with Visual Attention", ICML 2015

Image Captioning with RNNs and Attention

Compute alignments scores (scalars):

$$e_{t,i,j} = f_{att}(h_{t-1}, z_{i,j})$$

$f_{att}(.)$ is an MLP



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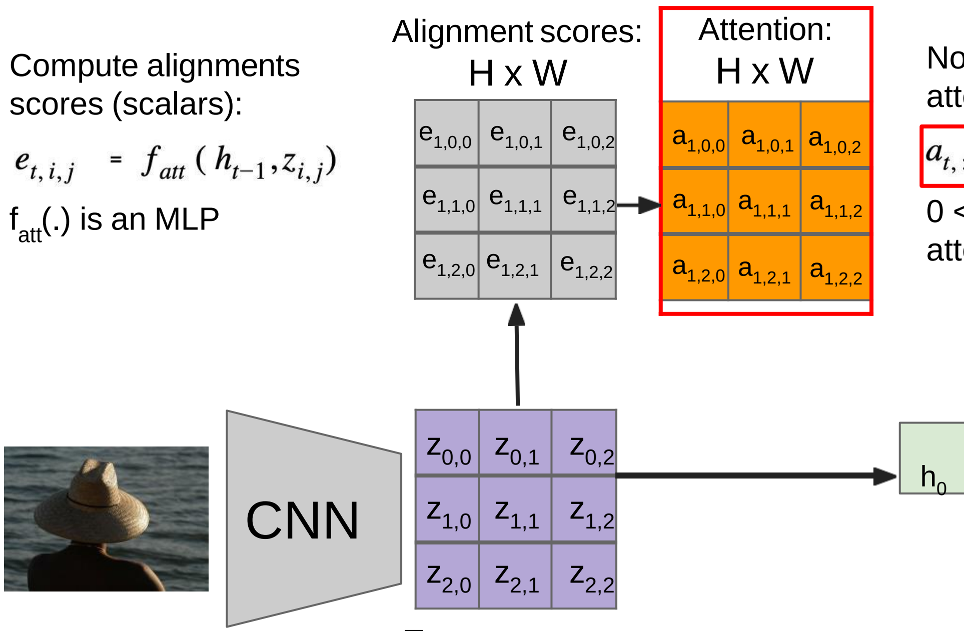


Normalize to get attention weights:

$$\boxed{a_{t,:,:} = softmax(e_{t,:,:})}$$

$0 < a_{t,i,j} < 1$,
attention values sum to 1

Extract spatial features from a pretrained CNN

Features:
H x W x D

Xu et al, “Show, Attend and Tell: Neural Image Caption Generation with Visual Attention”, ICML 2015

Image Captioning with RNNs and Attention

Compute alignments scores (scalars):

$$e_{t,i,j} = f_{att}(h_{t-1}, z_{i,j})$$

$f_{att}(.)$ is an MLP

Alignment scores: H x W

Attention: H x W

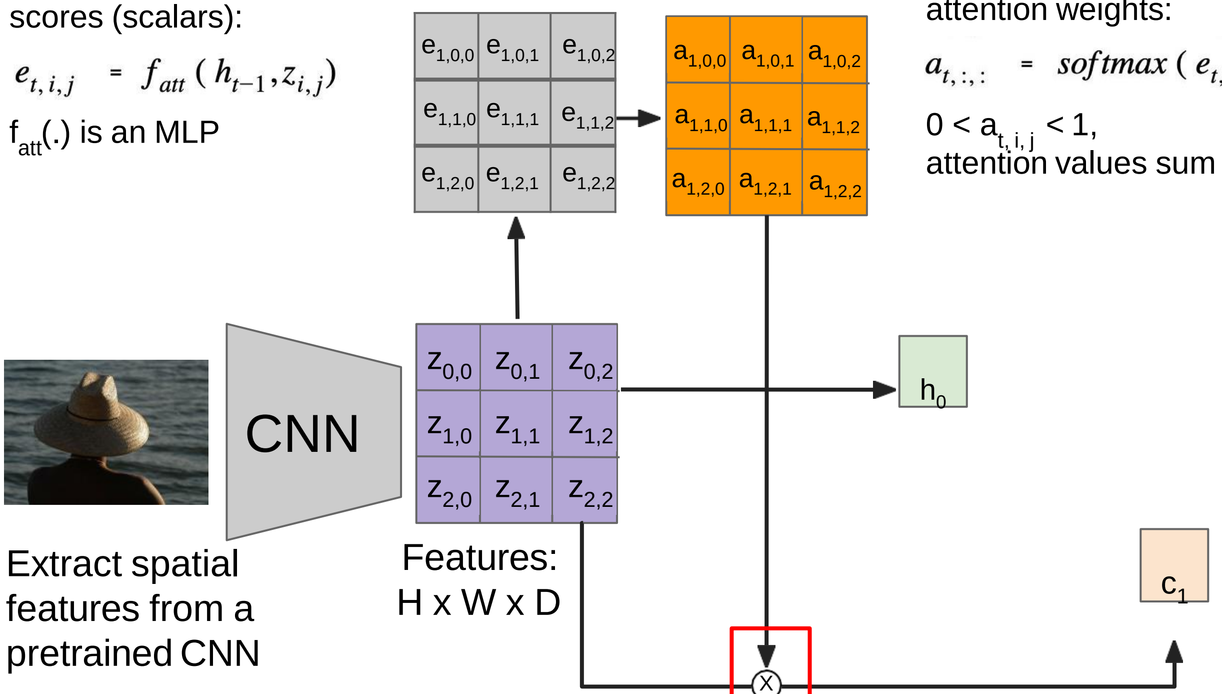
Normalize to get attention weights:

$$a_{t,:,:} = softmax(e_{t,:,:})$$

$0 < a_{t,i,j} < 1$,
attention values sum to 1

Compute context vector:

$$\boxed{c_t = \sum_{i,j} a_{t,i,j} z_{t,i,j}}$$



Xu et al, “Show, Attend and Tell: Neural Image Caption Generation with Visual Attention”, ICML 2015

Image Captioning with RNNs and Attention

Each timestep of decoder uses a different context vector that looks at different parts of the input image

Decoder: $y_t = g_V(y_{t-1}, h_{t-1}, c_t)$
New context vector at every time step

$$e_{t,i,j} = f_{att}(h_{t-1}, z_{i,j})$$
$$a_{t,:,:} = softmax(e_{t,:,:})$$
$$c_t = \sum_{i,j} a_{t,i,j} z_{t,i,j}$$

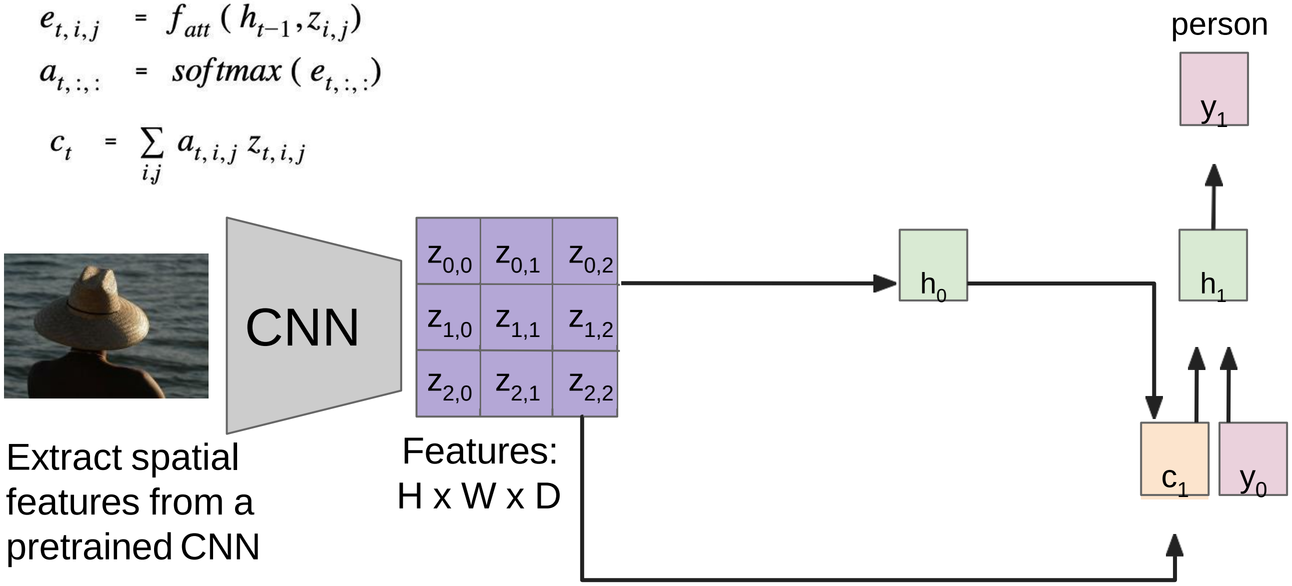


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Image Captioning with RNNs and Attention

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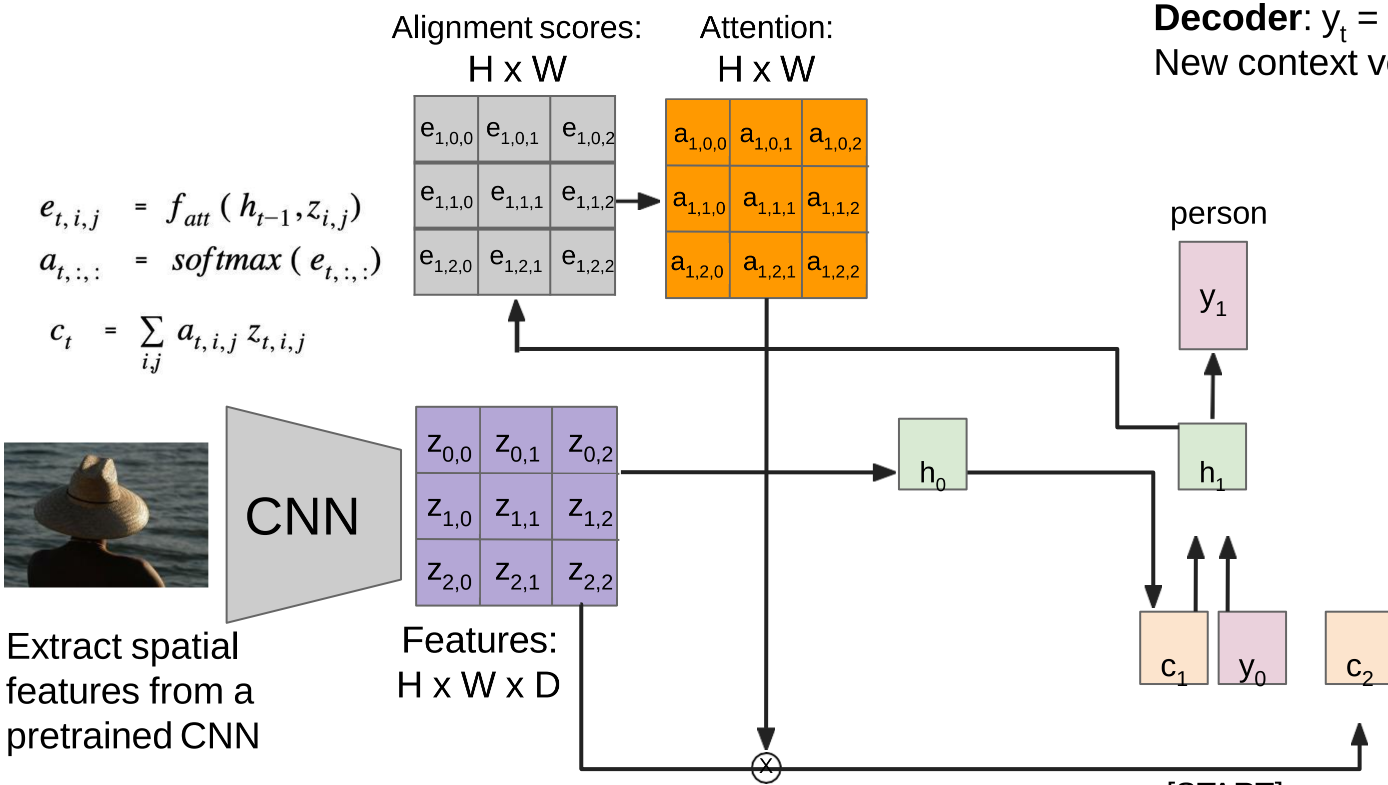
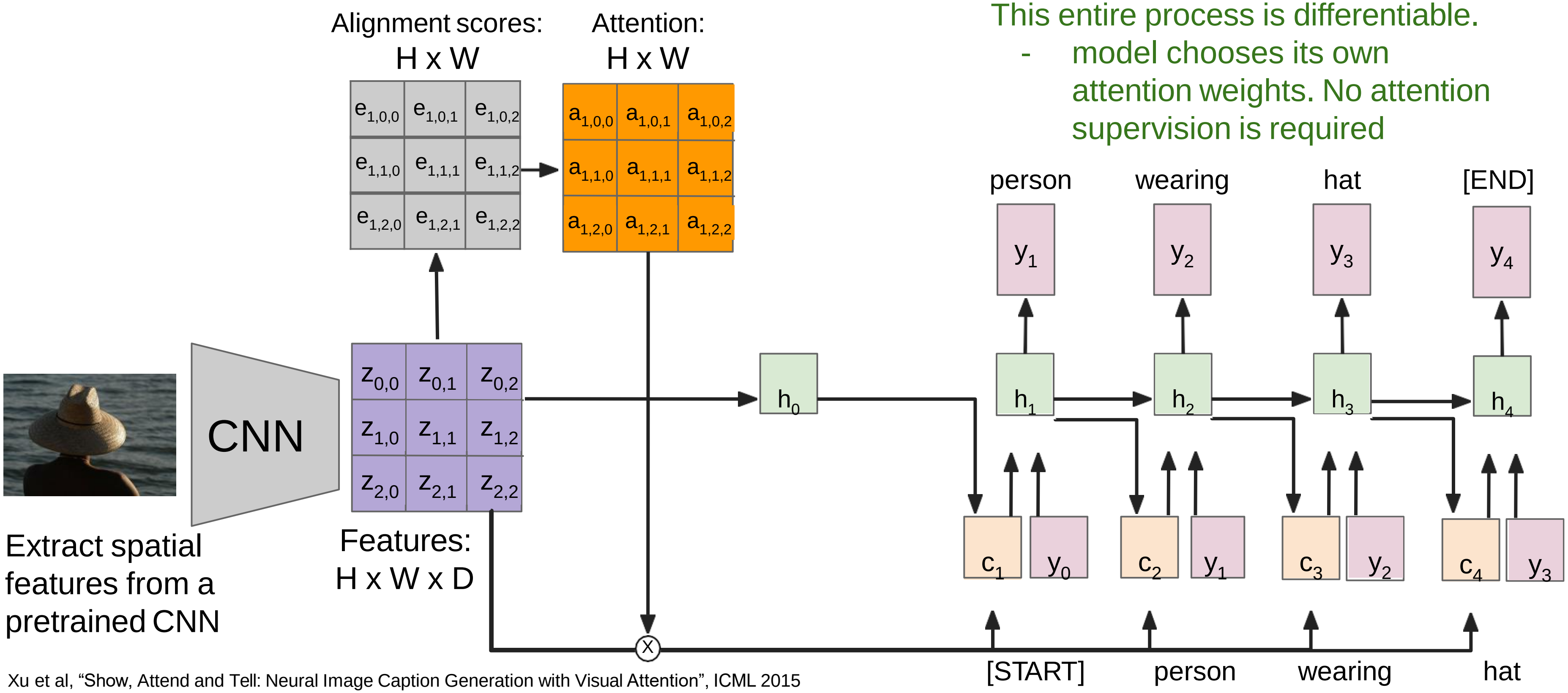


Xu et al, "Show, Attend and Tell: Neural Image Caption Generation with Visual Attention", ICML 2015

Image Captioning with RNNs and Attention

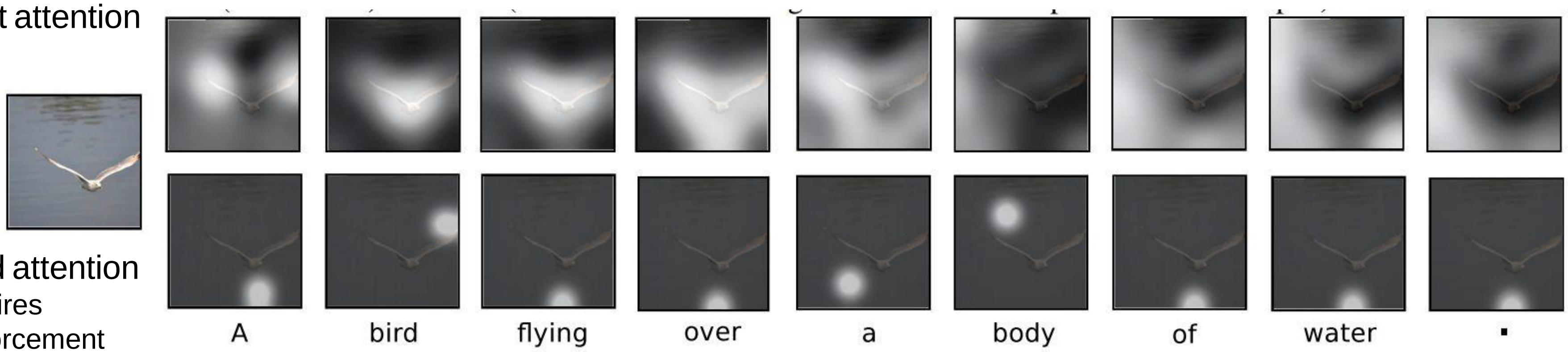
This entire process is differentiable.
- model chooses its own attention weights. No attention supervision is required



Xu et al, "Show, Attend and Tell: Neural Image Caption Generation with Visual Attention", ICML 2015

Image Captioning with Attention

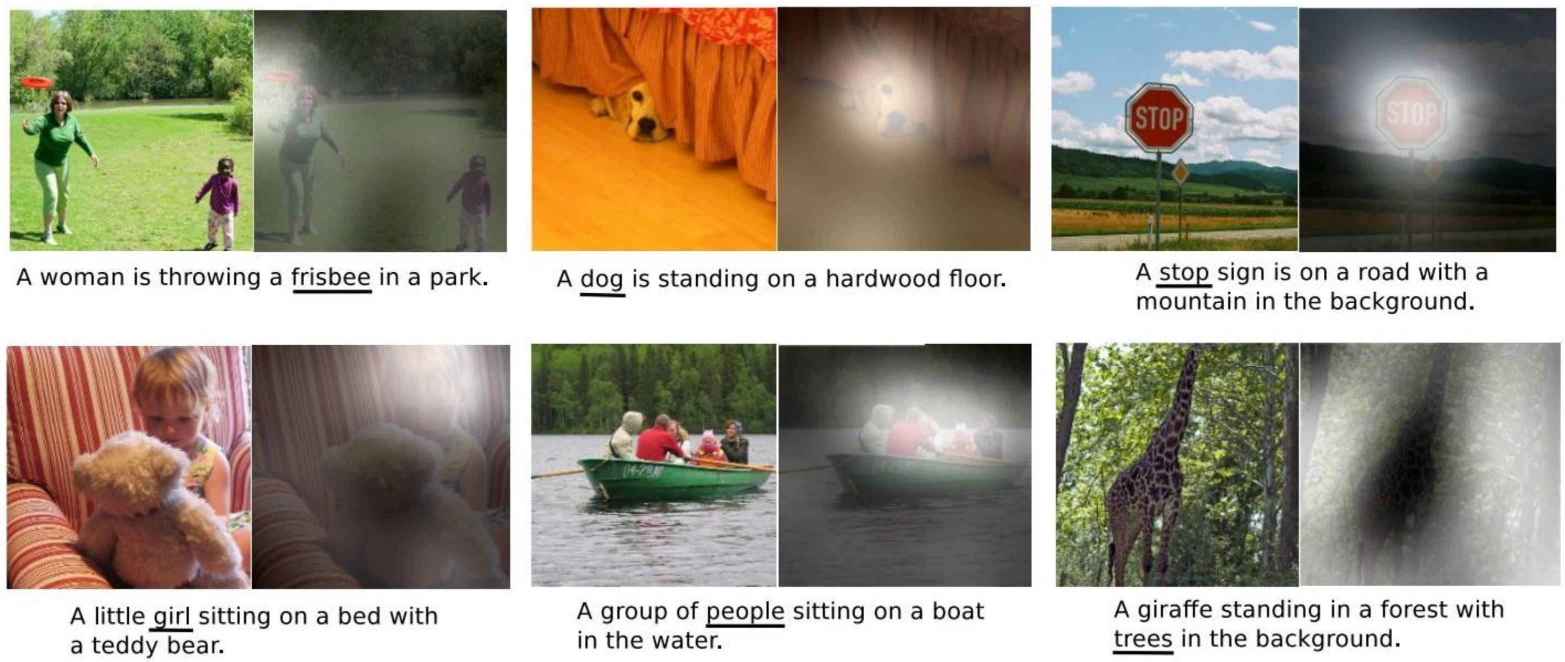
Soft attention



Hard attention
(requires
reinforcement
learning)

Xu et al, “Show, Attend, and Tell: Neural Image Caption Generation with Visual Attention”, ICML 2015

Image Captioning with Attention



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