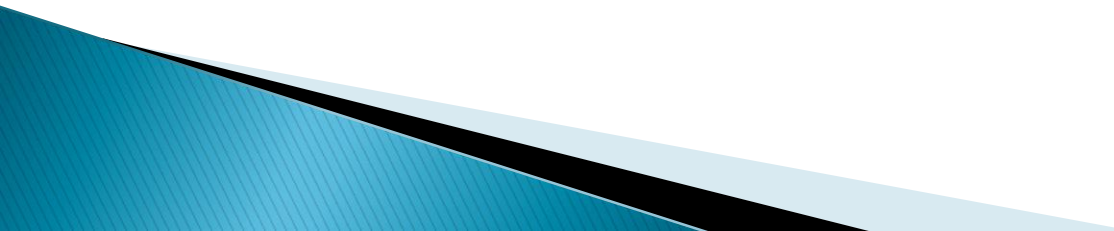


# Energy Corollaries to Amdahl's Law

Sangyeun Cho, Rami Melhem, Michael Moeng  
University of Pittsburgh

Presented By: Michael Moeng

# Outline

- ▶ Amdahl's Law
  - ▶ Power Applications
  - ▶ Problem Formulation
  - ▶ Derivations
  - ▶ Conclusions
- 

# Amdahl's Law

- ▶ Maximum speedup for a program given
  - Sequential fraction  $s$ , parallel fraction  $p=1-s$
  - $N$  processors
- ▶ Speedup = 
$$\frac{1}{s + p/N}$$
- ▶ Assumes parallel portion can be perfectly parallelized

# Power Applications

- ▶ Keep execution time constant and improve dynamic energy
- ▶ Assumes  $p \sim f^\alpha$
- ▶ Find optimal serial and parallel frequency by taking derivative

# Power Applications

- ▶ Keep execution time constant and improve energy

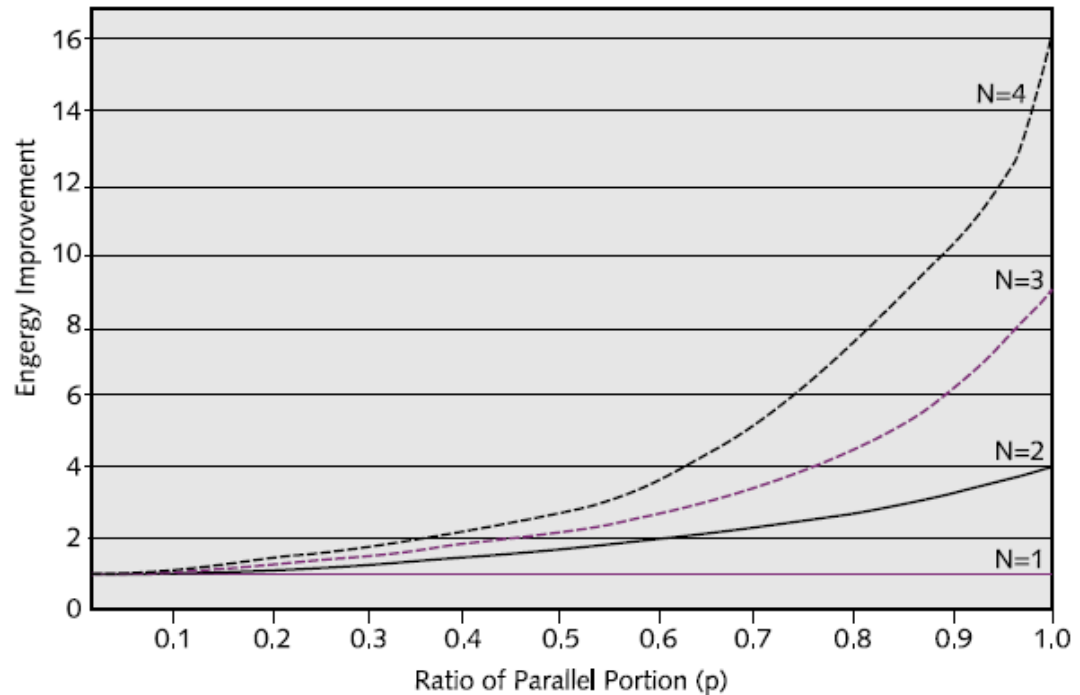


Figure 1. Achievable dynamic energy improvement assuming  $\alpha = 3$  and using 1, 2, 3, and 4 processors, given the ratio of serial and parallel work in a program.

# Generalized Power

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- ▶ Set  $f_s, f_p$
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- ▶ What are optimal serial and parallel frequencies?
  
- ▶ Trivial – minimize frequencies
- ▶ Must consider static power!

# Problem Formulation

- ▶ Serial work  $s$  completes in time  $t$
- ▶ Parallel work  $p=1-s$  completes in time  $1/x-t$ 
  - Recall that  $x$  is speedup, so  $1/x$  is total time

- ▶  $f_s = \frac{s}{t}$

- ▶  $f_p = \frac{1-s}{(1/x-t) \cdot N}$

- ▶ Energy is composed of
  - Serial dynamic energy
  - Parallel dynamic energy
  - Static energy

$$\begin{aligned} &= t \cdot f_s^a \\ &= N \cdot \left( \frac{1}{x} - t \right) \cdot f_p^a \\ &= N \cdot \lambda \cdot \frac{1}{x} \end{aligned}$$



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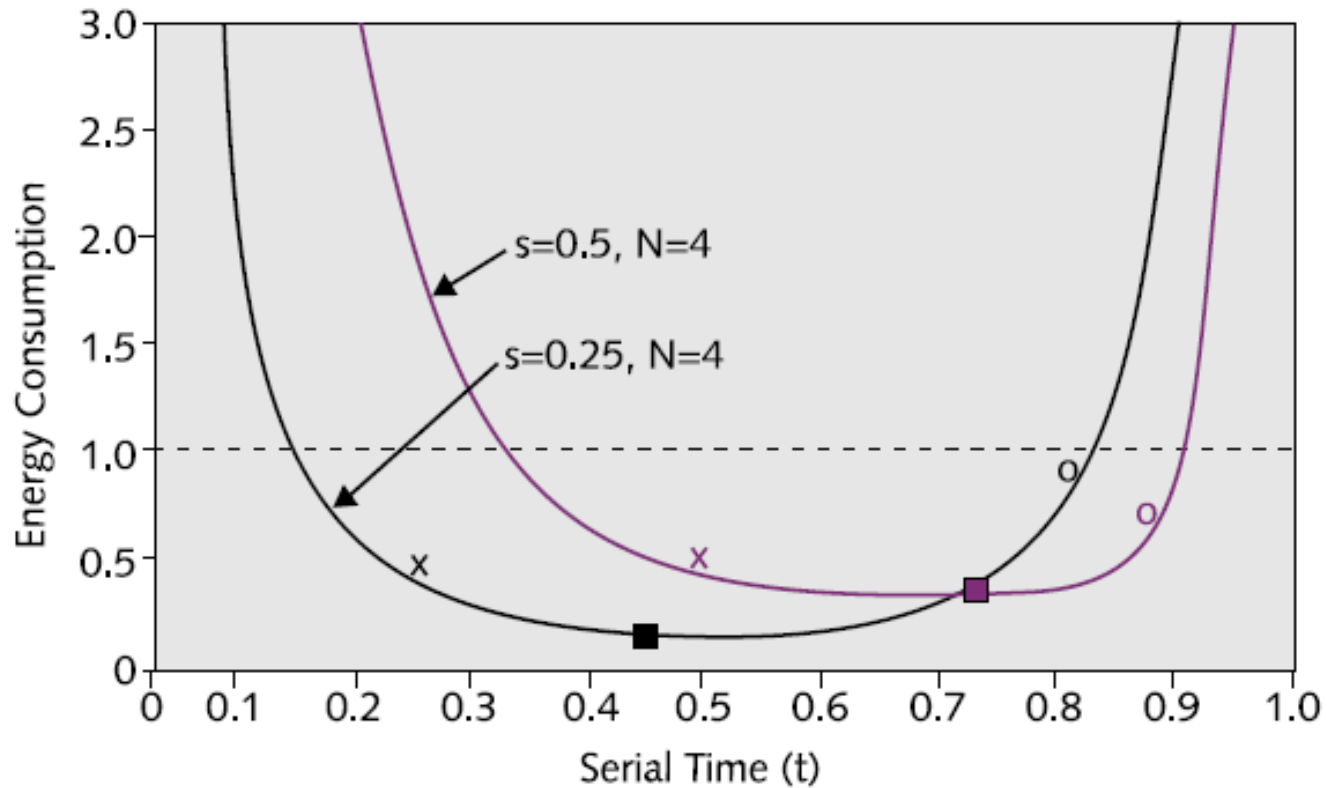
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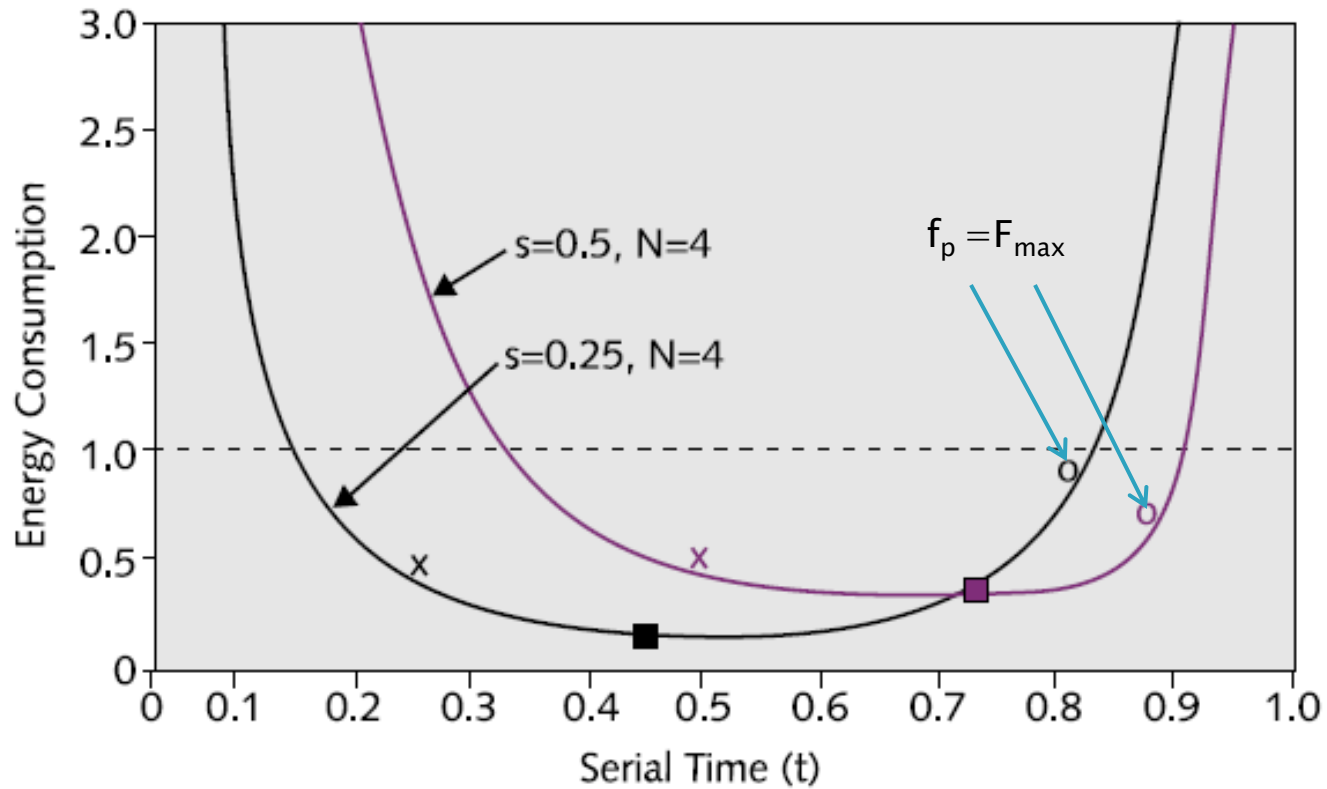
$$f_p^* = \left( s + \frac{p}{N^{(\alpha-1)/\alpha}} \right) / N^{1/\alpha} = f_s^* / N^{1/\alpha}$$

- ▶ Relation between  $f_s^*$  and  $f_p^*$  is dependent on  $N$ , but not  $s$ !
- ▶ Note that static energy has no effect in this case

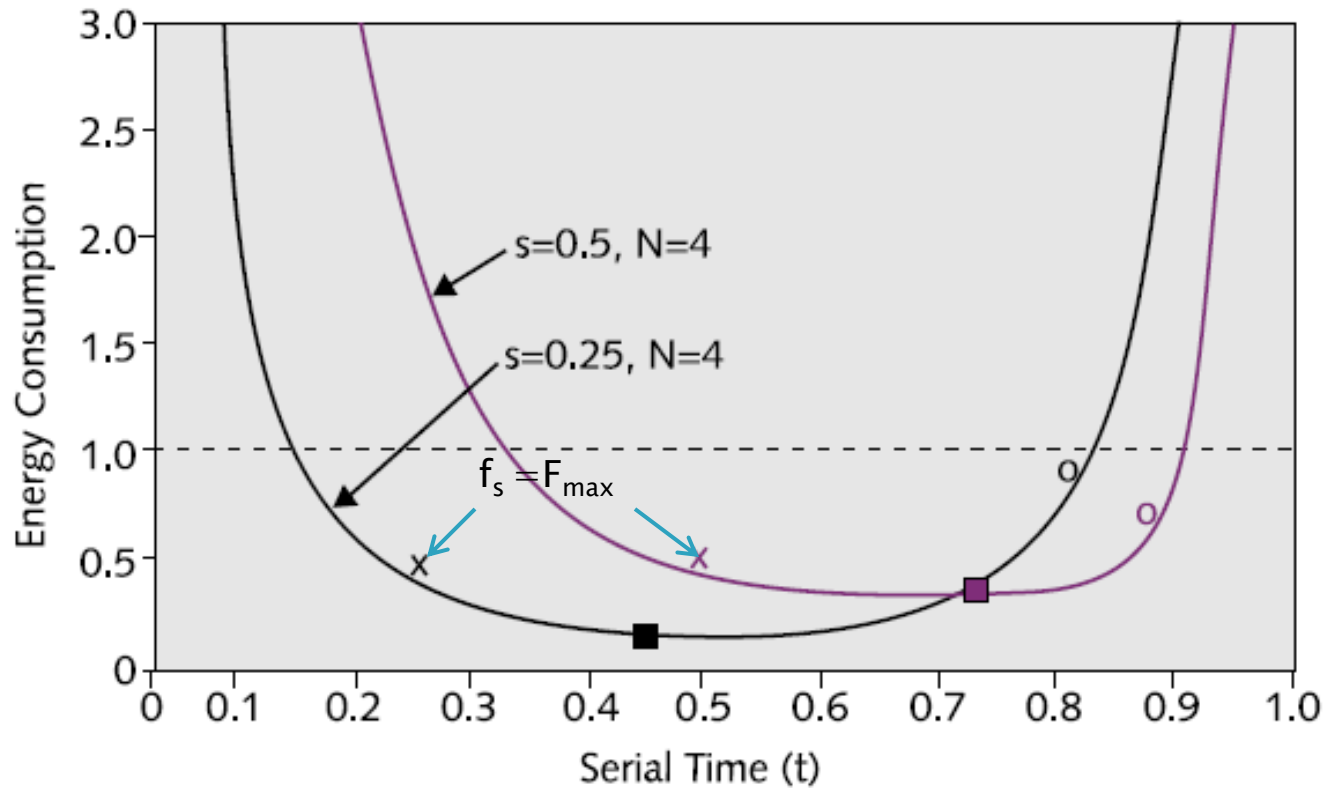
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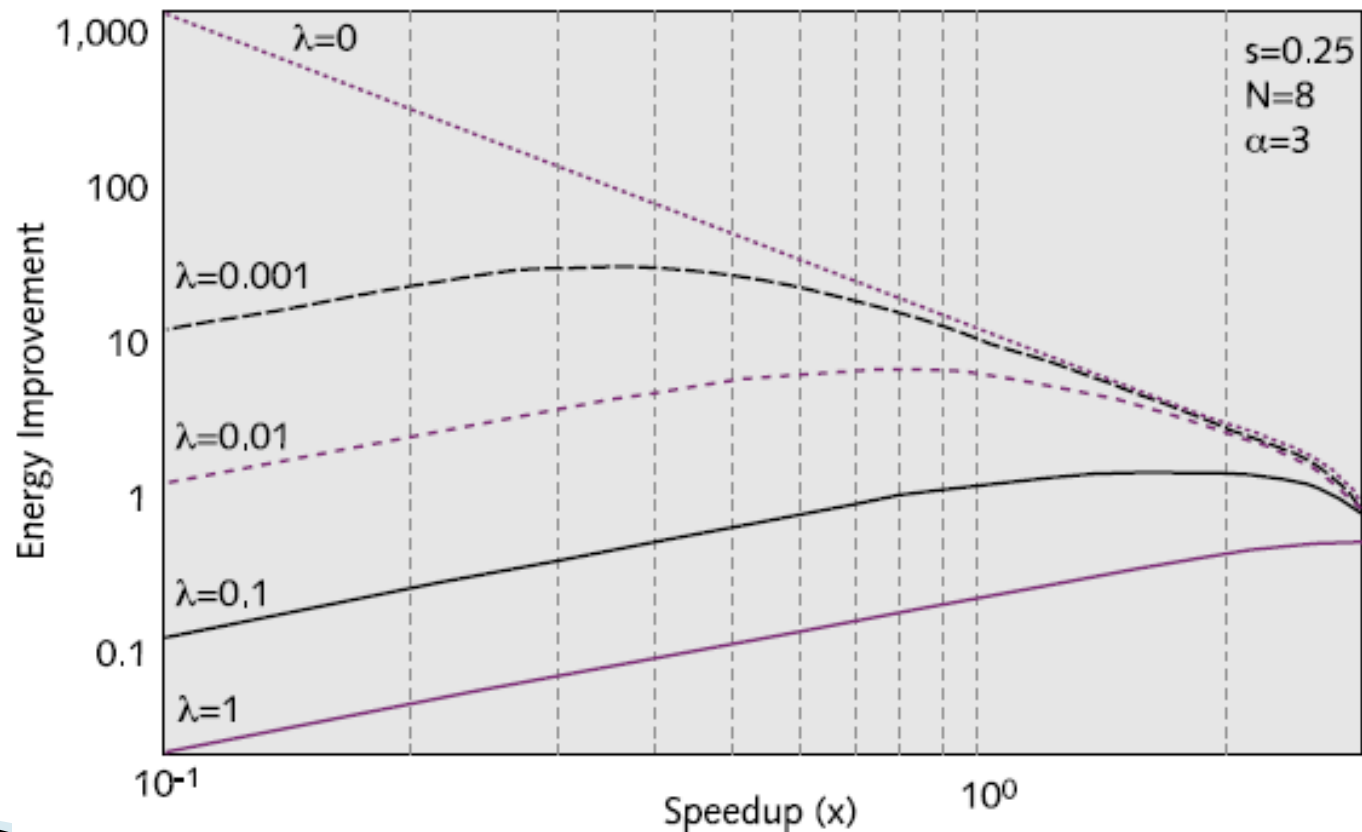
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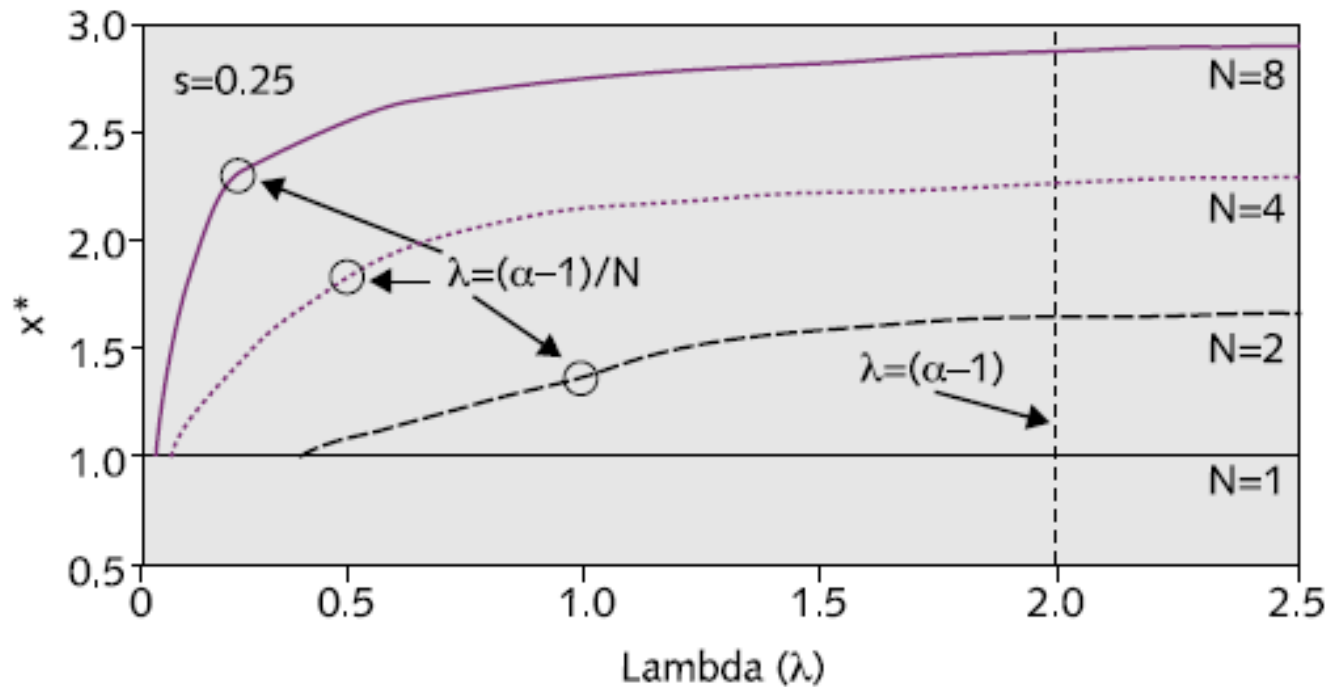
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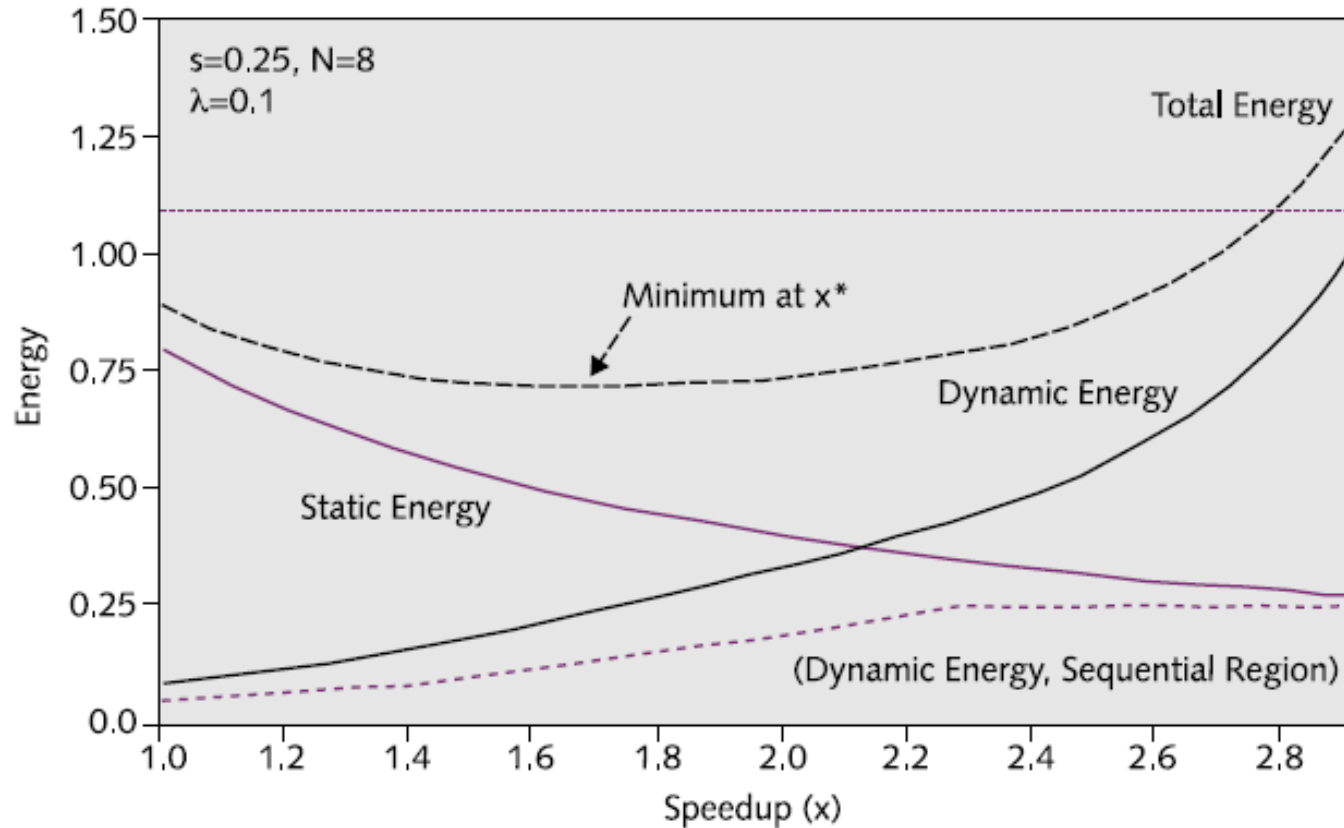
$$E_{dynamic} = \frac{1}{\alpha - 1} \cdot \frac{N\lambda}{x^*} \qquad E_{static} = \frac{N\lambda}{x^*}$$

# The Effect of Static Power

- ▶ Previous solution necessitates  $\lambda N \leq \alpha - 1$ 
  - $f_s = F_{\max}$



# Dynamic and Static Energy



# Other Results

- ▶ Energy Delay

$$ED(t, x) = (t \cdot f_s^\alpha + N \cdot \left(\frac{1}{x} - t\right) \cdot f_p^\alpha + N \cdot \lambda \cdot \frac{1}{x}) \cdot \frac{1}{x}$$



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- ▶ Same relation between  $f_s^*$  and  $f_p^*$

- ▶ Implications?

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- ▶ Synchronization cost
  - Parallel architectures have some overhead for communication
  - As  $N$  increases, more total work is required, which can be expressed as a function
  - Total work is now  $s + p(1 + \sigma(N))$

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  - Parallel architectures have some overhead for communication
  - As  $N$  increases, more total work is required, which can be expressed as a function
  - Total work is now  $s + (p + \sigma(N))$
- ▶ Optimal serial and parallel frequencies have the same relationship
  - Still differ by  $N^{1/\alpha}$

# Andahl's Law in the Multicore Era

Mark D. Hill, University of Wisconsin–Madison and  
Michael R. Marty, Google

Presented By: Michael Moeng



# Asymmetric Cores

- ▶ Chip has a total resource budget, defined in the number of 'baseline' cores that can be supported
- ▶ Assume performance for an  $r$ -BCE core grows by  $\sqrt{r}$

# Trade-off power vs performance

