

$W[1]$ -hardness

Dániel Marx

Recent Advances in Parameterized Complexity
Tel Aviv, Israel, December 3, 2017

Lower bounds

So far we have seen positive results: basic algorithmic techniques for fixed-parameter tractability.

What kind of negative results we have?

- Can we show that a problem (e.g., **CLIQUE**) is **not** FPT?
- Can we show that a problem (e.g., **VERTEX COVER**) has **no** algorithm with running time, say, $2^{o(k)} \cdot n^{O(1)}$?

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This would require showing that $P \neq NP$: if $P = NP$, then, e.g., k -**CLIQUE** is polynomial-time solvable, hence FPT.

Can we give some evidence for negative results?

Goals of this talk

Two goals:

- 1 Explain the theory behind parameterized intractability.
- 2 Show examples of parameterized reductions.

Classical complexity

Nondeterministic Turing Machine (NTM): single tape, finite alphabet, finite state, head can move left/right only one cell. In each step, the machine can branch into an arbitrary number of directions. Run is successful if at least one branch is successful.

NP: The class of all languages that can be recognized by a polynomial-time NTM.

Polynomial-time reduction from problem P to problem Q : a function ϕ with the following properties:

- $\phi(x)$ is a yes-instance of $Q \iff x$ is a yes-instance of P ,
- $\phi(x)$ can be computed in time $|x|^{O(1)}$.

Definition: Problem Q is **NP-hard** if any problem in **NP** can be reduced to Q .

If an **NP-hard** problem can be solved in polynomial time, then every problem in **NP** can be solved in polynomial time (i.e., $P = NP$).

Parameterized complexity

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- An appropriate notion of reduction.
- An appropriate hypothesis.

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Example: Graph G has an independent set k if and only if it has a vertex cover of size $n - k$.

\Rightarrow Transforming an **INDEPENDENT SET** instance (G, k) into a **VERTEX COVER** instance $(G, n - k)$ is a correct polynomial-time reduction.

However, **VERTEX COVER** is FPT, but **INDEPENDENT SET** is not known to be FPT.

Parameterized reduction

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Parameterized reduction from problem P to problem Q : a function ϕ with the following properties:

- $\phi(x)$ is a yes-instance of $Q \iff x$ is a yes-instance of P ,
- $\phi(x)$ can be computed in time $f(k) \cdot |x|^{O(1)}$, where k is the parameter of x ,
- If k is the parameter of x and k' is the parameter of $\phi(x)$, then $k' \leq g(k)$ for some function g .

Fact: If there is a parameterized reduction from problem P to problem Q and Q is FPT, then P is also FPT.

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Fact: If there is a parameterized reduction from problem P to problem Q and Q is FPT, then P is also FPT.

Non-example: Transforming an INDEPENDENT SET instance (G, k) into a VERTEX COVER instance $(G, n - k)$ is not a parameterized reduction.

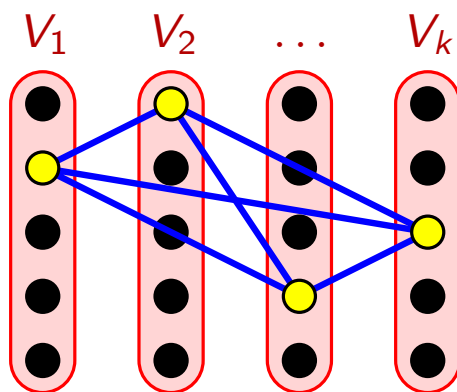
Example: Transforming an INDEPENDENT SET instance (G, k) into a CLIQUE instance (\overline{G}, k) is a parameterized reduction.

MULTICOLORED CLIQUE

A useful variant of **CLIQUE**:

MULTICOLORED CLIQUE: The vertices of the input graph G are colored with k colors and we have to find a clique containing one vertex from each color.

(or **PARTITIONED CLIQUE**)



Theorem

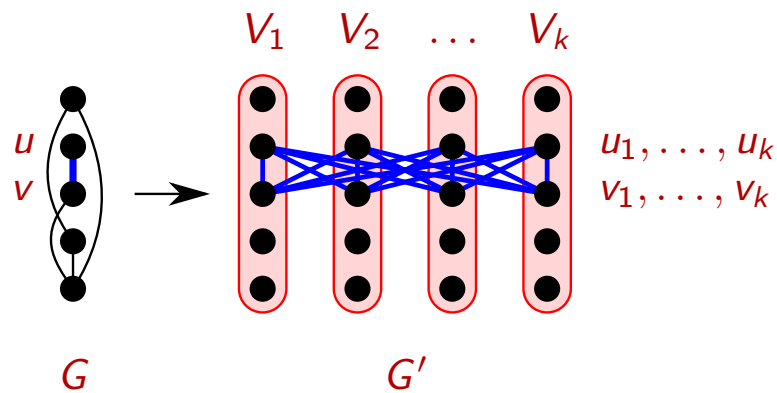
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There is a parameterized reduction from **CLIQUE** to **MULTICOLORED CLIQUE**.

Create G' by replacing each vertex v with k vertices, one in each color class. If u and v are adjacent in the original graph, connect all copies of u with all copies of v .



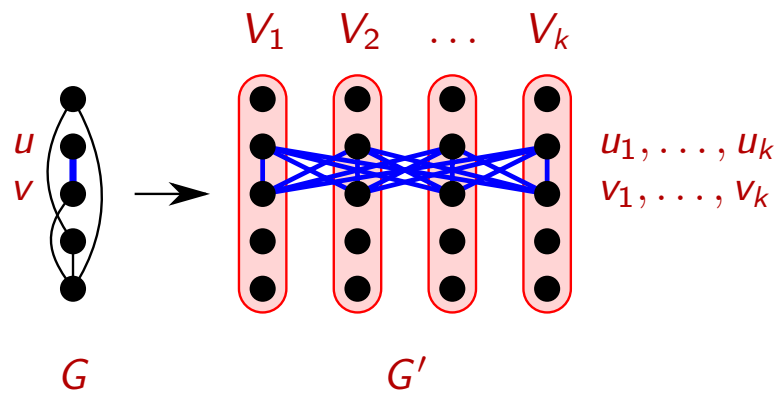
k -clique in $G \iff$ multicolored k -clique in G' .

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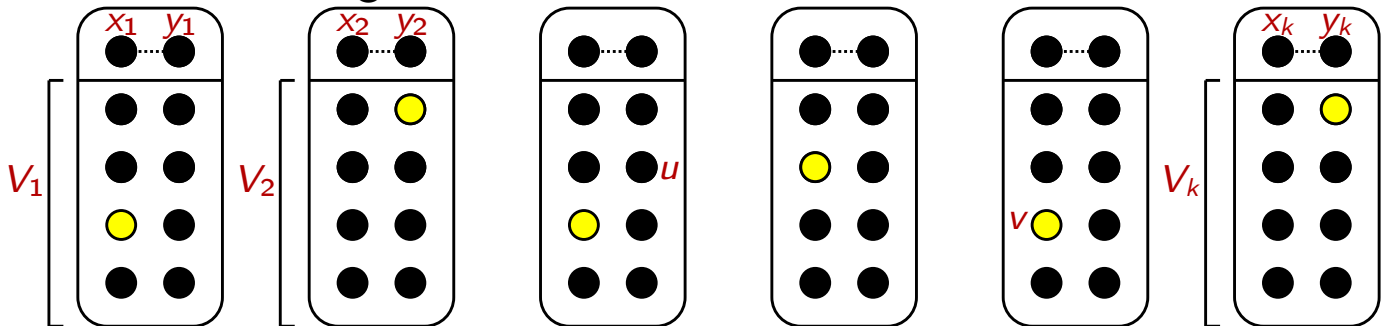
Similarly: reduction to **MULTICOLORED INDEPENDENT SET**.

DOMINATING SET

Theorem

There is a parameterized reduction from **MULTICOLORED INDEPENDENT SET** to **DOMINATING SET**.

Proof: Let G be a graph with color classes V_1, \dots, V_k . We construct a graph H such that G has a multicolored k -clique iff H has a dominating set of size k .



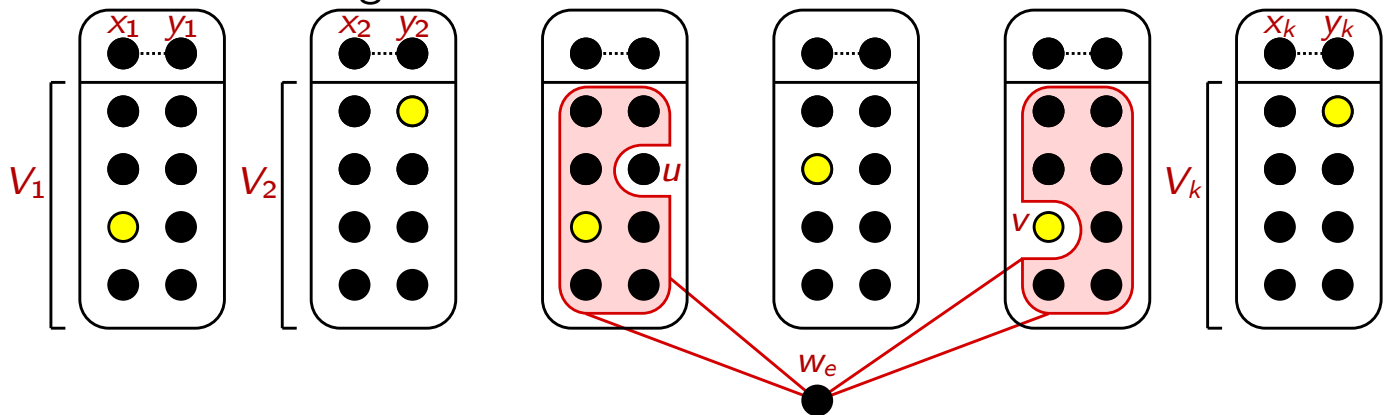
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- The dominating set has to contain one vertex from each of the k cliques V_1, \dots, V_k to dominate every x_i and y_i .
- For every edge $e = uv$, an additional vertex w_e ensures that these selections describe an independent set.

Variants of DOMINATING SET

- **DOMINATING SET**: Given a graph, find k vertices that dominate every vertex.
- **RED-BLUE DOMINATING SET**: Given a bipartite graph, find k vertices on the red side that dominate the blue side.
- **SET COVER**: Given a set system, find k sets whose union covers the universe.
- **HITTING SET**: Given a set system, find k elements that intersect every set in the system.

All of these problems are equivalent under parameterized reductions, hence at least as hard as **CLIQUE**.

Basic hypotheses

It seems that parameterized complexity theory cannot be built on assuming $P \neq NP$ – we have to assume something stronger.

Let us choose a basic hypothesis:

Engineers' Hypothesis

k -CLIQUE cannot be solved in time $f(k) \cdot n^{O(1)}$.

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Exponential Time Hypothesis (ETH)

n -variable 3SAT cannot be solved in time $2^{o(n)}$.

Which hypothesis is the most plausible?

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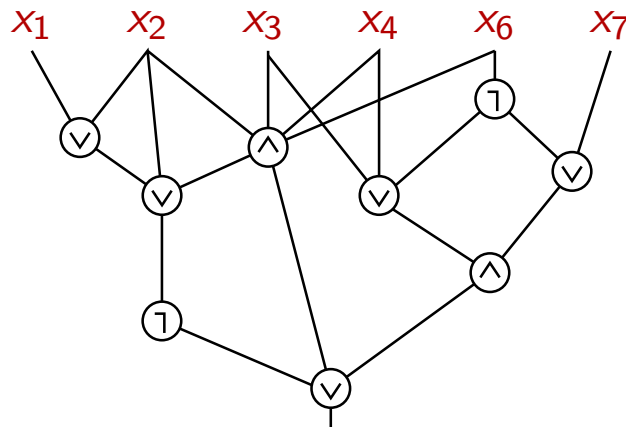
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Summary

- INDEPENDENT SET and k -STEP HALTING PROBLEM can be reduced to each other \Rightarrow Engineers' Hypothesis and Theorists' Hypothesis are equivalent!
- INDEPENDENT SET and k -STEP HALTING PROBLEM can be reduced to DOMINATING SET.
- Is there a parameterized reduction from DOMINATING SET to INDEPENDENT SET?
- Probably not. Unlike in NP-completeness, where most problems are equivalent, here we have a hierarchy of hard problems.
 - INDEPENDENT SET is $W[1]$ -complete.
 - DOMINATING SET is $W[2]$ -complete.
- Does not matter if we only care about whether a problem is FPT or not!

Boolean circuit

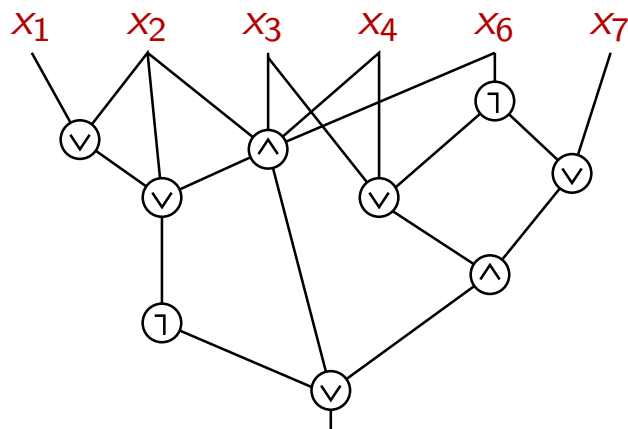
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Weight of an assignment: number of true values.

WEIGHTED CIRCUIT SATISFIABILITY: Given a Boolean circuit C and an integer k , decide if there is an assignment of weight k making the output true.