

CS2310 Milestone #2 Report

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Title:

A digit recognition system prototyped by SIS Testbed

1. Input

In this project we use the MNIST dataset as the input for recognition. MNIST contains a training set of 60,000 handwritten digit examples, and a test set of 10,000 handwritten digit examples.

Figure 1 shows five different styles extracted from MNIST dataset.

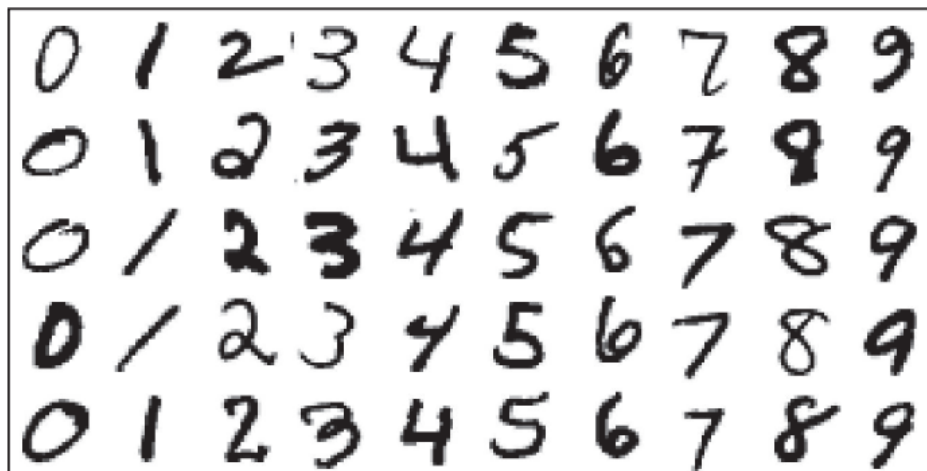


Figure 1 the black-white figure of digits from MNIST.

The package of MNIST has four files, including TRAINING SET LABEL FILE (train-labels-idx1-ubyte), TRAINING SET IMAGE FILE (train-images-idx3-ubyte), TEST SET LABEL FILE (t10k-labels-idx1-ubyte) and TEST SET IMAGE FILE (t10k-images-idx3-ubyte). Two label files share the same format:

[offset]	[type]	[value]	[description]
0000	32 bit integer	0x00000801(2049)	magic number (MSB first)
0004	32 bit integer	60000	number of items
0008	unsigned byte	??	label
0009	unsigned byte	??	label
.....			
xxxx	unsigned byte	??	label

The label is from 0 to 9.

Two image file also have the same format, as shown in following:

[offset]	[type]	[value]	[description]
0000	32 bit integer	0x00000803(2051)	magic number
0004	32 bit integer	60000	number of images
0008	32 bit integer	28	number of rows
0012	32 bit integer	28	number of columns
0016	unsigned byte	??	pixel
0017	unsigned byte	??	pixel
.....			
xxxx	unsigned byte	??	pixel

Pixels are organized row-wise. Pixel values are 0 to 255. 0 means background (white), 255 means foreground (black). Continuous 28x28 pixels in the image file consist of a digit.

From the label format and image format we can build a training dataset and a testing dataset for auto associative memory. The input for associative memory can be a vector consisted by 784 unsigned integers, each of which is between 0 and 255.

2. Algorithm

We use the The *Brain-state-in-a-box* (BSB) model, which is a simple, auto-associative, nonlinear, energy-minimizing neural network. A common application of the BSB model is *optical character recognition* (OCR) for printed text. The BSB model is a simple auto-associative neural network with two main operations – *training* and *recall*. The mathematical model for recall can be represented as:

$$\mathbf{x}(t+1) = S(\alpha \cdot \mathbf{A} \times \mathbf{x}(t) + \lambda \times \mathbf{x}(t))$$

where, \mathbf{x} is an N dimensional real vector, and \mathbf{A} is an N -by- N connection matrix. $\mathbf{A} \times \mathbf{x}(t)$ is a matrix-vector multiplication, which is the main function of the recall operation. α is a scalar constant feedback factor. λ is an inhibition decay constant. $S(y)$ is the “squash” function defined as follows:

$$S(y) = \begin{cases} 1, & \text{if } y \geq 1 \\ y, & \text{if } -1 < y < 1 \\ -1, & \text{if } y \leq -1 \end{cases}$$

For a given input pattern $\mathbf{x}(0)$, the recall function computes above function iteratively until *convergence*, that is, when all the entries of $\mathbf{x}(t+1)$ are either “1” or “-1”.

The BSB model has been implemented with C++, below two figure show the training source code recall source code:

```

bool TrainBSB(float *vec, float *wm)
{
    bool    converged;
    int     i, j, k;
    float   *wx;

    wx = (float *)malloc(BsbSize*sizeof(float));

    // Compute W*X
    for(i=0;i<BsbSize;){
        wx[i] = 0.0;
        for(j=0;j<BsbSize;){
            wx[i] += wm[i*BsbSize+j] * vec[j];
            ++j;
        }
        ++i;
    }

    converged = true;

    // Compute X-W*X
    for(i=0;i<BsbSize;){
        wx[i] = vec[i] - wx[i];
        if(fabsf(wx[i]) > 1.0E-4) converged = false;
        ++i;
    }

    // Update W = W + LR*(X-W*X) _outter_product_ X
    for(i=0;i<BsbSize;){
        for(j=0;j<BsbSize;){
            wm[i*BsbSize+j] = wm[i*BsbSize+j] + LEARN_RATE*wx[i]*vec[j];
            ++j;
        }
        ++i;
    }

    free(wx);
    return converged;
} « end TrainBSB »

```

Figure 2 the training function of BSB model

```

bool RecallBSB(float *vec, float *wm)
{
    int i, j, k;
    bool converged;
    float *wx;
    wx = (float *)malloc(BsbSize*sizeof(float));

    // Compute W*X
    for(i=0; i<BsbSize;){
        wx[i] = 0.0;
        for(j=0; j<BsbSize;){
            wx[i] += wm[i*BsbSize+j] * vec[j];
            ++j;
        }
        ++i;
    }

    // Compute S(Alpha*W*X + Lamda*X)
    for(i=0; i<BsbSize;){
        wx[i] = ALPHA*wx[i] + LAMDA*vec[i];
        if(wx[i] <= -1.0)
            vec[i] = -1.0;
        else
            if(wx[i] >= 1.0)
                vec[i] = 1.0;
            else
                vec[i] = wx[i];
        ++i;
    }

    // Check convergence
    converged = true;

    for(i=0; i<TagOffset; ++i){ // When converged, all tags must be 1.0
        if(vec[i] != 1.0) converged = false;
    }

    for(i=0; i<BsbSize; ++i){ // When converged, all image entries must be either -1 or 1
        if(fabsf(vec[i]) != 1.0) converged = false;
    }

    free(wx);
    return converged;
} « end RecallBSB »

```

Figure 3 the recall function of BSB model