

CS 1550: Introduction to Operating Systems

Recitation 4: InterProcess Communication (IPC)

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Process Synchronization

- **Inter-Process Communication (IPC)** refers to the mechanisms that allows processes to work on shared data e.g. client and server architecture where client requests data and the server responds to client requests.
- **Motivations**
 - Cooperating processes share a logical address space
 - Avoiding inconsistency while having many concurrent data access
 - In massively parallel algorithms, a process may be interrupted at any point
 - Enable multithreading while having multiple cores

Producer/consumer example

- Producer – consumer problem (bounded-buffer problem) is a classic example of multi-process synchronization problem which consists of:
 - A fixed-size buffer used as a queue.
 - A producer which generates data and put it into the buffer.
 - A consumer which consumes data and remove it from the buffer

Producer/consumer example

```
/* Producer */  
/* produce an item  
next_produced */
```

$R_1 = \text{counter}$
 $R_1 = R_1 + 1$
 $\text{counter} = R_1$

```
while (true)
```

```
{
```

```
    while (counter == BUFFER SIZE)
```

```
        ; /* do nothing */
```

```
    buffer[in] = next_produced;
```

```
    in = (in + 1) % BUF
```

```
    counter++;
```

Counter = 5

Counter = {4, 5, or 6}

```
}
```

```
/* Consumer */
```

```
/* consume the item
```

```
next_consumed */
```

```
while (true)
```

```
{
```

```
    while (counter == 0)
```

```
        ; /* do nothing */
```

```
    next_consumed = buffer[out];
```

```
    out = (out + 1) % BUFFER SIZE;
```

```
    counter--;
```

$R_2 = \text{counter}$
 $R_2 = R_2 - 1$
 $\text{counter} = R_2$

Example (counter = 5)

```
/* Producer */
```

```
R1 = counter (R1 = 5)
```

```
R1 = R1 + 1 (R1 = 6)
```

```
Φ
```

```
Φ
```

```
counter = R1 (counter = 6)
```

```
Φ
```

```
/* Consumer */
```

```
Φ
```

```
Φ
```

```
R2 = counter (R2 = 5)
```

```
R2 = R2 - 1 (R2 = 4)
```

```
Φ
```

```
counter = R2 (counter = 4)
```

```
counter = 4
```

Example (counter = 5)

```
/* Producer */
```

```
R1 = counter (R1 = 5)
```

```
R1 = R1 + 1      (R1 = 6)
```

```
∅
```

```
∅
```

```
∅
```

```
counter = R1 (counter = 6)
```

```
counter = 6
```

```
/* Consumer */
```

```
∅
```

```
∅
```

```
R2 = counter (R2 = 5)
```

```
R2 = R2 - 1      (R2 = 4)
```

```
counter = R2 (counter = 4)
```

```
∅
```

Example (counter = 5)

```
/* Producer */
```

```
R1 = counter (R1 = 5)
```

```
R1 = R1 + 1      (R1 = 6)
```

```
counter = R1 (counter = 6)
```

```
Ø
```

```
Ø
```

```
Ø
```

```
/* Consumer */
```

```
Ø
```

```
Ø
```

```
Ø
```

```
R2 = counter (R2 = 6)
```

```
R2 = R2 - 1      (R2 = 5)
```

```
counter = R2 (counter = 5)
```

```
counter = 5
```

Critical Section Problem

```
/* Typical control flow for a
process  $p_i$  */
do
{
    entry section
    critical section
    exit section
    non critical section
}
while (TRUE)
```

- Concurrent accesses to a shared resource can lead to an unexpected behavior. So, the part of the program which is accessed concurrently is protected. This protected section is called **Critical Section**.
- N processes: $P = \{p_0, p_1, \dots, p_n\}$
 - Change a variable
 - Update a table
 - Write to a file

Solution Requirements for Critical Section

- **Mutual Exclusion**
 - Only p_i can be in its critical section at a given point of time
- **Progress**
 - If the critical section is empty, processes must be able to enter it
- **Bounded waiting**
 - No process should wait forever to enter its critical region
- How OS handles critical section
 - Non-preemptive kernels
 - Free from race conditions
 - Starvation problem
 - Preemptive kernels
 - Difficult to design
 - More responsive
- Hardware based solutions

Peterson's Solution

```
/* Process pi in Peterson's solution*/
int turn;
boolean flag[2];
do {
    flag[i] = true
    turn = j
    while (flag[j] && turn == j)
        ; /* do nothing */
    critical section
    flag[i] = false;
    non critical section
}
while (TRUE)
```

- A classic software-based solution which is working
- Restricted to 2 processes working on their critical sections
 - $j = 1 - i$
- **turn** indicates whose turn is it?
- **flag** indicates a process is ready to enter its critical region or not

Proving CS Requirements for PS

1. Mutual Exclusion

2. Bounded Waiting

3. Progress

/ P₀ */*

do {

 flag[0] = true

 turn = 1

 while (flag[1] && turn == 1)

 ; */* do nothing */*

 critical section

 flag[0] = false;

 non critical section

}

while (TRUE)

/ P₁ */*

do {

 flag[1] = true

 turn = 0

 while (flag[0] && turn == 0)

 ; */* do nothing */*

 critical section

 flag[1] = false;

 non critical section

}

while (TRUE)

1

2

3

MUTEX (**MUT**ual **EX**clusion)

- **Race condition:** A race condition is an undesirable condition that happened when having multiple processes running on a piece of data which does not use any exclusive locks to control access.
- A **MUTEX** is a **LOCK** for **CRITICAL SECTION** and thus prevents **RACE CONDITION**
- Mutexes are the simplest synchronization tools in the operating system

MUTEX

```
/* Typical control flow for mutex
locks */
do
{
    acquire() lock
        critical section
    release() lock
        non critical section
}
while (TRUE)
```

```
acquire()
{
    while (!available)
        ; /* busy wait */
    available = false;
}

release()
{
    available = true;
}
```

MUTEX

- + **Atomicity**: Implemented using hardware mechanisms
 - test and set() instruction
 - compare and swap() instruction
- **Busy waiting**: process spins while waiting for the lock **spinlock**

SEMAPHORE

```
/* semaphore(s) */
up(s)
{
    s++;
}

down(s)
{
    while (s <= 0)
        ; /* busy wait */
    s--;
}
```

- A classic software-based solution which is working
- A more sophisticated mutex lock
- All modifications to semaphore must be indivisible
- No 2 processes can modify a semaphore simultaneously
- Counting / binary semaphores

Semaphore with blocking

```
class Semaphore {
    int value;
    ProcessList pl;

    void down () {
        value -= 1;
        if (value < 0) {
            // add this process to pl
            pl.enqueue(currentProcess);
            Sleep();
        }
    }

    void up () {
        Process P;
        value += 1;
        if (value <= 0) {
            // remove a process P from pl
            P = pl.dequeue();
            Wakeup(P);
        }
    }
}
```

Producer/Consumer with semaphores

```
const int n;  
Semaphore empty(n), full(0), mutex(1);  
Item buffer[n];
```

Producer

```
int in = 0;  
Item pitem;  
while (1) {  
    // produce an item  
    // into pitem  
    empty.down();  
    mutex.down();  
    buffer[in] = pitem;  
    in = (in+1) % n;  
    mutex.up();  
    full.up();  
}
```

Consumer

```
int out = 0;  
Item citem;  
while (1) {  
    full.down();  
    mutex.down();  
    citem = buffer[out];  
    out = (out+1) % n;  
    mutex.up();  
    empty.up();  
    // consume item from  
    // citem  
}
```