CS 1675 Introduction to Machine Learning
Lecture 5

Density estimation

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Review of probabilities

Probability theory

Studies and describes random processes and their outcomes

- **Random processes may result in multiple different outcomes**
- **Example 1: coin flip**
  - Outcome is either head or tail (binary outcome)
  - Fair coin: outcomes are equally likely

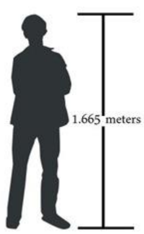
- **Example 2: sum of numbers obtained by rolling 2 dice**
  - Outcome number in between 2 to 12
  - Fair dices: outcome 2 is less likely then 3

Probability theory

Studies and describes random processes and their outcomes

- **Random processes may have multiple different outcomes**

- **Example 3: height of a person**
  - Select randomly a person from your school/city and report her height
  - Outcomes can be real numbers



- **And many others related to measurements, lotteries, etc**

Probabilities

When the process is repeated many times outcomes occur with certain relative frequencies or **probabilities**

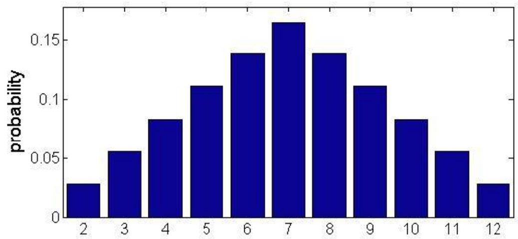
- **Example 1: coin flip**
  - **Fair coin:** outcomes are equally likely
    - Probability of head is 0.5 and tail is 0.5
  - Biased coin
    - Probability of head is 0.8 and tail is 0.2
    - Head outcome is 4 times more likely than tail

Probabilities

When the process is repeated many times outcomes occur with certain relative frequencies or **probabilities**

- **Example 2: sum of numbers obtained by rolling 2 dice**
  - Outcome number in between 2 to 12
  - Fair dice: outcome 2 is less likely then 3

    4 is less likely then 3, etc



Probability distribution function

Discrete (mutually exclusive) outcomes – the chance of outcomes is represented by **a probability distribution function**

- **probability distribution function – assigns a number between 0 and 1 to every outcome**
- **Example 1: coin flip**
  - Biased coin
    - Probability of head is 0.8 and tail is 0.2
    - Head outcome is 4 time more likely than tail

P(tail) = 0.2
P(head) = 0.8

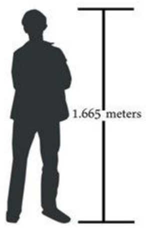
$$P(coin) = \begin{bmatrix} 0.2 \\ 0.8 \end{bmatrix}$$

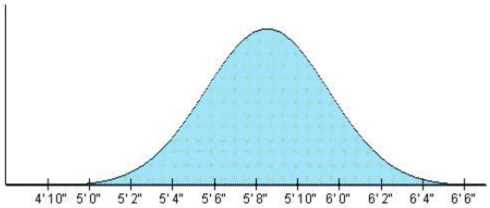
- **What is the condition we need to satisfy ?**
- **Sum of probabilities for discrete set of outcomes is 1**

Probability for real-valued outcomes

When the process is repeated many times outcomes occur with certain relative frequencies or **probabilities**

- **Example 3: height of a person**
  - Select randomly a person from your school/city and report her height
  - Outcomes can be real numbers
  - Different outcomes can be more or less likely



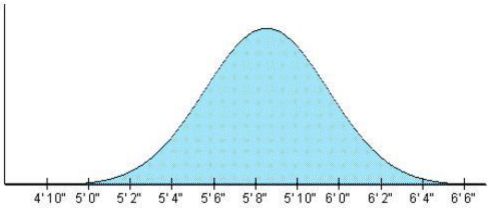


Normal (Gaussian) density

Probability density function

Real-valued outcomes – the chance of outcomes is represented by **a probability density function**

- **Probability density function – p(x)**



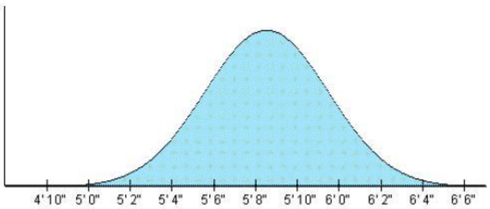
- **Conditions on p(x) and 1?**

$$\int p(x)dx = 1$$

Probability density function

Real-valued outcomes – the chance of outcomes is represented by **a probability density function**

- **Probability density function – p(x)**

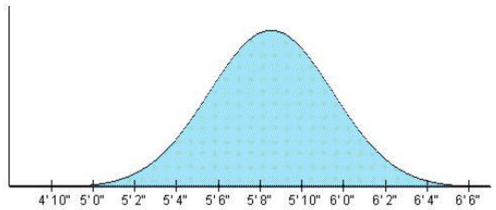


- **Can p(x) values for some x be negatives?**
- **No**

Probability density function

Real-valued outcomes – the chance of outcomes is represented by **a probability density function**

- **probability density function – p(x)**



- **Can p(x) values for some x be > 1?**
- **Remember we need:** $\int p(x)dx = 1$
- **Yes**

Random variable

Random variable = A function that maps observed outcomes (quantities) to real valued outcomes

Binary random variables: Two outcomes mapped to **0,1**

Example: Coin flip with head and tail outcomes

- **Tail mapped to 0,** $P(x=0)$
- **Head mapped to 1** $P(x=1)$

Example of observed outcome sequence:

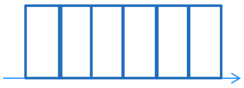
- tail, tail, head, tail, head, head… → 0, 0, 1, 0, 1, 1, …

Random variable

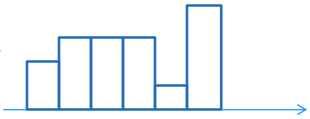
Example: roll of a dice

- Outcomes =1,2,3,4,5,6 based on the roll of a dice
- **trivial map to the same number**

A fair dice



A biased dice



Example of observed outcome sequence:

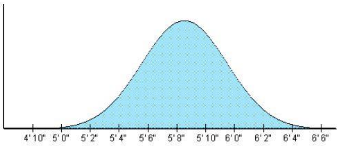
- **3, 6, 2, 6, 1, 2, 5, 4, 5, 3, 3 …**

Random variable

Example: x height of a person

Real valued outcomes

– trivial map to the same number



Example of observed outcome sequence:

- **5’4”, 6’1”, 5’9”, 5’8”**

Expected value of a random variable

Assume a random variable X with K discrete values

– Expected value of X is:

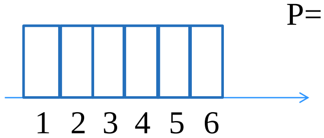
$$E[X] = \sum_{i=1}^{K} p(X = x_i)x_i$$

Example: Fair dice

- Outcomes =1,2,3,4,5,6 based on the roll

P=1/6

Fair dice



$$E[X] = \frac{1}{6}*1 + \frac{1}{6}*2 + \frac{1}{6}*3 + \frac{1}{6}*4 + \frac{1}{6}*5 + \frac{1}{6}*6 = 3.5$$

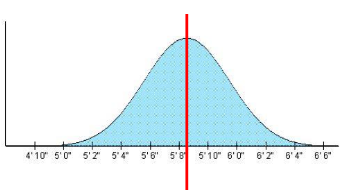
Expected value of a random variable

Assume a random variable X with continuous values

$$E[X] = \int x * p(x)dx$$

Example: x height of a person

- **Density function: Gaussian**
- **Expected value of X is the center of the Gaussian distribution or its mean**



Probability: basics

- **Let A be an outcome event, and ¬A its complement.**
  - **Then**

$$P(A) + P(\neg A) = ?$$

Probability: basics

- **Let A be an event, and ¬A its complement.**
  - **Then**

$$P(A) + P(\neg A) = 1$$

$$P(A \wedge \neg A) = ?$$

Probability: basics

- **Let A be an event, and ¬A its complement.**
  - **Then**

$$P(A)+P(\neg A)=1$$

$$P(A\wedge\neg A)=0$$

$$P(False)=0$$

$$P(A\vee\neg A)=?$$

Probability: basics

- **Let A be an event, and ¬A its complement.**
  - **Then**

$$P(A)+P(\neg A)=1$$

$$P(A\wedge\neg A)=0$$

$$P(False)=0$$

$$P(A\vee\neg A)=1$$

$$P(True)=1$$

Joint probability

Joint probability:

- **Let A and B be two events.** The probability of an event A, B occurring jointly

$$P(A \wedge B) = P(A, B)$$

We can add more events, say, A,B,C

$$P(A \wedge B \wedge C) = P(A, B, C)$$

Independence

Independence :

- Let A, B be two events. The events are independent if:

$$P(A, B) = ?$$

Independence

Independence :

- Let A, B be two events. The events are independent if:

$$P(A,B) = P(A)P(B)$$

Conditional probability

Conditional probability :

- Let A, B be two events. The conditional probability of A given B is defined as:

$$P(A \mid B) = ?$$

Conditional probability

Conditional probability :

- Let A, B be two events. The conditional probability of A given B is defined as:

$$P(A \mid B) = \frac{P(A,B)}{P(B)}$$

Product rule:

- A rewrite of the conditional probability

$$P(A,B) = P(A \mid B)P(B)$$

Bayes theorem

Bayes theorem

$$P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B)}$$

Why?

$$P(A \mid B) = \frac{P(A,B)}{P(B)} \qquad P(A,B) = P(B \mid A)P(A)$$

$$P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B)}$$

Density estimation

Density estimation

Density estimation: is an unsupervised learning problem

- **Goal:** Learn a model that represent the relations among attributes in the data $D = \{D_1, D_2, .., D_n\}$

Data: $D_i = \mathbf{x}_i$ a vector of attribute values

Attributes:

- modeled by random variables $\mathbf{X} = \{X_1, X_2, \ldots, X_d\}$ with
  - **Continuous or discrete valued variables**

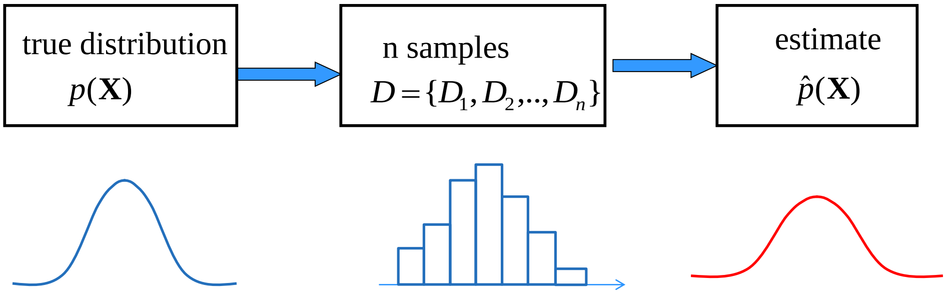
Density estimation: learn an underlying probability distribution model : $p(\mathbf{X}) = p(X_1, X_2, \ldots, X_d)$ from D

Density estimation

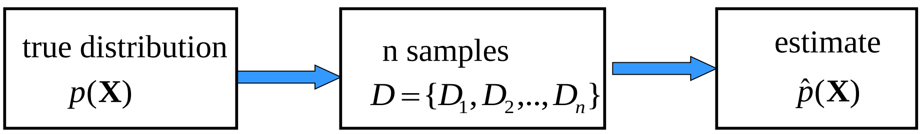
Data: $D = \{D_1, D_2, .., D_n\}$

$D_i = \mathbf{x}_i$ a vector of attribute values

Objective: estimate the model of the underlying probability distribution over variables $\mathbf{X}$, $p(\mathbf{X})$, using examples in D

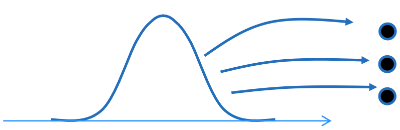


Density estimation: iid assumptions



Standard (iid) assumptions: Samples

- **are independent of each other**
- **come from the same (identical) distribution (fixed $p(\mathbf{X})$)**



Independently drawn instances from the same fixed distribution

Density estimation

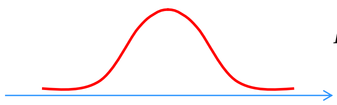
Types of density estimation:

(1) Parametric

- the distribution is modeled using a set of parameters Θ

$$\hat{p}(\mathbf{X}) = p(\mathbf{X} \mid \Theta)$$

- **Estimation:** find parameters Θ fitting the data D
- **Example:** estimate the mean and covariance of a normal distribution



$$\hat{p}(x) = N(x \mid \mu, \sigma)$$

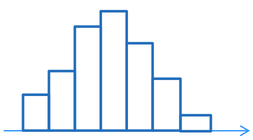
Density estimation

Types of density estimation:

(2) Non-parametric

- The model of the distribution utilizes all examples in D
- As if all examples were parameters of the distribution
- $$\hat{p}(\mathbf{X}) = p(\mathbf{X} \mid D)$$
- **Examples:**

histogram



Kernel density estimation